The PIC18F87K22 family devices that you have received conform functionally to the current Device Data Sheet (DS30009960F), except for the anomalies described in this document.

The silicon issues discussed in the following pages are for silicon revisions with the Device and Revision IDs listed in Table 1. The silicon issues are summarized in Table 2.

The errata described in this document will be addressed in future revisions of the PIC18F87K22 silicon.

**Note:** This document summarizes all silicon errata issues from all revisions of silicon, previous as well as current. Only the issues indicated in the last column of Table 2 apply to the current silicon revision (B5, C6).

For example, to identify the silicon revision level using MPLAB IDE in conjunction with a hardware debugger:

1. Using the appropriate interface, connect the device to the hardware debugger.
2. Open an MPLAB IDE project.
3. Configure the MPLAB IDE project for the appropriate device and hardware debugger.
4. Based on the version of MPLAB IDE you are using, do one of the following:
   a) For MPLAB IDE 8, select Programmer > Reconnect.
   b) For MPLAB X IDE, select Window > Dashboard and click the Refresh Debug Tool Status icon ( ).
5. Depending on the development tool used, the part number and Device Revision ID value appear in the Output window.

**Note:** If you are unable to extract the silicon revision level, please contact your local Microchip sales office for assistance.

The DEVREV values for the various PIC18F87K22 silicon revisions are shown in Table 1.

### TABLE 1: SILICON DEVREV VALUES

<table>
<thead>
<tr>
<th>Part Number</th>
<th>Device ID(1)</th>
<th>Revision ID for Silicon Revision(2)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>A3 B1 B3 B5 C1 C3 C5 C6</td>
</tr>
<tr>
<td>PIC18F65K22</td>
<td>530h</td>
<td>3h 4h 5h 6h 10h 11h 12h 13h</td>
</tr>
<tr>
<td>PIC18F66K22</td>
<td>52Ch</td>
<td></td>
</tr>
<tr>
<td>PIC18F85K22</td>
<td>536h</td>
<td></td>
</tr>
<tr>
<td>PIC18F86K22</td>
<td>532h</td>
<td></td>
</tr>
<tr>
<td>PIC18F67K22</td>
<td>518h</td>
<td></td>
</tr>
<tr>
<td>PIC18F87K22</td>
<td>51Ch</td>
<td></td>
</tr>
</tbody>
</table>

**Note 1:** The Device IDs (DEVID and DEVREV) are located at the last two implemented addresses of configuration memory space. They are shown in hexadecimal in the format “DEVID DEVREV”.

**Note 2:** Refer to the "PIC18F6XKXX/8XKXX Family Flash Microcontroller Programming Specification" (DS39947) for detailed information on Device and Revision IDs for your specific device.

