
Section 17. 10-Bit A/D Converter

HIGHLIGHTS

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17.1 INTRODUCTION

The PIC24F 10-bit A/D Converter has the following key features:

- Successive Approximation Register (SAR) Conversion
- Conversion Speeds of up to 500 ksps
- Up to 16 External Analog Input Channels
- Multiple Internal Reference Input Channels (select devices only)
- External Voltage Reference Input Pins
- Unipolar Differential Sample-and-Hold (S/H) Amplifier
- Automatic Channel Scan mode
- Selectable Conversion Trigger Source
- 16-Word Conversion Result Buffer
- Selectable Buffer Fill modes
- Four Options for Results Alignment
- Operation during CPU Sleep and Idle modes

The 10-bit A/D Converter module accepts a single analog signal at any one instant and converts it to a corresponding 10-bit digital value. It accommodates up to 16 analog inputs and separate reference inputs; the actual number available on a particular device depends on the package size. The heart of the module is a Successive Approximation Register (SAR) type of A/D Converter. Hardware features surrounding the SAR provide flexible configuration and hardware support for automatic operation, and minimize software overhead, especially in high-speed operation. The three major sections surrounding the ADC are analog input selection, a memory mapped output buffer, and timing and control functions.

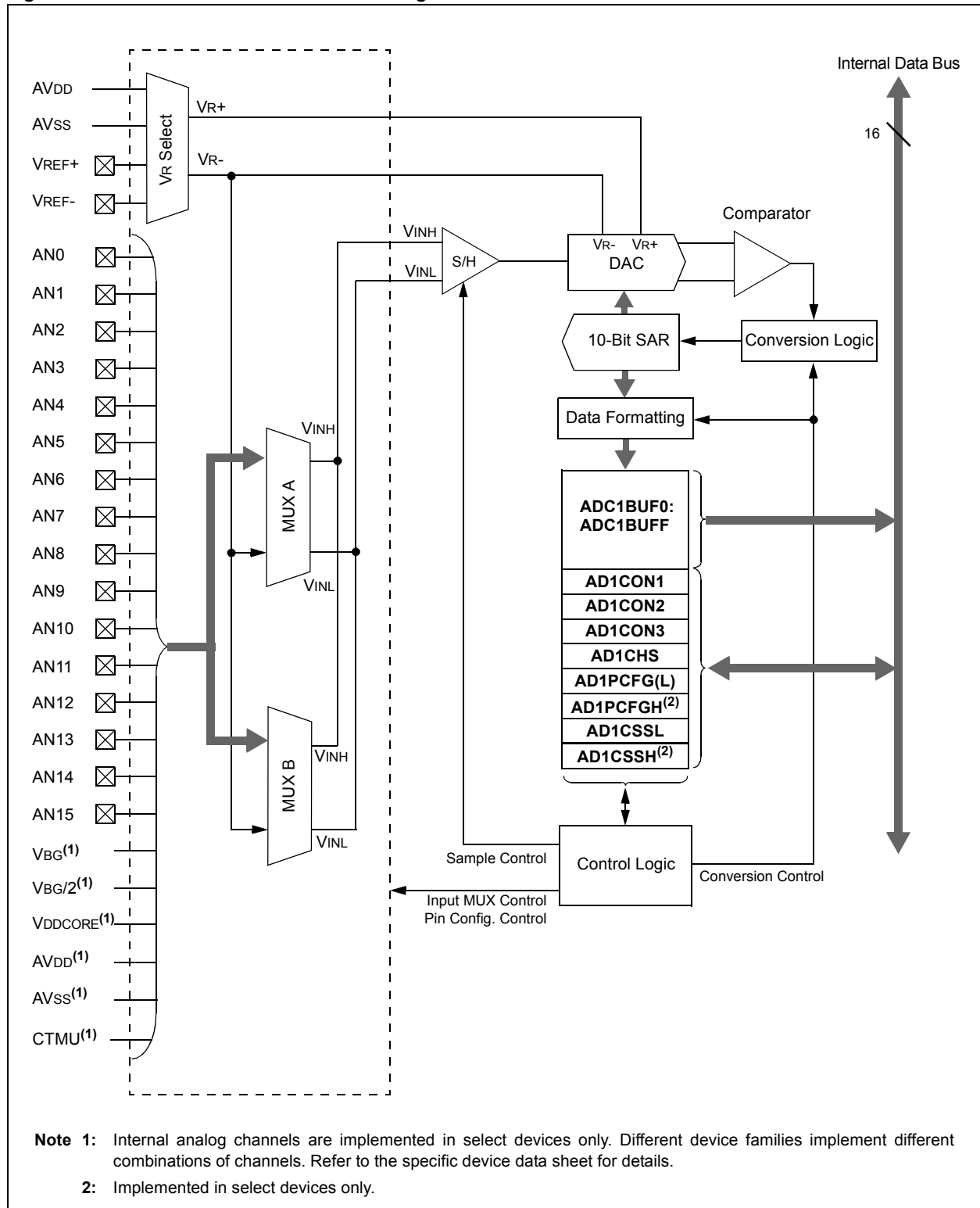
An internal Sample-and-Hold (S/H) amplifier acquires a sample of an input signal, then holds that value constant during the conversion process. A combination of input multiplexers selects the signal to be converted from multiple analog input pins. The whole multiplexer path includes provision for differential analog input, although the number of negative input pins is limited, and the signal difference must remain positive (i.e., unipolar). The sampled voltage is held and converted to a digital value, which strictly speaking, represents the ratio of that input voltage to a reference voltage. Configuration choices allow connection of an external reference or use of the device power and ground (AVDD and AVSS). Reference and input signal pins are assigned differently depending on the particular device.

An array of timing and control selections allow the user to create flexible scanning sequences. Conversions can be started individually by program control, continuously free running, or triggered by selected hardware events. A single channel may be repeatedly converted; alternate conversions may be performed on two channels, or any or all of the channels may be sequentially scanned and converted according to a user-defined bit map. The resulting conversion output is a 10-bit digital number which can be signed or unsigned, left or right justified.

Conversions are automatically stored in a dedicated 16-word buffer, allowing for multiple successive readings to be taken before software service is needed. Successive conversions are placed into sequential buffer locations. Alternatively, the buffer can be split into two 8-word sections for simultaneous conversion and read operations. The module sets its interrupt flag after a selectable number of conversions, from one to sixteen, when the whole buffer can be read. After the interrupt, the sequence restarts at the beginning of the buffer. When the interrupt flag is set according to the earlier selection, scan selections and the Output Buffer Pointer return to their starting positions.

A simplified block diagram for the module is shown in Figure 17-1.

Figure 17-1: 10-Bit A/D Converter Block Diagram



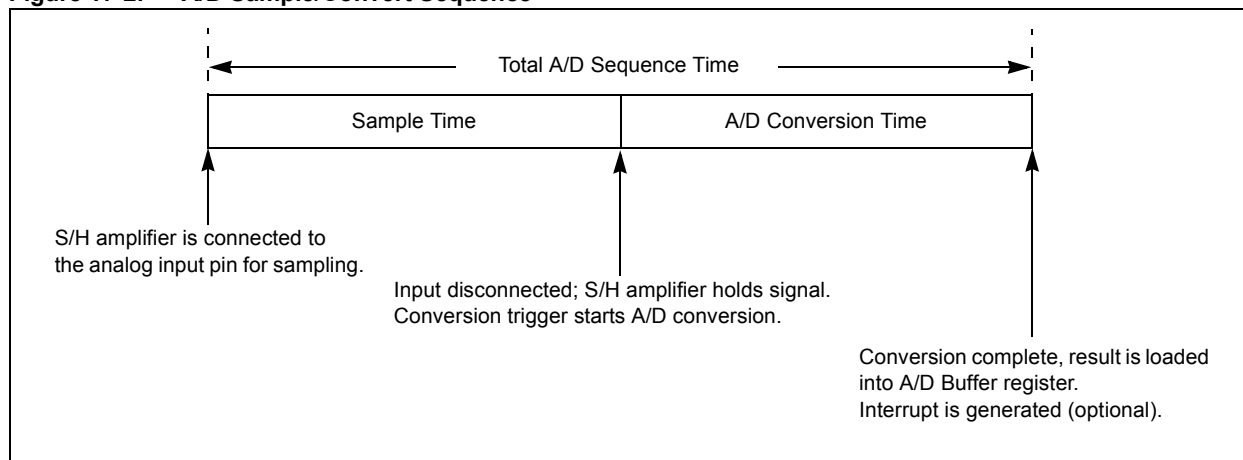
17.2 A/D TERMINOLOGY AND CONVERSION SEQUENCE

Sample time is the time that the A/D module's S/H amplifier is connected to the analog input pin. The sample time may be started and ended automatically by the A/D Converter's hardware or under direct program control. There is a minimum sample time to ensure that the S/H amplifier will give sufficient accuracy for the A/D conversion.

Conversion time is the time required for the A/D Converter to convert the voltage held by the S/H amplifier. The conversion trigger ends the sampling time and begins an A/D conversion or a repeating sequence. The conversion trigger sources can be taken from a variety of hardware sources or can be controlled directly in software. An A/D conversion requires one A/D clock cycle (TAD) to convert each bit of the result, plus two additional clock cycles, or a total of 12 TAD cycles for a 10-bit conversion. When the conversion is complete, the result is loaded into one of 16 A/D result buffers. The S/H can be reconnected to the input pin and a CPU interrupt may be generated. The sum of the sample time and the A/D conversion time provides the total A/D sequence time. Figure 17-2 shows the basic conversion sequence and the relationship between intervals.

