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Object of Declaration: MCP1632 Single-Cell Li-Ion Battery Charger Demo Board

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Manufacturer: Microchip Technology Inc.
2355 W. Chandler Blvd.
Chandler, Arizona, 85224-6199
USA

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Signed for and on behalf of Microchip Technology Inc. at Chandler, Arizona, USA

[Signature]
Derek Carlson
VP Development Tools

12-Sep-14
Date
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Preface

NOTICE TO CUSTOMERS

All documentation becomes dated, and this manual is no exception. Microchip tools and documentation are constantly evolving to meet customer needs, so some actual dialogs and/or tool descriptions may differ from those in this document. Please refer to our web site (www.microchip.com) to obtain the latest documentation available.

Documents are identified with a “DS” number. This number is located on the bottom of each page, in front of the page number. The numbering convention for the DS number is “DSXXYYYYYYA”, where “YYYYYY” is the document number and “A” is the revision level of the document.

For the most up-to-date information on development tools, see the MPLAB® IDE online help. Select the Help menu, and then Topics to open a list of available online help files.

INTRODUCTION

This chapter contains general information that will be useful to know before using the MCP1632 Single-Cell Li-Ion Battery Charger Demo Board. Items discussed in this chapter include:

• Document Layout
• Conventions Used in this Guide
• Recommended Reading
• Recommended Reading
• The Microchip Web Site
• Customer Support
• Customer Support
• Revision History

DOCUMENT LAYOUT

This document describes how to use the MCP1632 Single-Cell Li-Ion Battery Charger Demo Board as a development tool to emulate and debug firmware on a target board, as well as how to program devices. The document is organized as follows:

• Chapter 1. “Product Overview” – Important information about the MCP1632 Single-Cell Li-Ion Battery Charger Demo Board.
• Chapter 2. “Installation and Operation” – Includes instructions on how to get started with this user’s guide and a description of the user’s guide.
• Appendix A. “Schematic and Layouts” – Shows the schematic and layout diagrams for the MCP1632 Single-Cell Li-Ion Battery Charger Demo Board.
• Appendix B. “Bill of Materials (BOM)” – Lists the parts used to build the MCP1632 Single-Cell Li-Ion Battery Charger Demo Board.
**CONVENTIONS USED IN THIS GUIDE**

This manual uses the following documentation conventions:

<table>
<thead>
<tr>
<th>DOCUMENTATION CONVENTIONS</th>
<th>Description</th>
<th>Represents</th>
<th>Examples</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Arial font:</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Italic characters</td>
<td>Referenced books</td>
<td><em>MPLAB® IDE User's Guide</em></td>
<td>...is the only compiler...</td>
</tr>
<tr>
<td></td>
<td>Emphasized text</td>
<td>the Output window</td>
<td></td>
</tr>
<tr>
<td>Initial caps</td>
<td>A window</td>
<td>the Settings dialog</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A dialog</td>
<td>select Enable Programmer</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A menu selection</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Quotes</td>
<td>A field name in a window or dialog</td>
<td>“Save project before build”</td>
<td></td>
</tr>
<tr>
<td>Underlined, italic text with right angle bracket</td>
<td>A menu path</td>
<td><em>File&gt;</em>&lt;Save&gt;</td>
<td></td>
</tr>
<tr>
<td>Bold characters</td>
<td>A dialog button</td>
<td>Click OK</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A tab</td>
<td>Click the Power tab</td>
<td></td>
</tr>
<tr>
<td>N’Rnnnn</td>
<td>A number in verilog format, where N is the total number of digits, R is the radix and n is a digit.</td>
<td>4'b0010, 2'hF1</td>
<td></td>
</tr>
<tr>
<td>Text in angle brackets &lt; &gt;</td>
<td>A key on the keyboard</td>
<td>Press &lt;Enter&gt;, &lt;F1&gt;</td>
<td></td>
</tr>
<tr>
<td><strong>Courier New font:</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Plain Courier New</td>
<td>Sample source code</td>
<td>#define START</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Filenames</td>
<td>autoexec.bat</td>
<td></td>
</tr>
<tr>
<td></td>
<td>File paths</td>
<td>c:\mcc18\h</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Keywords</td>
<td>.asm, _endasm, static</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Command-line options</td>
<td>-Opa+, -Opa-</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Bit values</td>
<td>0, 1</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Constants</td>
<td>0xFF, ‘A’</td>
<td></td>
</tr>
<tr>
<td>Italic Courier New</td>
<td>A variable argument</td>
<td>file.o, where file can be any valid filename</td>
<td></td>
</tr>
<tr>
<td>Square brackets [ ]</td>
<td>Optional arguments</td>
<td>mcc18 [options] file [options]</td>
<td></td>
</tr>
<tr>
<td>Curly brackets and pipe character: {</td>
<td>Choice of mutually exclusive arguments; an OR selection</td>
<td>errorlevel {0</td>
<td>1}</td>
</tr>
<tr>
<td>Ellipses...</td>
<td>Replaces repeated text</td>
<td>var_name [, var_name...]</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Represents code supplied by user</td>
<td>void main (void) { ... }</td>
<td></td>
</tr>
</tbody>
</table>
RECOMMENDED READING