---

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<table>
<thead>
<tr>
<th>Module</th>
<th>Feature</th>
<th>Item No.</th>
<th>Issue Summary</th>
<th>Affected Revisions&lt;sup&gt;(1)&lt;/sup&gt;</th>
</tr>
</thead>
<tbody>
<tr>
<td>Analog-to-Digital Converter (A/D)</td>
<td>A/D Offset</td>
<td>1.1</td>
<td>The A/D offset is greater than specified in the data sheet’s A/D Converter Characteristics table.</td>
<td>X</td>
</tr>
<tr>
<td>Analog-to-Digital Converter (A/D)</td>
<td>A/D Offset</td>
<td>1.2</td>
<td>The A/D offset is greater than specified in the data sheet’s A/D Converter Characteristics table.</td>
<td>X X X X X X X X</td>
</tr>
<tr>
<td>Ports</td>
<td>Leakage</td>
<td>2.</td>
<td>I/O port leakage is higher than the D060 spec in the data sheet.</td>
<td>X X X X X X X X</td>
</tr>
<tr>
<td>High/Low-Voltage Detect (HLVD)</td>
<td>HLVD Trip</td>
<td>3.</td>
<td>The high-to-low (VDIRMAG = 0) setting of the HLVD may send initial interrupts.</td>
<td>X X X X X X X X</td>
</tr>
<tr>
<td>ECCP</td>
<td>Auto-Shutdown</td>
<td>4.</td>
<td>The tri-state setting of the auto-shutdown feature in the enhanced PWM may not successfully drive the pin to tri-state.</td>
<td>X X X X X X X X</td>
</tr>
<tr>
<td>EUSART</td>
<td>Synchronous Transmit</td>
<td>5.</td>
<td>When using the Synchronous Transmit mode of the EUSART, at high baud rates, transmitted data may become corrupted.</td>
<td>X X X X X X X X</td>
</tr>
<tr>
<td>IPD and IDD</td>
<td>Maximum Limit</td>
<td>6.</td>
<td>Maximum current limits may be higher than specified in Section 31.2 “DC Characteristics: Power-Down and Supply Current PIC18F87K22 Family (Industrial)” of the data sheet.</td>
<td>X</td>
</tr>
<tr>
<td>Ultra Low-Power Sleep</td>
<td>Sleep Entry</td>
<td>7.1</td>
<td>Entering Ultra Low-Power Sleep mode, by setting RETEN = 0 and SRETEN = 1, will cause the part not to be programmable through ICSP™.</td>
<td>X X X</td>
</tr>
<tr>
<td>Ultra Low-Power Sleep</td>
<td>WDT Wake-up</td>
<td>7.2</td>
<td>Using the WDT to exit Ultra Low-Power Sleep mode when VDD&gt;4.5V can cause the part to enter a Reset state requiring POR to exit.</td>
<td>X X X X X X X X</td>
</tr>
<tr>
<td>Resets (BOR)</td>
<td>Enable/Disable</td>
<td>8.</td>
<td>An unexpected Reset may occur if the Brown-out Reset module (BOR) is disabled, and then re-enabled, when the High/Low-Voltage Detection (HLVD) module is not enabled (HLVDCON&lt;4&gt; = 0).</td>
<td>X X X X X X X X</td>
</tr>
<tr>
<td>RG5 Pin</td>
<td>Leakage</td>
<td>9.</td>
<td>RG5 will cause excess pin leakage whenever it is driven low.</td>
<td>X</td>
</tr>
<tr>
<td>External Memory Bus (EMB)</td>
<td>Wait States</td>
<td>10.</td>
<td>The CE signal will not be extended properly if Wait states are used.</td>
<td>X X X X</td>
</tr>
<tr>
<td>Primary Oscillator</td>
<td>XT Mode</td>
<td>11.</td>
<td>XT Primary Oscillator mode does not reliably function when the driving crystals are above 3 MHz.</td>
<td>X X X X</td>
</tr>
<tr>
<td>Timer1/3/5/7</td>
<td>Interrupt</td>
<td>12.</td>
<td>When the timer is operated in Asynchronous External Input mode, unexpected interrupt flag generation may occur.</td>
<td>X X X X X X</td>
</tr>
</tbody>
</table>

Note 1: Only those issues indicated in the columns labeled B3 and C3 apply to the current silicon revision.

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### TABLE 2: SILICON ISSUE SUMMARY (CONTINUED)

<table>
<thead>
<tr>
<th>Module</th>
<th>Feature</th>
<th>Item No.</th>
<th>Issue Summary</th>
<th>Affected Revisions&lt;sup&gt;(1)&lt;/sup&gt;</th>
</tr>
</thead>
<tbody>
<tr>
<td>MSSP1</td>
<td>SPI Slave</td>
<td>13.</td>
<td>Slave samples SDI on both rising and falling edges of SCK.</td>
<td>X X X X X X X</td>
</tr>
</tbody>
</table>

**Note 1:** Only those issues indicated in the columns labeled B3 and C3 apply to the current silicon revision.
**Silicon Errata Issues**

**Note:** This document summarizes all silicon errata issues from all revisions of silicon, previous as well as current. Only the issues indicated by the shaded column in the following tables apply to the current silicon revision (B5, C6).

1. **Module: Analog-to-Digital Converter (A/D)**

   1.1 The A/D will not meet the Microchip standard A/D specification. The A/D may be usable if tested at the user end. The possible issues are high offset error, high DNL error and multiple missing codes. The A/D can be tested and used for relative measurements.

   **A/D Offset**
   The A/D may have a high offset error, up to a maximum of 50 LSB; it can be used if the A/D is calibrated for the offset.

   **Work around**
   Method to Calibrate for Offset:
   In Single-Ended mode, connect the A/D +ve input to ground and take the A/D reading. This will be the offset of the device and can be used to compensate for the subsequent A/D readings on the actual inputs.