The conversion trigger sources can be taken from a variety of hardware sources, or can be controlled directly by software. One of the conversion trigger options is an auto-conversion, which uses a counter and the A/D clock to set the time between auto-conversions. The Auto-Sample mode and auto-conversion trigger can be used together to provide continuous automatic conversions without software intervention.

Figure 17-2: A/D Sample/Convert Sequence



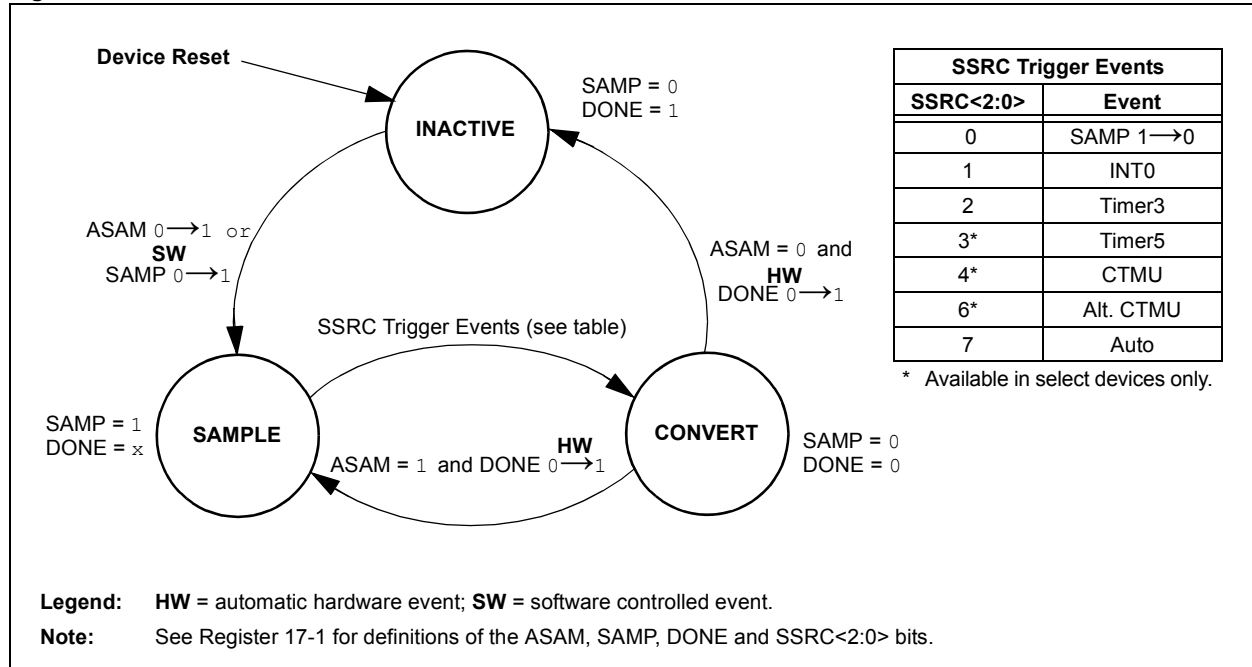
17.2.1 Operation as a State Machine

The A/D conversion process can be thought of in terms of a finite state machine (Figure 17-3). The sample state represents the time that the input channel is connected to the S/H amplifier and the signal is passed to the converter input. The convert state is transitory; the module enters this state as soon as it exits the sample state and transitions to a different state when that is done. The inactive state is the default state prior to module initialization and following a software-controlled conversion; it can be avoided in operation by using Auto-Sample mode. Machine states are identified by the state of several control and status bits in AD1CON1 (Register 17-1).

If the module is configured for Auto-Sample mode, the operation “ping-pongs” continuously between the sample and convert states. The module automatically selects the input channels to be sampled (if channel scanning is enabled), while the selected conversion trigger source paces the entire operation. Any time that Auto-Sample mode is not used for conversion, it is available for the sample state. The user needs to make certain that acquisition time is sufficient, in addition to accounting for the normal concerns about system throughput.

Whenever the issue of sampling time is important, the significant event is the transition from sample to convert state. This is the point where the Sample-and-Hold aperture closes and it is essentially the signal value at this instant which is applied to the A/D for conversion to digital.

Figure 17-3: A/D Module State Machine Model



17.3 REGISTERS

The 10-bit A/D Converter module uses a total of 22 registers for its operation. All registers are mapped in the data memory space.

17.3.1 Control Registers

Depending on the specific device, the module has up to eight control and status registers:

- AD1CON1: A/D Control Register 1
- AD1CON2: A/D Control Register 2
- AD1CON3: A/D Control Register 3
- AD1CHS: A/D Input Channel Select Register
- AD1PCFG(L) and AD1PCFGH: A/D Port Configuration Registers
- AD1CSSL and AD1CSSH: A/D Input Scan Select Registers

The AD1CON1, AD1CON2 and AD1CON3 registers (Register 17-1, Register 17-2 and Register 17-3) control the overall operation of the A/D module. This includes enabling the module, configuring the conversion clock and voltage reference sources, selecting the sampling and conversion triggers, and manually controlling the sample/convert sequences.

The AD1CHS register (Register 17-4) selects the input channels to be connected to the S/H amplifier. It also allows the choice of input multiplexers and the selection of a reference source for differential sampling.

The AD1PCFG (AD1PCFGL in select devices) register (Register 17-5) configures I/O pins as analog inputs or digital I/Os. For PIC24F devices with the internal reference channels, the PCFG<17:16> bits in the AD1PCFGH register (Register 17-6) enable these channels for inclusion in sequential scanning.

The AD1CSSL register (Register 17-7) selects the channels to be included for sequential scanning. For PIC24F devices with the internal reference channels, the AD1CSSH register (Register 17-8) selects these channels for inclusion in sequential scanning.

17.3.2 A/D Result Buffers

The module incorporates a 16-word, dual port RAM, called ADC1BUF, to store the A/D results. Each of the locations is mapped into the data memory space and is separately addressable. The 16 buffer locations are referred to as ADC1BUF0 through ADC1BUFF. The A/D result buffers are read-only.

Register 17-1: AD1CON1: A/D Control Register 1

R/W-0	U-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0
ADON	—	ADSIDL	—	—	—	FORM1	FORM0
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0, HCS	R/C-0, HCS
SSRC2	SSRC1	SSRC0	—	—	ASAM	SAMP	DONE
bit 7						bit 0	

Legend:	C = Clearable bit	U = Unimplemented bit, read as '0'
R = Readable bit	W = Writable bit	HCS = Hardware Clearable/Settable bit
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15 **ADON:** A/D Operating Mode bit
1 = A/D Converter module is operating
0 = A/D Converter is disabled
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **ADSIDL:** Stop in Idle Mode bit
1 = Discontinue module operation when device enters Idle mode
0 = Continue module operation in Idle mode
- bit 12-10 **Unimplemented:** Read as '0'
- bit 9-8 **FORM<1:0>:** Data Output Format bits
11 = Signed fractional (sddd dddd dd00 0000)
10 = Fractional (dddd dddd dd00 0000)
01 = Signed integer (ssss sssd dddd dddd)
00 = Integer (0000 00dd dddd dddd)
- bit 7-5 **SSRC<2:0>:** Conversion Trigger Source Select bits (event ends sampling and starts conversion)
111 = Internal counter (auto-convert)
110 = CTMU event (when not implemented as '100')⁽¹⁾
101 = Reserved
100 = CTMU event⁽¹⁾
011 = Timer5 compare match^(1,2)
010 = Timer3 compare match⁽²⁾
001 = Active transition on INT0 pin (basic sync convert)
000 = Clearing SAMP bit (full program control)
- bit 4-3 **Unimplemented:** Read as '0'
- bit 2 **ASAM:** A/D Sample Auto-Start Mode bit
1 = Sampling begins immediately after last conversion completes; SAMP bit is automatically set
0 = Sampling begins when SAMP bit is set
- bit 1 **SAMP:** A/D Sample Enable Mode Mode bit
1 = A/D Sample-and-Hold amplifier is sampling
0 = A/D Sample-and-Hold amplifier is holding
When ASAM = 0, writing '1' to this bit starts sampling. When SSRC<2:0> = 000, writing '0' to this bit will end sampling and start conversion.
- bit 0 **DONE:** A/D Conversion Status bit
1 = A/D conversion is done
0 = A/D conversion is not done or has not started
Clearing this bit will not affect any operation in progress; it is cleared by software or start of a new conversion.

Note 1: This option is available in select devices only. Refer to the specific device data sheet.

2: Use Timer3 or Timer5 as a clock divider for a fixed sample rate. The T3CK or T5CK input may also be selected with this mode to synchronize with an external event by configuring the counter to clock from the T3CK pin while preset for one pulse. See **Section 14. "Timers"** for more information.