This user's guide describes how to use the MCP1632 Single-Cell Li-Ion Battery Charger Demo Board. Other useful documents are listed below. The following Microchip documents are available and recommended as supplemental reference resources.

- MCP1632 Data Sheet – “High-Speed, Low-Side PWM Controller” (DS20005254)

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- **General Technical Support** – Frequently Asked Questions (FAQs), technical support requests, online discussion groups, Microchip consultant program member listing
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- Field Application Engineer (FAE)
- Technical Support

Customers should contact their distributor, representative or field application engineer (FAE) for support. Local sales offices are also available to help customers. A listing of sales offices and locations is included in the back of this document.

Technical support is available through the web site at:

http://www.microchip.com/support.

REVISION HISTORY

Revision A (November 2014)

- Initial release of this document.
NOTES:
1.1 INTRODUCTION

The MCP1632 Single-Cell Li-Ion Battery Charger Demo Board is a step-up/step-down, switch-mode, DC/DC converter used for battery charging applications. The demo board provides a 4.2V constant voltage source. Other output voltages can be obtained with minor modifications to the board’s Bill of Materials (BOM).

The MCP1632 Single-Cell Li-Ion Battery Charger Demo Board is an intelligent battery charging system for a single-cell Lithium-Ion battery. MCP1632 Single-Cell Li-Ion Battery Charger Demo Board utilizes Microchip’s MCP1632 high-speed Pulse-Width Modulator (PWM). The 8-pin MCP1632 device contains all the analog components necessary for a peak current mode control loop including an error amplifier, PWM comparator and a high-current driver output pin.

An 8-pin PIC12F1822 microcontroller is used to implement the charging algorithm. In addition, the PIC12F1822 firmware supervises the battery voltage and current.

1.2 BOARD FEATURES

The MCP1632 Single-Cell Li-Ion Battery Charger Demo Board has the following features:

- Compact size, highly efficient battery charger
- Can operate in Buck (step-down) or Boost (step-up) mode
- Maximum output current: 1500 mA; can be adjusted via firmware
- Chemistry-optimized charging algorithm
- Maximum output power: 7W
- Factory-programmed source code provided
- Additional application functions can be implemented in the firmware

1.3 DEVICE SUMMARY

The MCP1632 Single-Cell Li-Ion Battery Charger Demo Board uses the following primary devices on the board:

- MCP1632 high-speed current mode PWM controller. – When used in conjunction with a microcontroller, the MCP1632 will control the power system duty cycle to provide output current and/or voltage regulation.
- PIC12F1822 microcontroller (8-bit MCU) – Used to implement the charging algorithm and to provide additional software functions like protections.
- MCP1703 low dropout regulator (LDO) – Used to supply regulated voltage (+5V) to the PIC12F1822 microcontroller and the MCP1632 PWM controller
- MCP6021 operational amplifier – Used for the current sensing circuit.
1.4 TECHNICAL SPECIFICATIONS

- Input voltage: +4.5V to +12V
- Load disconnect protection software configurable
- Typical output current: 1000 mA
- Maximum output current: 1500 mA (with firmware adjustments)
- Typical output power: 4.2W (maximum 7W at +25°C degree ambient temperature)
- Fully protected against Short-Circuit and No Load condition
- Figure 1-1 shows a simplified block diagram of the application

![Figure 1-1: MCP1632 Block Diagram.](image)

1.5 FUNCTIONAL DESCRIPTION

MCP1632 provides all the analog functions necessary to implement a stand-alone switch-mode power converter. When combined with an external microcontroller, the MCP1632 can be used to implement different intelligent converters like those necessary for battery chargers.