   **Affected Silicon Revisions**

<table>
<thead>
<tr>
<th>A3</th>
<th>B1</th>
<th>B3</th>
<th>B5</th>
<th>C1</th>
<th>C3</th>
<th>C5</th>
<th>C6</th>
</tr>
</thead>
<tbody>
<tr>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

1.2 The A/D will meet the Microchip standard A/D specification when used as a 10-bit A/D. When used as a 12-bit A/D, the possible issues include high offset error (up to a maximum of ±25 LSBs at 25°C, ±30 LSBs at 85°C, 125°C and -40°C), high DNL error (up to a maximum of ±4 LSBs) and multiple missing codes (up to a maximum of 20). Users should evaluate the 12-bit A/D performance in their application using the suggested work around below. See Table 3 for guidance specifications.

   **A/D Offset**
   The A/D may have high offset error, up to a maximum of ±25 LSBs at 25°C, ±30 LSBs at 85°C, 125°C and -40°C; it can be used if the A/D is calibrated for the offset.

   **Work around**
   Method to Calibrate for Offset:
   In Single-Ended mode, connect A/D +ve input to ground and take the A/D reading. This will be the offset of the device and can be used to compensate for the subsequent A/D readings on the actual inputs.
TABLE 3: A/D CONVERTER CHARACTERISTICS

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>A01</td>
<td>NR</td>
<td>Resolution</td>
<td>—</td>
<td>—</td>
<td>12</td>
<td>bit</td>
<td>ΔVREF ≥ 5.0V</td>
</tr>
<tr>
<td>A03</td>
<td>EIL</td>
<td>Integral Linearity Error</td>
<td>—</td>
<td>—</td>
<td>±10.0</td>
<td>LSb</td>
<td>ΔVREF ≥ 5.0V</td>
</tr>
<tr>
<td>A04</td>
<td>EDL</td>
<td>Differential Linearity Error</td>
<td>—</td>
<td>—</td>
<td>+6.0/-4.0</td>
<td>LSb</td>
<td>ΔVREF ≥ 5.0V</td>
</tr>
<tr>
<td>A06</td>
<td>EOFF</td>
<td>Offset Error</td>
<td>—</td>
<td>—</td>
<td>±25</td>
<td>LSb</td>
<td>ΔVREF ≥ 5.0V, Temperature: 25°C</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>—</td>
<td>—</td>
<td>±30</td>
<td>LSb</td>
<td>ΔVREF ≥ 5.0V, Temperature: 85°C, -40°C</td>
</tr>
<tr>
<td>A07</td>
<td>EGN</td>
<td>Gain Error</td>
<td>—</td>
<td>—</td>
<td>±15</td>
<td>LSb</td>
<td>ΔVREF ≥ 5.0V</td>
</tr>
<tr>
<td>A10</td>
<td></td>
<td>Monotonicity(1)</td>
<td>—</td>
<td>—</td>
<td></td>
<td></td>
<td>VSS ≤ VAIN ≤ VREF</td>
</tr>
<tr>
<td>A20</td>
<td>ΔVREF</td>
<td>Reference Voltage Range</td>
<td>3</td>
<td>—</td>
<td>AVDD – AVSS</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>A21</td>
<td>VREFH</td>
<td>Reference Voltage High</td>
<td>AVSS + 3.0V</td>
<td>—</td>
<td>AVDD + 0.3V</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>A22</td>
<td>VREFL</td>
<td>Reference Voltage Low</td>
<td>AVSS – 0.3V</td>
<td>—</td>
<td>AVDD – 3.0V</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>A25</td>
<td>VAIN</td>
<td>Analog Input Voltage</td>
<td>VREFL</td>
<td>—</td>
<td>VREFH</td>
<td>V</td>
<td></td>
</tr>
</tbody>
</table>

Note 1: The A/D conversion result never decreases with an increase in the input voltage.

**Affected Silicon Revisions**

<table>
<thead>
<tr>
<th>A3</th>
<th>B1</th>
<th>B3</th>
<th>B5</th>
<th>C1</th>
<th>C3</th>
<th>C5</th>
<th>C6</th>
</tr>
</thead>
<tbody>
<tr>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
</tbody>
</table>
2. Module: Ports

The input leakage will not match the D060 specification in the data sheet. The leakage will meet the 200 nA specification at TA = 25°C. At TA = 85°C, the leakage will be up to a maximum of 2 µA.