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Register 17-2: AD1CON2: A/D Control Register 2

R/W-0	R/W-0	R/W-0	r-0	U-0	R/W-0	U-0	U-0
VCFG2	VCFG1	VCFG0	r	—	CSCNA	—	—
bit 15							bit 8

R-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
BUFS ⁽¹⁾	—	SMPI3	SMPI2	SMPI1	SMPI0	BUFM	ALTS
bit 7							bit 0

Legend: r = Reserved bit
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-13 **VCFG<2:0>:** Voltage Reference Configuration bits

VCFG<2:0>	VR+	VR-
000	AVDD	AVss
001	External VREF+ Pin	AVss
010	AVDD	External VREF- Pin
011	External VREF+ Pin	External VREF- Pin
1xx	AVDD	AVss

bit 12 **Reserved:** Maintain as '0'

bit 11 **Unimplemented:** Read as '0'

bit 10 **CSCNA:** MUX A Channel Scan/Input Channel Select bit

1 = Scan inputs selected by the AD1CSSL register as the MUX A input

0 = Use the channel selected by the CH0SA bits as the MUX A input

bit 9-8 **Unimplemented:** Read as '0'

bit 7 **BUFS:** Buffer Fill Status bit⁽¹⁾

1 = A/D is currently filling ADC1BUF8-ADC1BUFF, user should access data in ADC1BUF0-ADC1BUF7

0 = A/D is currently filling ADC1BUF0-ADC1BUF7, user should access data in ADC1BUF8-ADC1BUFF

bit 6 **Unimplemented:** Read as '0'

bit 5-2 **SMPI<3:0>:** Sample/Convert Sequences Per Interrupt Selection bits

1111 = Interrupts at the completion of conversion for each 16th sample/convert sequence

1110 = Interrupts at the completion of conversion for each 15th sample/convert sequence

.....

0001 = Interrupts at the completion of conversion for each 2nd sample/convert sequence

0000 = Interrupts at the completion of conversion for each sample/convert sequence

bit 1 **BUFM:** Buffer Mode Select bit

1 = Buffer configured as two 8-word buffers (ADC1BUF0 to ADC1BUF7 and ADC1BUF8 to ADC1BUFF)

0 = Buffer configured as one 16-word buffer (ADC1BUF0 to ADC1BUFF)

bit 0 **ALTS:** Alternate Input Sample Mode Select bit

1 = Alternate between MUX A and MUX B input multiplexer settings on successive conversions, starting with MUX A

0 = Always uses MUX A input multiplexer settings

Note 1: Only valid when ADC1BUF is functioning as two buffers (BUFM = 1).

Register 17-3: AD1CON3: A/D Control Register 3

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ADRC	—	—	SAMC4	SAMC3	SAMC2	SAMC1	SAMC0
bit 15							
			bit 8				
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ADCS7	ADCS6	ADCS5	ADCS4	ADCS3	ADCS2	ADCS1	ADCS0
bit 7							
			bit 0				

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **ADRC:** A/D Conversion Clock Source bit

1 = A/D internal RC clock

0 = Clock derived from system clock

bit 14-13 **Unimplemented:** Read as '0'

bit 12-8 **SAMC<4:0>:** Auto-Sample Time bits

11111 = 31 TAD

.....

00001 = 1 TAD

00000 = 0 TAD (not recommended)

bit 7-0 **ADCS<7:0>:** A/D Conversion Clock Period Select bits⁽¹⁾

11111111

..... = Reserved

01000000

00111111 = 64 • Tcy

.....

00000001 = 2 • Tcy

00000000 = Tcy

Note 1: Only valid when using the system clock as the conversion clock (ADRC = 0).

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Register 17-4: AD1CHS: A/D Input Channel Select Register

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0NB	—	—	CH0SB4 ⁽¹⁾	CH0SB3	CH0SB2	CH0SB1	CH0SB0
bit 15			bit 8				

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0NA	—	—	CH0SA4 ⁽¹⁾	CH0SA3	CH0SA2	CH0SA1	CH0SA0
bit 7			bit 0				

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **CH0NB:** S/H Amplifier Negative Input Select for MUX B Multiplexer Setting bit

1 = Negative input is AN1

0 = Negative input is VR-

bit 14-13 **Unimplemented:** Read as '0'

bit 12-8 **CH0SB<4:0>:** S/H Amplifier Positive Input Select for MUX B Multiplexer Setting bits⁽¹⁾

The number of implemented analog inputs and the bit combinations assigned to them vary significantly between device families. In general, external analog inputs, AN0 through AN15 (where implemented), are sequentially assigned from '00000' as shown below. If a sequential input is unimplemented, its corresponding bit value is also unimplemented.

In addition, some devices implement inputs for internal band gap references, external voltage references, and other analog modules, such as the CTMU. Refer to the specific device data sheet for a complete listing of implemented inputs for a particular device.

Any bit combinations not explicitly listed are unimplemented. Using an unimplemented channel for a conversion will produce unpredictable results.

01111 = Positive input is AN15

01110 = Positive input is AN14

01101 = Positive input is AN13

01100 = Positive input is AN12

01011 = Positive input is AN11

01010 = Positive input is AN10

01001 = Positive input is AN9

01000 = Positive input is AN8

00111 = Positive input is AN7

00110 = Positive input is AN6

00101 = Positive input is AN5

00100 = Positive input is AN4

00011 = Positive input is AN3

00010 = Positive input is AN2

00001 = Positive input is AN1

00000 = Positive input is AN0

bit 7 **CH0NA:** S/H Amplifier Negative Input Select for MUX A Multiplexer Setting bit

1 = Negative input is AN1

0 = Negative input is VR-

bit 6-5 **Unimplemented:** Read as '0'

bit 4-0 **CH0SA<4:0>:** S/H Amplifier Positive Input Select for MUX A Multiplexer Setting bits⁽¹⁾

Implemented combinations are identical to those for CH0SB<4:0>.

Note 1: CH0SB4 and CH0SA4 are implemented in select devices only. Their implementation generally indicates an extended range of input sources from voltage references and other analog modules.

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Register 17-5: AD1PCFG(L): A/D Port Configuration Low Register⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PCFG15	PCFG14	PCFG13	PCFG12	PCFG11	PCFG10	PCFG9	PCFG8
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PCFG7	PCFG6	PCFG5	PCFG4	PCFG3	PCFG2	PCFG1	PCFG0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **PCFG<15:0>**: Analog Input Pin Configuration Control bits

1 = Pin for corresponding analog channel is in Digital mode; port read input enabled, A/D input multiplexer input connected to AVss

0 = Pin for corresponding analog channel is in Analog mode; port read input disabled, A/D module samples pin voltage

Note 1: In devices without the internal band gap reference options, this register is named AD1PCFG. In devices with the band gap options, it is named AD1PCFGL.

Register 17-6: AD1PCFGH: A/D Port Configuration High Register⁽¹⁾

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	PCFG17	PCFG16
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-2 **Unimplemented:** Read as '0'

bit 1 **PCFG17:** A/D Input Band Gap Scan Enable bit

1 = Analog channel disabled from input scan

0 = Internal band gap (V_{BG}) channel enabled for A/D MUX input

bit 0 **PCFG16:** A/D Input Half Band Gap Scan Enable bit

1 = Analog channel disabled from input scan

0 = Internal V_{BG}/2 channel enabled for A/D MUX input

Note 1: AD1PCFGH is implemented in select devices only.

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Register 17-7: AD1CSSL: A/D Input Scan Select Low Register for MUX A⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CSSL15	CSSL14	CSSL13	CSSL12	CSSL11	CSSL10	CSSL9	CSSL8
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CSSL7	CSSL6	CSSL5	CSSL4	CSSL3	CSSL2	CSSL1	CSSL0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **CSSL<15:0>**: A/D Input Channel Scan Selection bits

1 = Corresponding analog channel, ANx, is selected for sequential scanning on MUX A

0 = Corresponding analog channel is ignored in sequential scanning

Note 1: Only MUX A supports scanning of input channels.

Register 17-8: AD1CSSH: A/D Input Scan Select High Register for MUX A^(1,2)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	CSSL17	CSSL16
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-2 **Unimplemented:** Read as '0'

bit 1 **CSSL17**: A/D Input Band Gap Scan Selection bit

1 = Internal band gap (VBG) channel is selected for sequential scanning on MUX A

0 = Analog channel is ignored in sequential scanning

bit 0 **CSSL16**: A/D Input Half Band Gap Scan Selection bit

1 = Internal VBG/2 channel is selected for sequential scanning on MUX A

0 = Analog channel is ignored in sequential scanning

Note 1: Only MUX A supports scanning of input channels.

2: AD1CSSH is implemented in select devices only.

17.4 A/D MODULE CONFIGURATION

All of the registers described in the previous section must be configured for module operation to be fully defined. An effective approach is first to describe the signals and sequences for the particular application. Typically, it is an iterative process to assign signals to port pins, to establish timing methods and to organize a scanning scheme, as well as to integrate the whole process with the software design.

The various configuration and control functions of the module are distributed throughout the module's six (or eight) control registers. Control functions can be broadly sorted into four groups: input, timing, conversion and output. Table 17-1 shows the register location of control or status bits by register.

Table 17-1: A/D Module Functions by Registers and Bits

A/D Function	Register(s)	Specific Bits
Input	AD1CON2	VCFG<2:0>, CSCNA, ALTS
	AD1CHS	CH0NB, CH0SB<4:0>, CH0NA, CH0SA<4:0>
	AD1PCFG(H/L)	PCFG<17:16> ⁽¹⁾ , PCFG<15:0>
	AD1CSS(H/L)	CSSL<17:16> ⁽¹⁾ , CSSL<15:0>
Conversion	AD1CON1	ADON, ADSIDL, SSRC<2:0>, ASAM, SAMP, DONE
	AD1CON2	SMPI<3:0>
Timing	AD1CON3	ADRC, SAMC<4:0>, ADCS<7:0>
Output	AD1CON1	FORM<1:0>
	AD1CON2	BUFS, BUFM

Note 1: Implemented in select devices only.

Note: Do not write to the SSRC, ASAM, BUFS, SMPI, BUFM and ALTS bits, or the AD1CON3 and AD1CSSL registers, while ADON = 1; otherwise, indeterminate conversion data may result.