The power train of this application uses the Single-Ended Primary Inductor Converter (SEPIC) topology. This topology offers buck-boost functionality and also has non-pulsating input current.

The converter provides constant voltage with limited current at the output, necessary for certain battery charging applications (ex. Li-Ion-based batteries).

The output voltage is measured with a voltage divider resistor pair (R1, R5). This voltage must be precisely 4.2V, required by the battery chemistry.

The average current in the L1B inductor, which is also the output current of the converter, is sensed using a 0.1Ω shunt resistor (RS). As the voltage across the shunt resistor is negative, a -10x amplifier (U3) is used for battery charging current sensing. The conversion gain of this circuit is 1V/A.

The PWM output available from the PIC12F1822 microcontroller is used to control the reference voltage of the MCP1632 using the circuit created with D2 and R3 components. Maximum output current is set by the PIC12F1822 microcontroller.
1.6 WHAT DOES THE MCP1632 SINGLE-CELL LI-ION BATTERY CHARGER DEMO BOARD INCLUDE?

The MCP1632 Single-Cell Li-Ion Battery Charger Demo Board includes:

- MCP1632 Single-Cell Li-Ion Battery Charger Demo Board (ARD00558)
- Information Sheet
Chapter 2. Installation and Operation

2.1 GETTING STARTED

The MCP1632 Single-Cell Li-Ion Battery Charger Demo Board is fully assembled and tested. The board requires the use of an external input voltage source (+4.5V to +12V).

2.1.1 Additional Components Required for Operation

• A DC Power Supply. A bench supply that can produce between 4.5V and 12V, 2A is recommended to operate the board at the full rated power. A USB connector can also be used. In this case, make sure that the input current does not exceed the USB connector requirements. Note that there is no USB device enumeration mechanism on this board.
• An oscilloscope and/or multi-meter to observe waveforms and measure electrical parameters (optional).

2.2 SETUP PROCEDURE

To operate the demonstration board, you need to complete the following steps:
1. Connect a power supply to the input connector J1 (observe the polarity).
2. Attach a single-cell battery to the output connector J2 (observe the polarity).
3. Press the Start/Stop Button to start the battery charging and again to stop it.

Detailed instructions are provided below for each step.

**WARNING**

Please observe the polarity for all steps to avoid board damage.

2.2.1 Demo Board Output Current Configuration

The board is configured to deliver 1000 mA to a single-cell battery. Maximum output voltage is set to approximately 4.2V.
2.2.2 Connecting the Single-Cell Battery

A single-cell battery can be used to evaluate the board. In this case, the power delivered to the load will be about 4.2W.

The board can charge a single-cell battery with 1000 mA as the output current. Maximum output voltage is set to 4.2V (Li-Ion specific) for the default software/hardware configuration. The output voltage can be modified with minor software/hardware modifications.

![Power Supply and Load Connection Diagram.]

2.2.3 Powering the Board

Connect a power supply to J1 to power-up the MCP1632 Single-Cell Li-Ion Battery Charger Demo Board. Ensure that the power supply has the (+) terminal connected to J2 terminal block at pin 1 (up) and (–) terminal connected to pin 2 (down). The input voltage source should be limited to the 4.5V to 12V range. Ensure that the chosen power supply can provide enough current at the selected voltage to properly charge the single-cell battery.

For 12V input voltage the current drain will be around 650 mA at full load (7W).

**WARNING**

This board does not have a Thermal Shut-Down function implemented. Please ensure that the board load is properly cooled.

2.2.4 Using the Reference Board

The button is used to start or stop the battery charging.

Board is protected for the No-Load Condition. Typical value is +4.2 V\text{DC} for the output voltage.

**Note:** It is not recommended to operate the board without a proper load connected to output. Maximum power at the output must be limited to 7W at ambient temperature.
2.3 EVALUATING THE APPLICATION

The best way to evaluate the MCP1632 Single-Cell Li-Ion Battery Charger Demo Board is to examine the circuit and measure voltages and currents with a Digital Voltage Meter (DVM) and probe the board with an oscilloscope.