**Work around**
None.

**Affected Silicon Revisions**

<table>
<thead>
<tr>
<th>A3</th>
<th>B1</th>
<th>B3</th>
<th>B5</th>
<th>C1</th>
<th>C3</th>
<th>C5</th>
<th>C6</th>
</tr>
</thead>
<tbody>
<tr>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
</tbody>
</table>

3. Module: High/Low-Voltage Detect (HLVD)

The high-to-low (VDIRMAG = 0) setting of the HLVD may send initial interrupts. High trip points that are close to the intended operating voltage are susceptible to this behavior.

**Work around**
Select a lower trip voltage that allows consistent start-up or clear any initial interrupts from the HLVD on start-up.

**Affected Silicon Revisions**

<table>
<thead>
<tr>
<th>A3</th>
<th>B1</th>
<th>B3</th>
<th>B5</th>
<th>C1</th>
<th>C3</th>
<th>C5</th>
<th>C6</th>
</tr>
</thead>
<tbody>
<tr>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
</tbody>
</table>

4. Module: ECCP

The tri-state setting of the auto-shutdown feature in the enhanced PWM may not successfully drive the pin to tri-state. The pin will remain an output and should not be driven externally. All tri-state settings will be affected.

**Work around**
None.

**Affected Silicon Revisions**

<table>
<thead>
<tr>
<th>A3</th>
<th>B1</th>
<th>B3</th>
<th>B5</th>
<th>C1</th>
<th>C3</th>
<th>C5</th>
<th>C6</th>
</tr>
</thead>
<tbody>
<tr>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
</tbody>
</table>

5. Module: EUSART

When using the Synchronous Transmit mode of the EUSART, at high baud rates, transmitted data may become corrupted. One or more bits of the intended transmit message may be incorrect.

**Work around**
Since this problem is related to the baud rate used, adding a fixed delay before loading the TXREGx may not be a reliable work around. Lower the baud rate until no errors occur, or when loading the TXREGx, check that the TRMT bit inside of the TXSTAx register is set instead of checking the TXxIF bit. The following code can be used:

**EXAMPLE 1: EUSART SYNCHRONOUS TRANSMIT WORK AROUND**

```c
while(!TXSTAxbits.TRMT);
// wait to load TXREGx until TRMT is set
```

**Affected Silicon Revisions**

<table>
<thead>
<tr>
<th>A3</th>
<th>B1</th>
<th>B3</th>
<th>B5</th>
<th>C1</th>
<th>C3</th>
<th>C5</th>
<th>C6</th>
</tr>
</thead>
<tbody>
<tr>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
</tbody>
</table>
6. Module: IPD and IDD

The IPD and IDD limits will not match the data sheet. The values, in bold in Section 31.2 “DC Characteristics: Power-Down and Supply Current PIC18F87K22 Family (Industrial)”, reflect the updated silicon maximum limits.