The following steps should be followed for performing an A/D conversion.

- Configure the A/D module:
 - Select voltage reference source to match expected range on analog inputs
 - Select the analog conversion clock to match desired data rate with processor clock
 - Determine how sampling will occur
 - Set the multiplexer input assignments
 - Select the desired sample/conversion sequence
 - Select the output data format
 - Select the number of readings per interrupt
- Configure A/D interrupt (if required):
 - Clear AD1IF bit
 - Select A/D interrupt priority
- Turn on A/D module.

The options for each configuration step are described in the subsequent sections.

17.4.1 Selecting the Voltage Reference Source

The voltage references for A/D conversions are selected using the VCFG<2:0> control bits (AD1CON2<15:13>). The upper voltage reference (VR+) and the lower voltage reference (VR-) may be the internal AVDD and AVSS voltage rails or the VREF+ and VREF- input pins.

The external voltage reference pins may be shared with the AN0 and AN1 inputs on low pin count devices. The A/D Converter can still perform conversions on these pins when they are shared with the VREF+ and VREF- input pins.

The voltages applied to the external reference pins must meet certain specifications. Refer to **Section 17.16 "Electrical Specifications"** for further details.

17.4.2 Selecting the A/D Conversion Clock

The A/D Converter has a maximum rate at which conversions may be completed. An analog module clock, TAD, controls the conversion timing. The A/D conversion requires 12 clock periods (12 TAD). The A/D clock is derived from the device instruction clock.

The period of the A/D conversion clock is software selected using a 6-bit counter. There are 64 possible options for TAD, specified by the ADCS bits in the AD1CON3 register. Equation 17-1 gives the TAD value as a function of the ADCS control bits and the device instruction cycle clock period, T_{CY}. For correct A/D conversions, the A/D conversion clock (TAD) must be selected to ensure a minimum TAD time of 75 ns.

Equation 17-1: A/D Conversion Clock Period

$$TAD = T_{CY} (ADCS + 1)$$

$$ADCS = \frac{TAD}{T_{CY}} - 1$$

Note: Based on T_{CY} = 2/F_{OSC}, Doze mode and PLL are disabled.

The A/D Converter also has its own dedicated RC clock source that can be used to perform conversions. The A/D RC clock source should be used when conversions are performed while the device is in Sleep mode. The RC oscillator is selected by setting the ADRC bit (AD1CON3<15>). When the ADRC bit is set, the ADCS bits have no effect on A/D operation.

17.4.3 Configuring Analog Port Pins

The AD1PCFG register (AD1PCFGL and AD1PCFGH registers in select devices) specifies the input condition of device pins used as analog inputs. A pin is configured as an analog input when the corresponding PCFGx bit (AD1PCFG<x>) is cleared. The register is cleared on device Resets, causing the A/D input pins to be configured for analog inputs by default. When configured for analog inputs, the associated port I/O digital input buffer is disabled, so it does not consume current.

For external analog inputs, both the AD1PCFG(L) register and the corresponding TRIS register bits control the operation of the A/D port pins. The port pins that will function as analog inputs must also have their corresponding TRIS bits set, specifying the pins as inputs. After a device Reset, all TRIS bits are set.

If the I/O pin associated with an A/D channel is configured as a digital output (TRIS bit is cleared), while the pin is configured for Analog mode (AD1PCFG<x> = 0), the port digital output level (V_{OH} or V_{OL}) will be converted.

A pin is configured as digital I/O when the corresponding PCFGx bit is set. In this configuration, the input to the analog multiplexer is connected to AV_{SS}.

- Note 1:** When reading a PORT register, any pin configured as an analog input reads as '0'.
- 2:** Analog levels on any pin that is defined as a digital input (including the AN<15:0> pins) may cause the input buffer to consume current that is out of the device's specification.

17.4.4 Input Channel Selection

The A/D Converter incorporates two independent sets of input multiplexers (MUX A and MUX B) that allow users to choose which analog channels are to be sampled. The inputs specified by the CH0SA bits and CH0NA are collectively called the MUX A inputs. The inputs specified by the CH0SB bits and CH0NB are collectively called the MUX B inputs.

Functionally, MUX A and MUX B are very similar to each other. Both multiplexers allow any of the analog input channels to be selected for individual sampling and allow selection of a negative reference source for differential signals. In addition, MUX A can be configured for sequential analog channel scanning. This is discussed in more detail in **Section 17.4.4.1 “Configuring MUX A and MUX B Inputs”** and **Section 17.4.4.3 “Scanning Through Several Inputs”**.

Note: Different PIC24F devices will have different numbers of analog inputs. Verify the analog input availability against the particular device’s data sheet.

17.4.4.1 CONFIGURING MUX A AND MUX B INPUTS

The user may select any one of up to 16 analog inputs to connect to the positive input of the S/H amplifier. For MUX A, the CH0SA<3:0> bits (AD1CHS<3:0>) normally select the analog channel for the positive input. For MUX B, the positive channel is selected by the CH0SB<3:0> bits (AD1CHS<11:8>).

On certain PIC24F devices, users may also select the microcontroller’s internal band gap voltage reference (V_{BG}) or one-half of the reference (V_{BG}/2) as the positive input to the S/H amplifier. For these devices, the CH0SA<4:0> bits (AD1CHS<4:0>) and CH0SB<4:0> bits (AD1CHS<12:8>) select the positive input.

For the negative (inverting) input of the amplifier, the user has two options, selected by the CH0NA and CH0NB bits (AD1CHS<7,15>, respectively). Setting either bit selects AN1 as the multiplexer’s negative input; clearing the bit selects the current V_{R-} source designated by the VCFG<2:0> bits (AD1CON2<15:13>).

17.4.4.2 ALTERNATING MUX A AND MUX B INPUT SELECTIONS

By default, the A/D Converter only samples and converts the inputs selected by MUX A. The ALTS bit (AD1CON2<0>) enables the module to alternate between two sets of inputs selected by MUX A and MUX B during successive samples.

If the ALTS bit is ‘0’, only the inputs specified by the CH0SA and CH0NA bits are selected for sampling. When the ALTS bit is ‘1’, the module will alternate between the MUX A inputs on one sample and the MUX B inputs on the subsequent sample.

If the ALTS bit is ‘1’ on the first sample/convert sequence, the inputs specified by the CH0SA bits and CH0NA are selected for sampling. On the next sample/convert sequence, the inputs specified by the CH0SB bits and CH0NB are selected for sampling. This pattern repeats for subsequent sample conversion sequences.

17.4.4.3 SCANNING THROUGH SEVERAL INPUTS

When using MUX A to select analog inputs, the A/D module has the ability to scan multiple analog channels. When the CSCNA bit (AD1CON2<10>) is set, the CH0SA bits are ignored and the channels specified by the AD1CSSL register are sequentially sampled.

Each bit in the AD1CSSL register and AD1CSSH register (when implemented) corresponds to one of the analog channels. If a bit in the AD1CSSL or AD1CSSH register is set, the corresponding analog channel is included in the scan sequence. Inputs are always scanned from lower to higher numbered inputs, starting at the first selected channel after each interrupt occurs.

Note: If the number of scanned inputs selected is greater than the number of samples taken per interrupt, the higher numbered inputs will not be sampled.

The AD1CSSL or AD1CSSH bits only specify the positive input of the channel. The CH0NA bit still selects the negative input of the channel during scanning.

Scanning is only available on the MUX A input selection. The MUX B input selection, as specified by the CH0SB bits, will still select the alternating input. When alternated sampling between MUX A and MUX B is selected (ALTS = 1), the input will alternate between a set of scanning inputs specified by the AD1CSSL register and a fixed input specified by the CH0SB bits.

17.4.5 Enabling the Module

When the ADON bit (AD1CON1<15>) is set, the module is fully powered and functional. When ADON is '0', the module is disabled. The digital and analog portions of the circuit are turned off for maximum current savings. As the ADC1BUF registers are also part of the A/D module, clearing ADON may also result in a loss of conversion data.

When enabling the module by setting the ADON bit, the user must wait for the analog stages to stabilize. For the stabilization time, refer to **Section 17.16 “Electrical Specifications”**.

17.5 INITIALIZATION

Example 17-1 shows a simple initialization code example for the A/D module. In this particular configuration, all 16 analog input pins are set up as analog inputs. Operation in Idle mode is disabled, output data is in unsigned fractional format, and AVDD and AVSS are used for VR+ and VR-. The start of sampling, as well as the start of conversion (conversion trigger), are performed directly in software. Scanning of inputs is disabled and an interrupt occurs after every sample/convert sequence (1 conversion result) with only one channel (AN0) being converted. The A/D conversion clock is Tcy/2.

This example shows one method of controlling a sample/convert sequence by manually setting and clearing the SAMP bit (AD1CON1<1>). This method, among others, is more fully discussed in **Section 17.6 “Controlling the Sampling Process”** and **Section 17.7 “Controlling the Conversion Process”**.