Additional tools are necessary to evaluate some technical parameters of the board (temperature of power components, ability to withstand surge voltage pulse on input, EMI).

The firmware program in the PIC12F1822 can also be edited to modify the operation of the application.

2.4 FIRMWARE DESCRIPTION

The PIC12F1822 comes pre-programmed with firmware to operate the system as described above. The firmware structure is shown in Figure 2-2.

The main loop controls all the voltage and current regulating functions. The battery charging state machine is only called every second and makes decisions based only on the output voltage and current values. It sets the voltage and current limit, depending on the charging state.

FIGURE 2-2: Library File Structure.
2.4.1 Main Loop Description

The charger state machine is hardware independent, so all the output regulation is done in the main loop.

Besides calling the state machine every second, different parameters and macros are required for the state machine code. All values are 12 bits (4 x 10-bit ADC readings).

\( V_{\text{SENSE}} \) and \( I_{\text{SENSE}} \) contain updated values of the output voltage and current. They can be defined as macros or return functions:

- \#define \( V_{\text{SENSE}} \) \( V_{\text{OUT}} \)
- \#define \( I_{\text{SENSE}} \) \( I_{\text{OUT}} \)

\text{Set\_Voltage}(x) \) and \text{Set\_Current}(x) \) set the converter maximum output voltage and current. They can be defined as macros or functions:

- \#define \text{Set\_Voltage}(x) \{ \text{vref} = x; \}
- \#define \text{Set\_Current}(x) \{ \text{iref} = x; \}

\text{Set\_Led\_Blink}(x) \) sets the LED state and blink rate to show the current battery charging state.

\text{Constant\_Voltage} should show whether the converter is regulating the output voltage or not. This is important for the state machine, because the minimum current and flat current charge termination should only be initiated in Constant Voltage mode.

- \#define \text{Constant\_Voltage} (!\text{cmode})

\text{I\_Bat\_Detect} \) is a minimum current reading that shows a missing battery/load. The value depends on the current shunt amplifier offset and amplification. It is useful for detecting that the battery has been removed during charge, since there is no OCV (Open Circuit Voltage) measurement.

- \#define \text{I\_Bat\_Detect} 16
2.4.2  State Machine Description

There are five states, as shown in Figure 2-3 and explained in Table 2-1.

**FIGURE 2-3:** The Charger State Machine.
An LED is used to signal the charging state. The on/off states and blinking rates are defined in Hardware.h.

### TABLE 2-1: CHARGING STATES

<table>
<thead>
<tr>
<th>State</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Precharge</td>
<td>Charges battery with a low current (usually C/10) until the battery voltage exceeds the defined cutoff voltage.</td>
</tr>
<tr>
<td>Charge</td>
<td>The Charge state has two phases: constant current mode and constant voltage mode. The Charge cycle starts in constant current mode, in which the battery is charged with a constant current (usually C/2) until the battery voltage equals +4.2 VDC. After that, it enters the constant voltage mode, keeping a constant voltage at the output (+4.2 VDC). When the current is under the minimum threshold or it does not decrease for a certain time (flat current), the state machine switches to Done state. If the battery is removed before the charging is complete (battery current is under the battery detection current), then the state machine switches to Idle state. If a time out occurs before any of these conditions are triggered, then the state machine will switch to Fault state.</td>
</tr>
<tr>
<td>Done</td>
<td>When the state machine reaches this state, it means that the battery is fully charged and can be removed. The converter is stopped, but, if a special Standby_mode is enabled, then this state will monitor the OCV (Open Circuit Voltage) of the battery and jump back to the Charge state, when it drops too much. If the Standby_mode is not enabled, then it switches to Idle state.</td>
</tr>
<tr>
<td>Idle</td>
<td>In this state, the converter is stopped and the whole system waits for user input. A button press reinitializes the state machine, and the charging process starts from the beginning.</td>
</tr>
<tr>
<td>Fault</td>
<td>Stops the converter and waits for user input. A button press changes the state to Idle.</td>
</tr>
</tbody>
</table>

### TABLE 2-2: LED STATES

<table>
<thead>
<tr>
<th>LED State</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>LED Off</td>
<td>Idle state</td>
</tr>
<tr>
<td>LED blinking 0.5 Hz</td>
<td>Precharge and Charge states</td>
</tr>
<tr>
<td>LED On</td>
<td>Done state</td>
</tr>
<tr>
<td>LED blinking 2 Hz</td>
<td>Fault state</td>
</tr>
</tbody>
</table>

2.4.2.1 CHARGER VARIABLES AND FUNCTIONS

Battery_state – Holds the current charging state of the battery charger. This variable is available to the main program loop.

```c
enum charge_states { IDLE = 0, FAULT = 1, DONE = 2, PRECHARGE = 3, CHARGE = 4, FLOAT = 5 };
```

State_counter – Used as a time-out counter for Precharge and Charge states.