31.2 DC Characteristics: Power-Down and Supply Current PIC18F87K22 Family (Industrial)

<table>
<thead>
<tr>
<th>PIC18F87K22 Family (Industrial)</th>
<th>Standard Operating Conditions (unless otherwise stated)</th>
<th>Operating temperature: -40°C ≤ TA ≤ +85°C for industrial</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Param. No.</strong></td>
<td><strong>Device</strong></td>
<td><strong>Typ.</strong></td>
</tr>
<tr>
<td>Power-Down Current (IPD)$^{(1)}$</td>
<td></td>
<td></td>
</tr>
<tr>
<td>All devices</td>
<td>10</td>
<td>500</td>
</tr>
<tr>
<td></td>
<td>20</td>
<td>500</td>
</tr>
<tr>
<td></td>
<td>120</td>
<td>600</td>
</tr>
<tr>
<td></td>
<td>630</td>
<td>2000</td>
</tr>
<tr>
<td>All devices</td>
<td>50</td>
<td>700</td>
</tr>
<tr>
<td></td>
<td>60</td>
<td>900</td>
</tr>
<tr>
<td></td>
<td>170</td>
<td>1100</td>
</tr>
<tr>
<td></td>
<td>700</td>
<td>5000</td>
</tr>
<tr>
<td>All devices</td>
<td>350</td>
<td>1300</td>
</tr>
<tr>
<td></td>
<td>400</td>
<td>1400</td>
</tr>
<tr>
<td></td>
<td>550</td>
<td>1500</td>
</tr>
<tr>
<td></td>
<td>1350</td>
<td>4000</td>
</tr>
<tr>
<td>Supply Current (IDD) Cont.$^{(2,3)}$</td>
<td></td>
<td></td>
</tr>
<tr>
<td>All devices</td>
<td>3.7</td>
<td>8.5</td>
</tr>
<tr>
<td></td>
<td>5.4</td>
<td>10</td>
</tr>
<tr>
<td></td>
<td>6.6</td>
<td>13</td>
</tr>
<tr>
<td>All devices</td>
<td>8.7</td>
<td>18</td>
</tr>
<tr>
<td></td>
<td>10</td>
<td>20</td>
</tr>
<tr>
<td></td>
<td>12</td>
<td>35</td>
</tr>
<tr>
<td>All devices</td>
<td>60</td>
<td>160</td>
</tr>
<tr>
<td></td>
<td>90</td>
<td>190</td>
</tr>
<tr>
<td></td>
<td>100</td>
<td>240</td>
</tr>
</tbody>
</table>

**Note 1:** The power-down current in Sleep mode does not depend on the oscillator type. Power-down current is measured with the part in Sleep mode, with all I/O pins in a high-impedance state and tied to VDD or VSS, and all features that add delta current are disabled (such as WDT, SOSC oscillator, BOR, etc.).

**Note 2:** The supply current is mainly a function of operating voltage, frequency and mode. Other factors, such as I/O pin loading and switching rate, oscillator type and circuit, internal code execution pattern and temperature, also have an impact on the current consumption. The test conditions for all IDD measurements in active operation mode are:
- OSC1 = external square wave, from rail-to-rail; all I/O pins tri-stated, pulled to VDD; MCLR = VDD; WDT enabled/disabled as specified.

**Note 3:** Standard, low-cost 32 kHz crystals have an operating temperature range of -10°C to +70°C. Extended temperature crystals are available at a much higher cost.

**Note 4:** Voltage regulator disabled (ENVREG = 0, tied to Vss, RETEN (CONFIG1L<0>) = 1).

**Note 5:** Voltage regulator enabled (ENVREG = 1, tied to Vdd, SRETEN (WDTCN<4>) = 1 and RETEN (CONFIG1L<0>) = 0).
### 31.2 DC Characteristics: Power-Down and Supply Current

#### PIC18F87K22 Family (Industrial) (Continued)

<table>
<thead>
<tr>
<th>Param. No.</th>
<th>Device</th>
<th>Typ.</th>
<th>Max.</th>
<th>Units</th>
<th>Conditions</th>
</tr>
</thead>
<tbody>
<tr>
<td>All devices</td>
<td>1.2</td>
<td>4</td>
<td>µA</td>
<td>-40°C</td>
<td>VDD = 1.8V(^{(4)}) Regulator Disabled</td>
</tr>
<tr>
<td></td>
<td>1.7</td>
<td>5</td>
<td>µA</td>
<td>+25°C</td>
<td></td>
</tr>
<tr>
<td></td>
<td>2.6</td>
<td>6</td>
<td>µA</td>
<td>+85°C</td>
<td></td>
</tr>
<tr>
<td>All devices</td>
<td>1.6</td>
<td>7</td>
<td>µA</td>
<td>-40°C</td>
<td>VDD = 3.3V(^{(4)}) Regulator Disabled</td>
</tr>
<tr>
<td></td>
<td>2.8</td>
<td>9</td>
<td>µA</td>
<td>+25°C</td>
<td></td>
</tr>
<tr>
<td></td>
<td>4.1</td>
<td>17</td>
<td>µA</td>
<td>+85°C</td>
<td></td>
</tr>
<tr>
<td>All devices</td>
<td>60</td>
<td>150</td>
<td>µA</td>
<td>-40°C</td>
<td>VDD = 5V(^{(5)}) Regulator Enabled</td>
</tr>
<tr>
<td></td>
<td>80</td>
<td>180</td>
<td>µA</td>
<td>+25°C</td>
<td></td>
</tr>
<tr>
<td></td>
<td>100</td>
<td>240</td>
<td>µA</td>
<td>+85°C</td>
<td></td>
</tr>
</tbody>
</table>

**Note 1:** The power-down current in Sleep mode does not depend on the oscillator type. Power-down current is measured with the part in Sleep mode, with all I/O pins in a high-impedance state and tied to VDD or VSS, and all features that add delta current are disabled (such as WDT, SOSC oscillator, BOR, etc.).