Example 17-1: A/D Initialization Code Example

```
AD1PCFG = 0xFFFE;    // Configure A/D port
                      // AN0 input pin is analog
AD1CON1 = 0x2202;    // Configure sample clock source
                      // and conversion trigger mode.
                      // Unsigned Fraction format (FORM<1:0>=10),
                      // Manual conversion trigger (SSRC<2:0>=000),
                      // Manual start of sampling (ASAM=0),
                      // No operation in Idle mode (ADSIDL=1),
                      // S/H in Sample (SAMP = 1)
AD1CON2 = 0;         // Configure A/D voltage reference
                      // and buffer fill modes.
                      // Vr+ and Vr- from AVdd and AVss (VCFG<2:0>=000),
                      // Inputs are not scanned,
                      // Interrupt after every sample
AD1CON3 = 0x0100;    // Configure sample time = 1Tad,
                      // A/D conversion clock as Tcy
AD1CHS = 0;          // Configure input channels,
                      // S/H+ input is AN0,
                      // S/H- input is Vr- (AVss).
AD1CSSL = 0;         // No inputs are scanned.
IFS0bits.AD1IF = 0;  // Clear A/D conversion interrupt.

// Configure A/D interrupt priority bits (AD1IP<2:0>) here, if
// required. Default priority level is 4.

IEC0bits.AD1IE = 1;  // Enable A/D conversion interrupt
AD1CON1bits.ADON = 1; // Turn on A/D
AD1CON1bits.SAMP = 1; // Start sampling the input
Delay();              // Ensure the correct sampling time has elapsed
                      // before starting conversion.
AD1CON1bits.SAMP = 0; // End A/D sampling and start conversion

// Example code for A/D ISR:
void __attribute__((__interrupt__)) _ADC1Interrupt(void)
{
    IFS0bits.AD1IF = 0;
}
```


17.6 CONTROLLING THE SAMPLING PROCESS

17.6.1 Manual Sampling

Setting the SAMP bit (AD1CON1<1>) while the ASAM bit (AD1CON1<2>) is clear causes the A/D to begin sampling. Clearing the SAMP bit ends sampling and automatically begins the conversion; however, there must be a sufficient delay between setting and clearing SAMP for the sampling process to start (tpss, parameter AD61). Sampling will not resume until the SAMP bit is once again set. For an example, see Figure 17-4.

17.6.2 Automatic Sampling

Setting the ASAM bit causes the A/D to automatically begin sampling after a conversion has been completed. One of several options can be used to end sampling and complete the conversions. Sampling will continue on the next selected channel after the conversion in progress has completed. For an example, see Figure 17-5.

17.6.3 Monitoring Sample Status

The SAMP bit indicates the sampling state of the A/D. Generally, when the SAMP bit clears, indicating the end of sampling, the DONE bit is automatically cleared to indicate the start of conversion. If SAMP is '0' while DONE is '1', the A/D is in an inactive state.

17.6.4 Aborting a Sample

While in Manual Sampling mode, clearing the SAMP bit will terminate sampling. If SSRC<2:0> = 000, it may also start a conversion automatically.

Clearing the ASAM bit while in Automatic Sampling mode will not terminate an ongoing sample/convert sequence; however, sampling will not automatically resume after a subsequent conversion.

17.7 CONTROLLING THE CONVERSION PROCESS

The conversion trigger source will terminate sampling and start a selected sequence of conversions. The SSRC<2:0> bits (AD1CON1<7:5>) select the source of the conversion trigger.

Note 1: The available conversion trigger sources may vary depending on the PIC24F device variant. Please refer to the specific device data sheet for the available conversion trigger sources.

2: The SSRC selection bits should not be changed when the A/D module is enabled. If the user wishes to change the conversion trigger source, the A/D module should be disabled first by clearing the ADON bit (AD1CON1<15>).

17.7.1 Manual Control

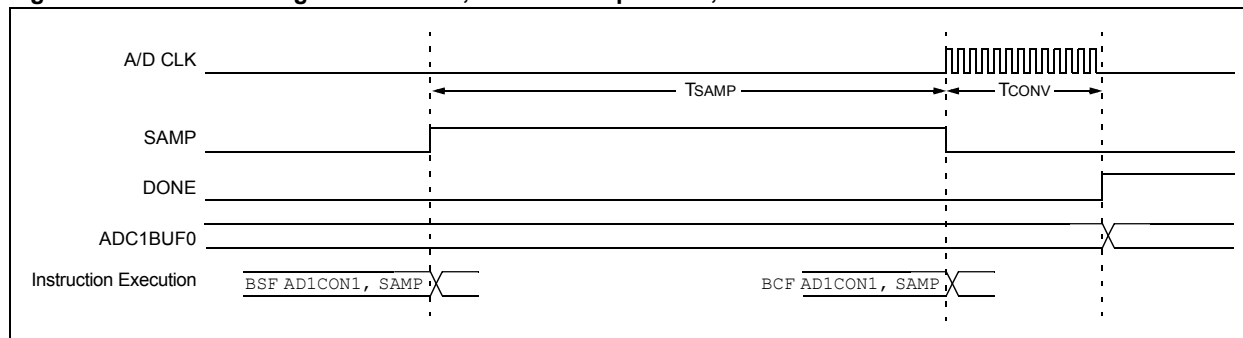
When SSRC<2:0> = 000, the conversion trigger is under software control. Clearing the SAMP bit (AD1CON1<1>) starts the conversion sequence.

Figure 17-4 is an example where setting the SAMP bit initiates sampling, and clearing the SAMP bit terminates sampling and starts conversion. The user software must time the setting and clearing of the SAMP bit to ensure adequate sampling time of the input signal.

Figure 17-5 is an example where setting the ASAM bit initiates automatic sampling, and clearing the SAMP bit terminates sampling and starts conversion. After the conversion completes, the module sets the SAMP bit and returns to the sample state. The user software must time the clearing of the SAMP bit to ensure adequate sampling time of the input signal, understanding that the time since previously clearing the SAMP bit includes the conversion time which immediately follows, as well as the next sampling time.

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Figure 17-4: Converting One Channel, Manual Sample Start, Manual Conversion Start



Example 17-2: Converting One Channel, Manual Sample Start, Manual Conversion Start Code

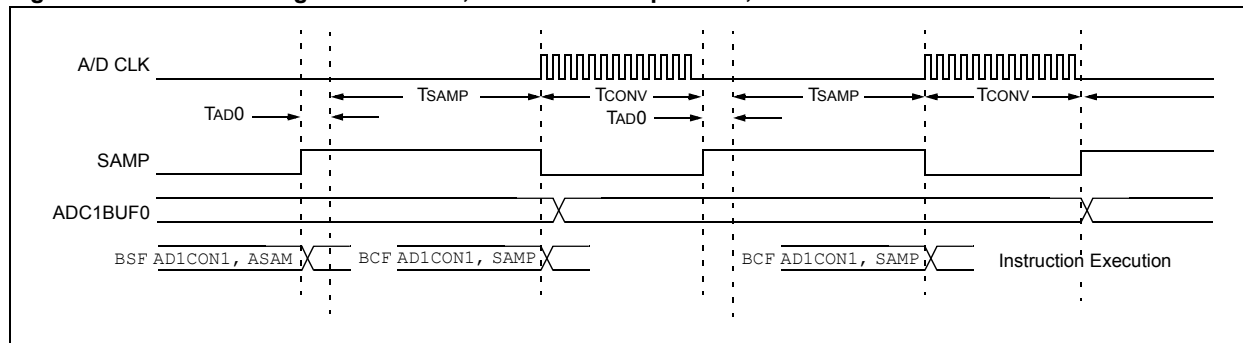
```
int ADCValue;

AD1PCFG = 0xFFFF;           // AN2 as analog, all other pins are digital
AD1CON1 = 0x0000;           // SAMP bit = 0 ends sampling and starts converting
AD1CHS = 0x0002;            // Connect AN2 as S/H+ input
                             // in this example AN2 is the input

AD1CSSL = 0;
AD1CON3 = 0x0002;           // Manual Sample, Tad = 3Tcy
AD1CON2 = 0;
AD1CON1bits.ADON = 1;       // turn ADC ON

while (1)                   // repeat continuously
{
    AD1CON1bits.SAMP = 1;    // start sampling...
    Delay();                 // Ensure the correct sampling time has elapsed
                             // before starting conversion.
    AD1CON1bits.SAMP = 0;    // start converting
    while (!AD1CON1bits.DONE){}; // conversion done?
    ADCValue = ADC1BUF0;     // yes then get ADC value
}
```

Figure 17-5: Converting One Channel, Automatic Sample Start, Manual Conversion Start



17.7.2 Clocked Conversion Trigger

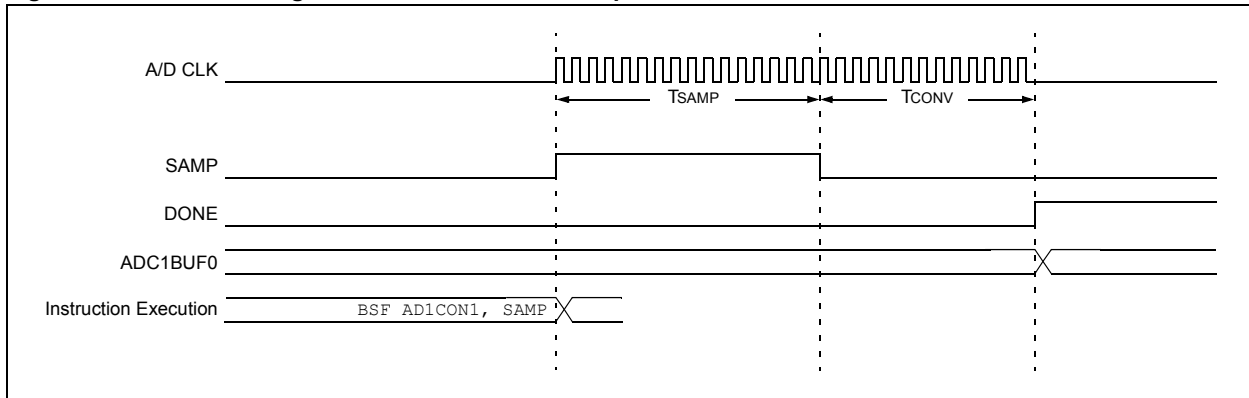
When SSRC<2:0> = 111, the conversion trigger is under A/D clock control. The SAMC bits (AD1CON3<12:8>) select the number of TAD clock cycles between the start of sampling and the start of conversion. After the start of sampling, the module will count a number of TAD clocks specified by the SAMC bits. The SAMC bits must always be programmed for at least 1 clock cycle to ensure sampling requirements are met.