- $I_{\text{MIN}}$ – The minimum current value recorded during the constant voltage phase of the Charge state. When the value of this variable falls below the minimum current threshold (calculated as a fraction of the battery capacity), the charge is complete.
- $I_{\text{MIN, DB}}$ – The minimum current debouncing counter. When the value of $I_{\text{SENSE}}$ is smaller than $I_{\text{MIN}}$ for $I_{\text{MIN, UPDATE}}$ times in a row, $I_{\text{MIN}}$ is updated with the value of $I_{\text{SENSE}}$.
- $I_{\text{FLAT, DB}}$ – The flat current debouncing counter. This counter is reset every time $I_{\text{MIN}}$ is updated. When it reaches zero, it triggers an End of Charge condition.

The charger library has two functions:

- `Init_State_Machine()` initializes the state machine debouncing and time-out counters, sets the charging voltage and current limits and starts the converter. This function should be called when starting to charge from Idle.
- `Battery_State_Machine()` contains the code for each of the charge/battery state machines and will handle state transitions based on the measured current and voltage values. This function expects to be called every second, otherwise the time-out counters measure a different interval.
2.4.2.2 THE BATTERY CHEMISTRY DEFINITION FILES

LiCo.h contains example definitions for charging this chemistry.

It supports all Li-Ion chemistries that have a charging voltage of 4.2V. For Li-Fe cells the charging voltage needs to be changed to 3.6V.

The values in the definition files depend on the charger hardware implementation and the number of ADC samples taken on each measurement. In this case, we have a 10-bit ADC with a 5V reference, and four samples are taken for every measurement. The output current shunt is 0.1Ω, amplified 10 times. The output voltage divider is 2.44.

EQUATION 2-1: VOLTAGE CALCULATION EXAMPLE FOR 4.2V

\[
\text{Voltage Counts} = \frac{\text{ADC maximum} \times \text{Voltage}}{\text{Output Divider} \times \text{ADC Reference}}
\]

\[
\text{Counts} = \frac{4096 \times 4.2V}{2.44 \times 2.048V} = 3443
\]

EQUATION 2-2: CURRENT CALCULATION EXAMPLE FOR 1000 MA

\[
\text{Current Counts} = \frac{\text{ADC maximum} \times \text{Current} \times \text{Shunt Value} \times \text{Amplification}}{\text{ADC Reference}}
\]

\[
\text{Counts} = \frac{4096 \times 1A \times 0.1\Omega \times 10}{2.048V} = 2000
\]
Appendix A. Schematic and Layouts

A.1 INTRODUCTION

This appendix contains the following schematics and layouts for the MCP1632 Single-Cell Li-Ion Battery Charger Demo Board:

- Board – Schematic
- Board – Top Silk
- Board – Top Copper and Silk
- Board – Top Copper
- Board – Bottom Copper
- Board – Bottom Copper and Silk
A.4 BOARD – TOP COPPER AND SILK

MCP1632 Single Cell Li-Ion Battery Charger
A.6 BOARD – BOTTOM COPPER
A.7 BOARD – BOTTOM COPPER AND SILK
### Appendix B. Bill of Materials (BOM)

**TABLE B-1: BILL OF MATERIALS**

<table>
<thead>
<tr>
<th>Quantity</th>
<th>Designator</th>
<th>Description</th>
<th>Manufacturer</th>
<th>Manufacturer Part Number</th>
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<td>Cap. ceramic 1 µF 16V 10% X7R 0603</td>
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**Note:** The components listed in this Bill of Materials are representative of the PCB assembly. The released BOM used in manufacturing uses all RoHS-compliant components.
### TABLE B-1: BILL OF MATERIALS (CONTINUED)

<table>
<thead>
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<th>Quantity</th>
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</table>

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