**Note 2:** The supply current is mainly a function of operating voltage, frequency and mode. Other factors, such as I/O pin loading and switching rate, oscillator type and circuit, internal code execution pattern and temperature, also have an impact on the current consumption. The test conditions for all IDD measurements in active operation mode are:

- OSC1 = external square wave, from rail-to-rail; all I/O pins tri-stated, pulled to VDD;
- MCLR = VDD; WDT enabled/disabled as specified.

**Note 3:** Standard, low-cost 32 kHz crystals have an operating temperature range of -10°C to +70°C. Extended temperature crystals are available at a much higher cost.

**Note 4:** Voltage regulator disabled (ENVREG = 0, tied to VSS, RETEN (CONFIG1L<0>) = 1).

**Note 5:** Voltage regulator enabled (ENVREG = 1, tied to VDD, SRETEN (WDTCON<4>) = 1 and RETEN (CONFIG1L<0>) = 0).

**Work around**

None.

**Affected Silicon Revisions**

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<tr>
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<th>B3</th>
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</table>
7. Module: Ultra Low-Power Sleep

7.1 Entering Ultra Low-Power Sleep mode, by setting \texttt{RETEN = 0} and \texttt{SRETEN = 1}, will cause the part to not be programmable through ICSP™. This issue occurs when the \texttt{RETEN} fuse bit in \texttt{CONFIG1L<0>} is cleared to \textquoteleft{}0\textquoteright{}, the \texttt{SRETEN} bit in the \texttt{WDTCON} register is set to \textquoteleft{}1\textquoteright{} and a \texttt{SLEEP} instruction is executed. This happens within the first 350 μs of code execution or whenever the above Sleep mode is entered and MCLR is disabled. Discontinue use of the MCLR disabled ROG5 mode if ICSP™ reprogramming is necessary.

\textbf{Work around}

Use normal Sleep and Low-Power Sleep modes only, or on any Reset, ensure that at least 350 μs passes before executing a \texttt{SLEEP} instruction when ULP is enabled. To ensure the Ultra Low-Power Sleep mode is not enabled, the \texttt{RETEN} fuse bit in \texttt{CONFIG1L<0>} should be set to \textquoteleft{}1\textquoteright{}, and the \texttt{SRETEN} bit in the \texttt{WDTCON} register should be cleared to a \textquoteleft{}0\textquoteright{}. The following code can be used:

\begin{verbatim}
//This will ensure the RETEN fuse is set to 1
#pragma config RETEN = OFF
//This will ensure the SRETEN bit is 0
WDTCONbits.SRETEN = 0;
\end{verbatim}

If the Ultra Low-Power Sleep mode is needed, then the user must ensure that the minimum time, before the first \texttt{SLEEP} instruction is executed, is greater than 350 μs.

\textbf{AFFECTED SILICON REVISIONS}

\begin{tabular}{cccccccc}
\textbf{A3} & \textbf{B1} & \textbf{B3} & \textbf{B5} & \textbf{C1} & \textbf{C3} & \textbf{C5} & \textbf{C6} \\
\hline
X & X & & X & X & X & X & \\
\end{tabular}

7.2 Using the WDT to exit Ultra Low-Power Sleep mode when \texttt{VDD}>4.5V can cause the part to enter a Reset state that requires a POR to exit. The issue occurs when the \texttt{RETEN} fuse bit in \texttt{CONFIG1L<0>} is cleared to \textquoteleft{}0\textquoteright{}, the \texttt{SRETEN} bit in the \texttt{WDTCON} register is set to \textquoteleft{}1\textquoteright{}, \texttt{VDD}>4.5V. Upon entering the failure state, the device ceases to respond to MCLR events and will only exit the Reset state upon experiencing a POR.

\textbf{Work around}

Do not use the Ultra Low-Power Sleep mode with \texttt{VDD} above 4.5V.