Equation 17-2: Clocked Conversion Trigger Time

$$T_{SMP} = SAMC<4:0> * T_{AD}$$

Figure 17-6 shows how to use the clocked conversion trigger with the sampling started by the user software.

Figure 17-6: Converting One Channel, Manual Sample Start, TAD-Based Conversion Start



Example 17-3: Converting One Channel, Manual Sample Start, TAD-Based Conversion Start Code

```
int ADCValue;

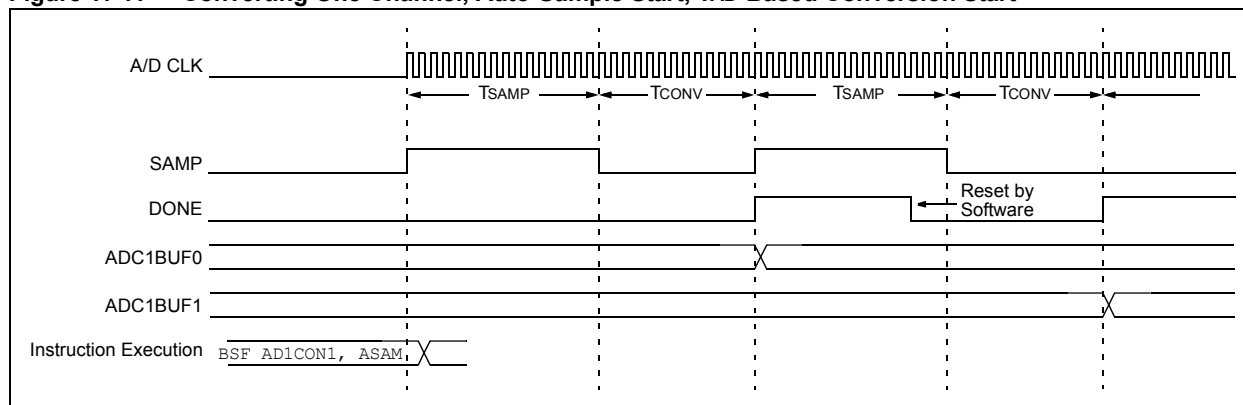
AD1PCFG = 0xEFFF;           // all PORTB = Digital; RB12 = analog
AD1CON1 = 0x00E0;           // SSRC<2:0> = 111 implies internal counter ends sampling
                              // and starts converting.
AD1CHS  = 0x000C;           // Connect AN12 as S/H input.
                              // in this example AN12 is the input
AD1CSSL = 0;
AD1CON3 = 0x1F02;           // Sample time = 31Tad, Tad = 3Tcy
AD1CON2 = 0;
AD1CON1bits.ADON = 1;       // turn ADC ON
while (1)                   // repeat continuously
{
    AD1CON1bits.SAMP = 1;    // start sampling, then after 31Tad go to conversion
    while (!AD1CON1bits.DONE){}; // conversion done?
    ADCValue = ADC1BUF0;     // yes then get ADC value
}                             // repeat
```

17.7.2.1 FREE-RUNNING SAMPLE CONVERSION SEQUENCE

Using the Auto-Convert Conversion Trigger mode (SSRC<2:0> = 111), in combination with the Auto-Sample Start mode (ASAM = 1), allows the A/D module to schedule sample/conversion sequences with no intervention by the user or other device resources. This “Clocked” mode, shown in Figure 17-7, allows continuous data collection after module initialization.

Note that all timing in this mode scales with TAD, either from the A/D internal RC clock or from TCY (as prescaled by the ADCS<7:0> bits). In both cases, the SAMC<4:0> bits set the number of TAD clocks in TSAMP. TCONV is fixed at 12 TAD.

Figure 17-7: Converting One Channel, Auto-Sample Start, TAD-Based Conversion Start



Example 17-4: Converting One Channel, Auto-Sample Start, TAD-Based Conversion Start Code

```
int ADCValue, count;
int *ADC16Ptr;

AD1PCFG = 0xFFFFB;           // AN2 as analog, all other pins are digital
AD1CON1 = 0x00E0;             // SSRC bit = 111 implies internal counter
                                // ends sampling and starts converting.
AD1CHS = 0x0002;              // Connect RB2/AN2 as CH0 input..
                                // in this example RB2/AN2 is the input

AD1CSSL = 0;
AD1CON3 = 0x0F00;             // Sample time = 15Tad, Tad = Tcy
AD1CON2 = 0x0004;             // Set AD1IF after every 2 samples
AD1CON1bits.ADON = 1;         // turn ADC ON
while (1)                     // repeat continuously
{
    ADCValue = 0;              // clear variable
    ADC16Ptr = &ADC1BUF0;      // initialize ADC1BUF pointer
    IFS0bits.AD1IF = 0;        // clear ADC interrupt flag
    AD1CON1bits.ASAM = 1;      // auto start sampling for 31Tad
                                // then go to conversion
    while (!IFS0bits.AD1IF){}; // conversion done?
    AD1CON1bits.ASAM = 0;      // yes then stop sample/convert
    for(count = 0; count < 2; count++) // average the 2 ADC value
    {
        ADCValue = ADCValue + *ADC16Ptr++;
    }
    ADCValue = ADCValue >> 1;
}                               // repeat
```

17.7.2.2 SAMPLE TIME CONSIDERATIONS USING CLOCKED CONVERSION TRIGGER AND AUTOMATIC SAMPLING

The user must ensure the sampling time satisfies the sampling requirements as outlined in **Section 17.10 “A/D Sampling Requirements”**. Assuming that the module is set for automatic sampling and using a clocked conversion trigger, the sampling interval is specified by the SAMC bits.

17.7.3 Event Trigger Conversion Start

It is often desirable to synchronize the end of sampling and the start of conversion with some other time event. The A/D module may use one of three sources as a conversion trigger event.

17.7.3.1 EXTERNAL INTO PIN TRIGGER

When $SSRC\langle 2:0 \rangle = 001$, the A/D conversion is triggered by an active transition on the INTO pin. The pin may be programmed for either a rising edge input or a falling edge input.

17.7.3.2 GENERAL PURPOSE TIMER COMPARE TRIGGER

The A/D is configured in this Trigger mode by setting $SSRC\langle 2:0 \rangle = 010$. When a match occurs between the 32-bit timer, TMR3/TMR2, and the 32-bit combined Period register, PR3/PR2, a special ADC trigger event signal is generated by Timer3. Refer to **Section 14. “Timers”** for more details.

In select devices, this feature is also implemented for the TMR5/TMR4 timer pair. Refer to the specific device data sheet for details.

17.7.3.3 SYNCHRONIZING A/D OPERATIONS TO INTERNAL OR EXTERNAL EVENTS

The modes where an external event trigger pulse ends sampling and starts conversion ($SSRC\langle 2:0 \rangle = 001, 010$ or 011) may be used in combination with auto-sampling ($ASAM = 1$) to cause the A/D to synchronize the sample conversion events to the trigger pulse source. For example, in Figure 17-9 where $SSRC\langle 2:0 \rangle = 010$ and $ASAM = 1$, the A/D will always end sampling and start conversions synchronously with the timer compare trigger event. The A/D will have a sample conversion rate that corresponds to the timer comparison event rate.

Figure 17-8: Manual Sample Start, Conversion Trigger-Based Conversion Start

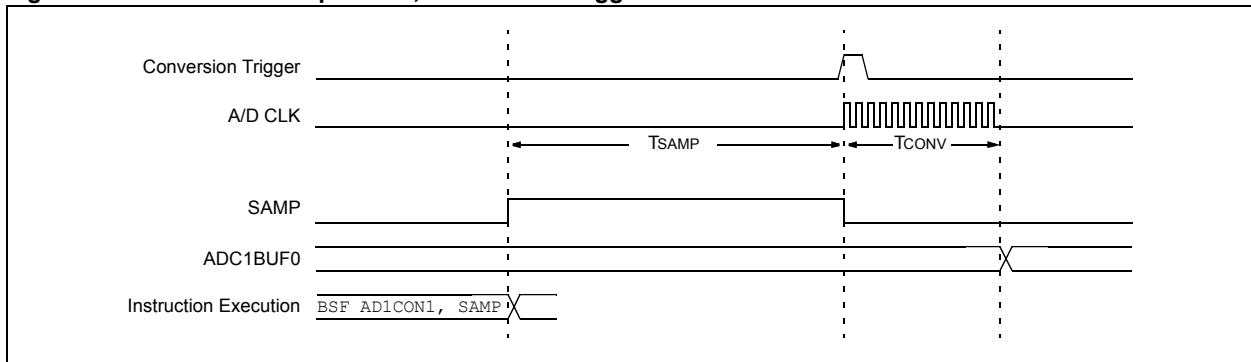
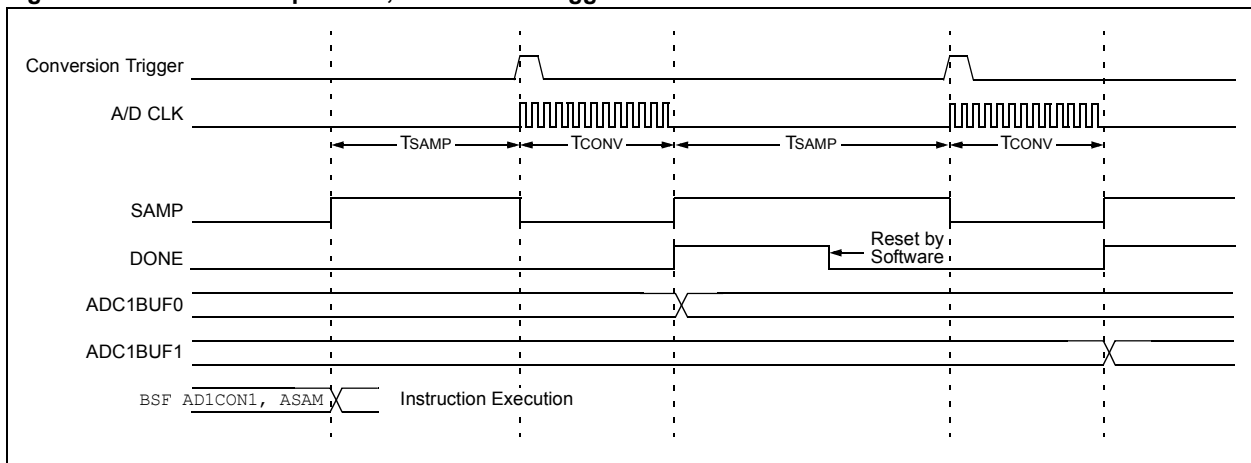


Figure 17-9: Auto-Sample Start, Conversion Trigger-Based Conversion Start



Example 17-5: Converting One Channel, Auto-Sample Start, Conversion Trigger-Based Conversion Start Code

```
int ADCValue;

AD1PCFG = 0xFFFF;           // AN2 analog, all other pins digital
AD1CON1 = 0x0040;           // SSRC bit = 010 implies GP TMR3
                             // compare ends sampling and starts converting.
AD1CHS = 0x0002;            // Connect AN2 as CH0 input...
                             // in this example AN2 is the input

AD1CSSL = 0;
AD1CON3 = 0x0000;           // Sample time is TMR3, Tad = Tcy
AD1CON2 = 0x0004;           // Set AD1IF after 2 conversions
TMR3 = 0x0000;              // set TMR3 to time out every 125 ms
PR3 = 0x3FFF;
T3CON = 0x8010;
AD1CON1bits.ADON = 1;        // turn ADC ON
AD1CON1bits.ASAM = 1;        // start auto sampling every 125 ms
while (1)                   // repeat continuously
{
    while (!IFS0bits.AD1IF){}; // conversion done?
    ADCValue = ADC1BUF0;       // yes then get first ADC value
    IFS0bits.AD1IF = 0;       // clear AD1IF
}
```

17.7.3.4 SAMPLE TIME CONSIDERATIONS FOR AUTOMATIC SAMPLING/CONVERSION SEQUENCES

Different sample/conversion sequences provide different available sampling times for the S/H channel to acquire the analog signal. The user must ensure the sampling time satisfies the sampling requirements, as outlined in **Section 17.10 “A/D Sampling Requirements”**.

Assuming that the module is set for automatic sampling, and an external trigger pulse is used as the conversion trigger, the sampling interval is a portion of the trigger pulse interval. The sampling time is the trigger pulse period, less the time required to complete the conversion.

Equation 17-3: Calculating Available Sampling Time for Sequential Sampling

$$T_{SMP} = \text{Trigger Pulse Interval (TSEQ)} - \text{Conversion Time (TCONV)} = T_{SEQ} - T_{CONV}$$

17.7.4 Monitoring Sample/Conversion Status

The DONE bit (AD1CON1<0>) indicates the conversion state of the A/D. Generally, when the SAMP bit clears, indicating the end of sampling, the DONE bit is automatically cleared to indicate the start of conversion. If SAMP is '0' while DONE is '1', the A/D is in an inactive state.

In some operational modes, the SAMP bit may also invoke and terminate sampling. In these modes, the DONE bit cannot be used to terminate conversions in progress.

17.7.5 Generating A/D Interrupts

The SMPI<3:0> bits (AD1CON2<5:2>) control the generation of the AD1IF interrupt flag. The A/D interrupt flag is set after the number of sample/conversion sequences is specified by the SMPI bits, after the start of sampling, and continues to recur after that number of samples. The value specified by the SMPI bits also corresponds to the number of data samples in the buffer, up to the maximum of 16. To enable the interrupt, it is necessary to set the A/D Interrupt Enable bit, AD1IE.

17.7.6 Aborting a Conversion

Clearing the ADON bit during a conversion will abort the current conversion. The A/D results buffer will not be updated with the partially completed A/D conversion sample; that is, the corresponding ADC1BUF buffer location will continue to contain the value of the last completed conversion (or the last value written to the buffer).

17.8 A/D RESULTS BUFFER

As conversions are completed, the module writes the results of the conversions into the A/D result buffer. This buffer is a RAM array of sixteen words, accessed through the SFR space.

User software may attempt to read each A/D conversion result as it is generated; however, this might consume too much CPU time. Generally, to minimize software overhead, the module will fill the buffer with results and then generate an interrupt when the buffer is filled.

17.8.1 Number of Conversions per Interrupt

The SMPI<3:0> bits select how many A/D conversions will take place before the CPU is interrupted. This can vary from one to 16 samples per interrupt. The A/D Converter module always starts writing its conversion results at the beginning of the buffer, after each interrupt. For example, if SMPI<3:0> = 0000, the conversion results will always be written to the ADC1BUF0. In this example, no other buffer locations would be used, since only one sequence per interrupt is specified.

17.8.2 Buffer Fill Mode

When the BUFM bit (AD1CON2<1>) is '1', the 16-word results buffer is split into two 8-word groups: a lower group (ADC1BUF0 through ADC1BUF7) and an upper group (ADC1BUF8 through ADC1BUFF). The 8-word buffers will alternately receive the conversion results after each interrupt event. The initial 8-word buffer used after BUFM is set is the lower group. When BUFM is '0', the entire 16-word buffer is used for all conversion sequences.

Note: When the BUFM bit (AD1CON2<1>) is set, the user should not program the SMPI bits to a value that specifies more than 8 conversions per interrupt.

The decision to use the split buffer feature will depend upon how much time is available to move the buffer contents, after the interrupt, as determined by the application. If the application can quickly unload a full buffer within the time it takes to sample and convert one channel, the BUFM bit can be '0', and up to 16 conversions may be done per interrupt. The application will have one sample/convert time before the first buffer location is overwritten.

If the processor cannot unload the buffer within the sample and conversion time, the BUFM bit should be '1'. For example, if SMPI<3:0> = 0111, then eight conversions will be loaded into the lower half of the buffer, following which, an interrupt may occur. The next eight conversions will be loaded into the upper half of the buffer. The processor will, therefore, have the entire time between interrupts to move the eight conversions out of the buffer.

17.8.3 Buffer Fill Status

When the conversion result buffer is split, using the BUFM control bit, the BUFS status bit (AD1CON2<7>) indicates which half of the buffer that the A/D Converter is currently writing. If BUFS = 0, the A/D Converter is filling the lower group, and the user software should read conversion values from the upper group. If BUFS = 1, the situation is reversed, and the user software should read conversion values from the lower group.

17.8.4 Buffer Data Formats

The results of each A/D conversion are 10 bits wide. To maintain data format compatibility, the result of each conversion is automatically converted to one of four selectable, 16-bit formats. The FORM<1:0> bits (AD1CON1<9:8>) select the format. Figure 17-10 shows the data output formats that can be selected.

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Figure 17-10: A/D Output Data Formats