\textbf{AFFECTED SILICON REVISIONS}

\begin{tabular}{cccccccc}
\textbf{A3} & \textbf{B1} & \textbf{B3} & \textbf{B5} & \textbf{C1} & \textbf{C3} & \textbf{C5} & \textbf{C6} \\
\hline
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\end{tabular}
8. Module: Resets (BOR)

An unexpected Reset may occur if the Brown-out Reset (BOR) module is disabled, and then re-enabled when the High/Low-Voltage Detection (HLVD) module is not enabled (HLVDCON<4> = 0). This issue affects BOR modes: BOREN<1:0> = 10 and BOREN<1:0> = 01. In both of these modes, if the BOR module is re-enabled while the device is active, unexpected Resets may be generated.

**Work around**

If BOR is required, and power consumption is not an issue, use BOREN<1:0> = 11. For BOREN<1:0> = 10 mode, either switch to BOREN<1:0> = 11 mode or enable the HLVD (HLVDCON<4> = 1) prior to entering Sleep. If power consumption is an issue and low power is desired, do not use BOREN<1:0> = 10 mode. Instead, use BOREN<1:0> = 01 and follow the steps below when entering and exiting Sleep.

1. Disable BOR by clearing SBOREN (RCON<6> = 0).

```c
WDTCONbits.SBOREN = 0;
```

2. Enter Sleep mode (if desired).

```c
Sleep();
```

3. After exiting Sleep mode (if entered), enable the HLVD (HLVDCON<4> = 1).

```c
HLVDCONbits.HLVDEN = 1;
```

4. Wait for the internal reference voltage (IrVST) to stabilize (typically 25 µs).

```c
while(!HLVDCONbits.IRVST);
```

5. Re-enable BOR by setting SBOREN (RCON<6> = 1).

```c
WDTCONbits.SBOREN = 1;
```

6. Disable the HLVD by clearing HLVDEN (HLVDCON<4> = 0).

```c
HLVDCONbits.HLVDEN = 0;
```

**Affected Silicon Revisions**

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9. Module: RG5 Pin

RG5 will cause excess pin leakage whenever it is driven low. When RG5 is held at 0V, the pin will typically source an additional 160 µA of current.

**Work around**

In power-sensitive applications, using RG5 as an input, ensure that any input attached to this pin Idles high.

**Affected Silicon Revisions**

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10. Module: External Memory Bus (EMB)

The CE signal will not be extended properly if Wait states are used. The duration of the CE signal will remain 0 TCY despite the setting in MEMCON<5:4>.

**Work around**

None.

**Affected Silicon Revisions**

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11. Module: Primary Oscillator (XT Mode)

On some parts, using the XT oscillator at the top end of its specified frequency range (3.0-4.0 MHz) may cause the part to cease driving the oscillator.

**Work around**

Use XT mode only for frequencies lower than 3.0 MHz.

Use HS mode if frequencies greater than 3.0 MHz on a crystal oscillator are required.

**Affected Silicon Revisions**

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12. Module: Timer1/3/5/7

When Timer1, Timer3, Timer5 or Timer7 is operated in Asynchronous External Input mode, unexpected interrupt flag generation may occur if an external clock edge arrives too soon following a firmware write to the TMRxH:TMRxL registers. An unexpected interrupt flag event may also occur when enabling the module or switching from Synchronous to Asynchronous mode.

**Work around**

This issue only applies when operating the timer in Asynchronous mode. Whenever possible, operate the timer module in Synchronous mode to avoid spurious timer interrupts.

If Asynchronous mode must be used in the application, potential strategies to mitigate the issue may include any of the following:

- Design the firmware so it does not rely on the TMRxIF flag or keep the respective interrupt disabled. The timer still counts normally and does not reset to 0x0000 when the spurious interrupt flag event is generated.
- Design the firmware so that it does not write to the TMRxH:TMRxL registers or does not periodically disable/enable the timer, or switch modes. Reading from the timer does not trigger the spurious interrupt flag events.
- If the firmware must use the timer interrupts and must write to the timer (or disable/enable, or mode switch the timer), implement code to suppress the spurious interrupt event, should it occur. This can be achieved by following the process shown in Example 3.

**EXAMPLE 3: ASYNCHRONOUS TIMER MODE WORK AROUND TO AVOID SPURIOUS INTERRUPT**

```c
//Timer1 update procedure in asynchronous mode
//The code below uses Timer1 as example

T1CONbits.TMR1ON = 0; //Stop timer from incrementing
PIE1bits.TMR1IE = 0; //Temporarily disable Timer1 interrupt vectoring
TMR1H = 0x00; //Update timer value
TMR1L = 0x00;
T1CONbits.TMR1ON = 1; //Turn on timer

//Now wait at least two full T1CKI periods + 2TCY before re-enabling Timer1 interrupts.
//Depending upon clock edge timing relative to TMR1H/TMR1L firmware write operation,
//a spurious TMR1IF flag event may sometimes assert. If this happens, to suppress
//the actual interrupt vectoring, the TMR1IE bit should be kept clear until
//after the "window of opportunity" (for the spurious interrupt flag event has passed).
//After the window is passed, no further spurious interrupts occur, at least
//until the next timer write (or mode switch/enable event).
while(TMR1L < 0x02); //Wait for 2 timer increments more than the Updated Timer
                  //value (indicating more than 2 full T1CKI clock periods elapsed)
NOP(); //Wait two more instruction cycles
NOP();
PIE1bits.TMR1IE = 0; //Clear TMR1IF flag, in case it was spuriously set
PIE1bits.TMR1IE = 1; //Now re-enable interrupt vectoring for timer 1
```

**Affected Silicon Revisions**

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13. Module: MSSP1

MSSP1 SPI Slave samples SDI on rising and falling edges of SCK. The MSSP1 SPI in Slave mode improperly samples the SDI data input on both the rising and falling edges of the SCK clock input. This results in unexpected receive data.

Work around
Use MSSP2 for slave SPI operation.

Affected Silicon Revisions

<table>
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</table>
Data Sheet Clarifications

The following typographic corrections and clarifications are to be noted for the latest version of the device data sheet (DS30009960F):

<table>
<thead>
<tr>
<th>Note</th>
<th>Corrections are shown in bold. Where possible, the original bold text formatting has been removed for clarity.</th>
</tr>
</thead>
</table>

None.
APPENDIX A: DOCUMENT
REVISION HISTORY

Rev P Document (12/2018)
Data Sheet Clarifications: Removed data sheet corrections.

Rev N Document (01/2017)
Data Sheet Clarifications: Added Module 7 – DC Characteristic (Comparator Specifications). Other minor corrections.

Rev M Document (9/2016)
Added silicon issue 13 (MSSP1).

Rev L Document (7/2015)
Added silicon revision B5; Other minor corrections.

Rev K Document (03/2015)
Added silicon revision C6; Other minor corrections.
Added Module 12, Timer1/3/5/7
Data Sheet Clarifications: added Module 6.

Rev J Document (9/2014)
Added silicon revision C5.

Rev H Document (9/2014)
Added Module 7.2; Other minor corrections.

Data Sheet Clarifications: Added Module 5; Other minor corrections.

Rev F Document (12/2013)
Added silicon issues 1.2 (Analog-to-Digital Converter) and 11 (Primary Oscillator - XT Mode); Other minor corrections.

Rev E Document (10/2012)
Added MPLAB X IDE; Added Silicon Revision C3.
Data Sheet Clarifications: Added Module 4, DC Characteristics (Input Low Voltage and Input High Voltage).

Rev D Document (2/2012)
Added silicon issue 10 (External Memory Bus – EMB).
Added data sheet clarifications 2 (Voltage Regulator Pins – ENVREG and VCAP/VDDCORE) and 3 (DC Characteristics – Injection Current).

Added silicon issues 7 (Ultra Low-Power Sleep), 8 (Resets – BOR) and 9 (RG5 Pin). Removed data sheet clarifications 1-3 (Voltage Regulator Pins – ENVREG and VCAP/VDDCORE). Added data sheet clarification 1 (Electrical Characteristics).

Removed silicon issue 2 (Brown-out Reset). Changes were made to silicon issue 3 (HLVD). Added silicon issues 4 (ECCP), 5 (EUSART) and 6 (IPD and IDD).

Initial release of this document. Silicon issues 1 (A/D), 2 (BOR), 3 (HLVD) and 4 (Ports).
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