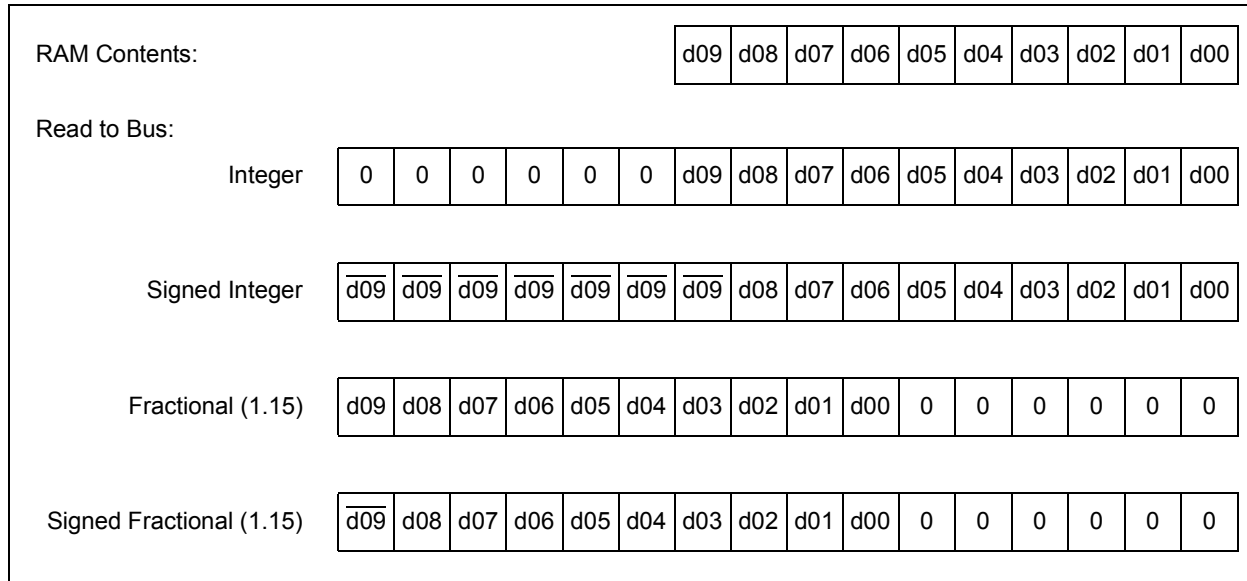


Table 17-2: Numerical Equivalents of Various Result Codes: Integer Formats

VIN/VREF	10-Bit Output Code	16-Bit Integer Format/ Equivalent Decimal Value			16-Bit Signed Integer Format/ Equivalent Decimal Value		
1023/1024	11 1111 1111	0000 0011 1111 1111	1023	0000 0001 1111 1111	511		
1022/1024	11 1111 1110	0000 0011 1111 1110	1022	0000 0001 1111 1110	510		
...							
513/1024	10 0000 0001	0000 0010 0000 0001	513	0000 0000 0000 0001	1		
512/1024	10 0000 0000	0000 0010 0000 0000	512	0000 0000 0000 0000	0		
511/1024	01 1111 1111	0000 0001 1111 1111	511	1111 1111 1111 1111	-1		
...							
1/1024	00 0000 0001	0000 0000 0000 0001	1	1111 1110 0000 0001	-511		
0/1024	00 0000 0000	0000 0000 0000 0000	0	1111 1110 0000 0000	-512		

Table 17-3: Numerical Equivalents of Various Result Codes: Fractional Formats

VIN/VREF	10-Bit Output Code	16-Bit Fractional Format/ Equivalent Decimal Value			16-Bit Signed Fractional Format/ Equivalent Decimal Value		
1023/1024	11 1111 1111	1111 1111 1100 0000	0.999	0111 1111 1100 0000	0.499		
1022/1024	11 1111 1110	1111 1111 1000 0000	0.998	0111 1111 1000 0000	0.498		
...							
513/1024	10 0000 0001	1000 0000 0100 0000	0.501	0000 0000 0100 0000	0.001		
512/1024	10 0000 0000	1000 0000 0000 0000	0.500	0000 0000 0000 0000	0.000		
511/1024	01 1111 1111	0111 1111 1100 0000	0.499	1111 1111 1100 0000	-0.001		
...							
1/1024	00 0000 0001	0000 0000 0100 0000	0.001	1000 0000 0100 0000	-0.499		
0/1024	00 0000 0000	0000 0000 0000 0000	0.000	1000 0000 0000 0000	-0.500		

17.9 CONVERSION SEQUENCE EXAMPLES

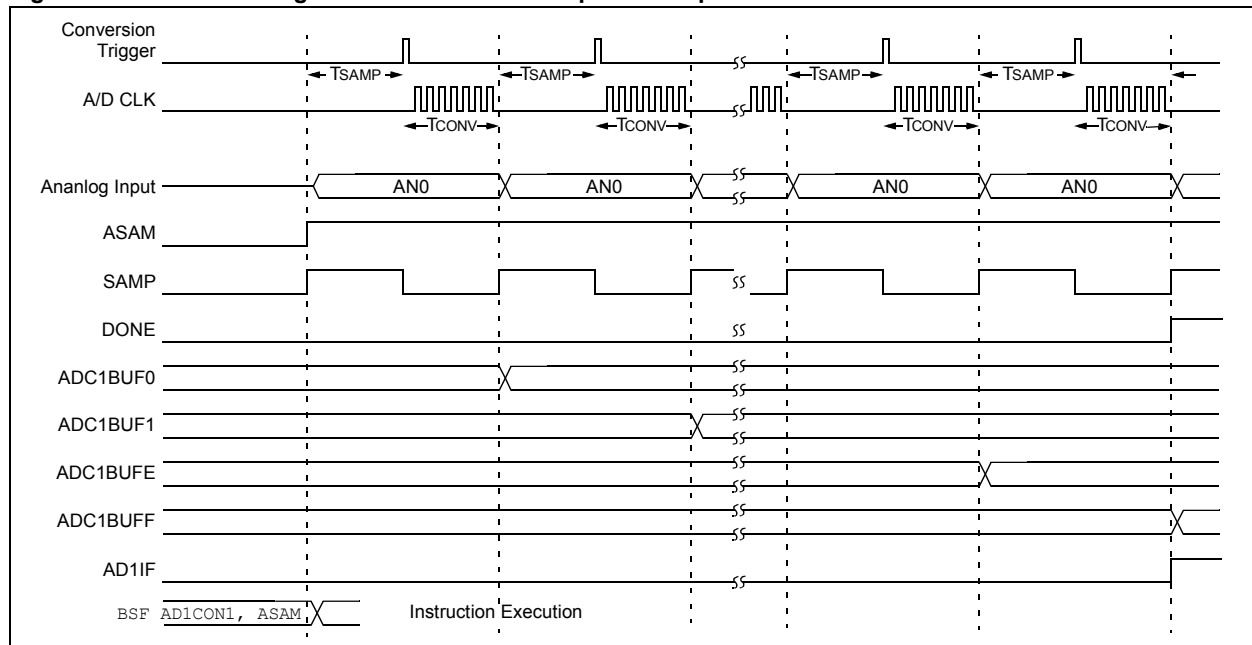
The following configuration examples show the A/D operation in different sampling and buffering configurations. In each example, setting the ASAM bit starts automatic sampling. A conversion trigger ends sampling and starts conversion.

17.9.1 Sampling and Converting a Single Channel Multiple Times

Figure 17-11 and Example 17-6 illustrate a basic configuration of the A/D. In this case, one A/D input, AN0, will be sampled and converted. The results are stored in the ADC1BUF buffer. This process repeats 16 times until the buffer is full and then the module generates an interrupt. The entire process will then repeat.

With ALTS clear, only the MUX A inputs are active. The CH0SA bits and CH0NA bit are specified (AN0-VR-) as the inputs to the sample/hold channel. All other input selection bits are unused.

Figure 17-11: Converting One Channel 16 Times per Interrupt



Example 17-6: Sampling and Converting a Single Channel Multiple Times

```
int ADCValue, count;
int *ADC16Ptr;
AD1PCFG = 0xFFFE;           // Only AN0 as analog input
AD1CON1 = 0x00E0;           // Internal counter triggers conversion
AD1CHS = 0x0000;           // Connect AN0 as positive input
AD1CSSL = 0;
AD1CON3 = 0x0F00;           // Sample time = 15Tad, Tad = Tcy
AD1CON2 = 0x003C;           // Set AD1IF after every 16 samples
AD1CON1bits.ADON = 1;       // turn ADC ON
while(1)                    // repeat continuously
{
    ADCValue = 0;            // clear value
    ADC16Ptr = &ADC1BUF0;   // initialize ADC1BUF pointer
    IFS0bits.AD1IF = 0;      // clear ADC interrupt flag
    AD1CON1bits.ASAM = 1;     // auto start sampling for 31Tad
                              // then go to conversion
    while (!IFS0bits.AD1IF){} // conversion done?
    AD1CON1bits.ASAM = 0;     // yes then stop sample/convert
    for (count = 0; count < 16; count++) // average the 16 ADC value
    {
        ADCValue = ADCValue + *ADC16Ptr++;
    }
    ADCValue = ADCValue >> 4;
}                             // repeat
```

Example 17-7: Converting a Single Channel 16 Times per Interrupt

A/D Configuration:

- Select AN0 for S/H+ Input (CH0SA<3:0> = 0000)
- Select VR- for S/H- Input (CH0NA = 0)
- Configure for No Input Scan (CSCNA = 0)
- Use Only MUX A for Sampling (ALTS = 0)
- Set AD1IF on Every 16th Sample (SMPI<3:0> = 1111)
- Configure Buffers for Single, 16-Word Results (BUFM = 0)

Operational Sequence:

1. Sample MUX A Input AN0; Convert and Write to Buffer 0h
2. Sample MUX A Input AN0; Convert and Write to Buffer 1h
3. Sample MUX A Input AN0; Convert and Write to Buffer 2h
4. Sample MUX A Input AN0; Convert and Write to Buffer 3h
5. Sample MUX A Input AN0; Convert and Write to Buffer 4h
6. Sample MUX A Input AN0; Convert and Write to Buffer 5h
7. Sample MUX A Input AN0; Convert and Write to Buffer 6h
8. Sample MUX A Input AN0; Convert and Write to Buffer 7h
9. Sample MUX A Input AN0; Convert and Write to Buffer 8h
10. Sample MUX A Input AN0; Convert and Write to Buffer 9h
11. Sample MUX A Input AN0; Convert and Write to Buffer Ah
12. Sample MUX A Input AN0; Convert and Write to Buffer Bh
13. Sample MUX A Input AN0; Convert and Write to Buffer Ch
14. Sample MUX A Input AN0; Convert and Write to Buffer Dh
15. Sample MUX A Input AN0; Convert and Write to Buffer Eh
16. Sample MUX A Input AN0; Convert and Write to Buffer Fh
17. Set AD1IF Flag (and generate interrupt, if enabled)
18. Repeat (1-16) after Return from Interrupt

Results Stored in Buffer (after 2 cycles):

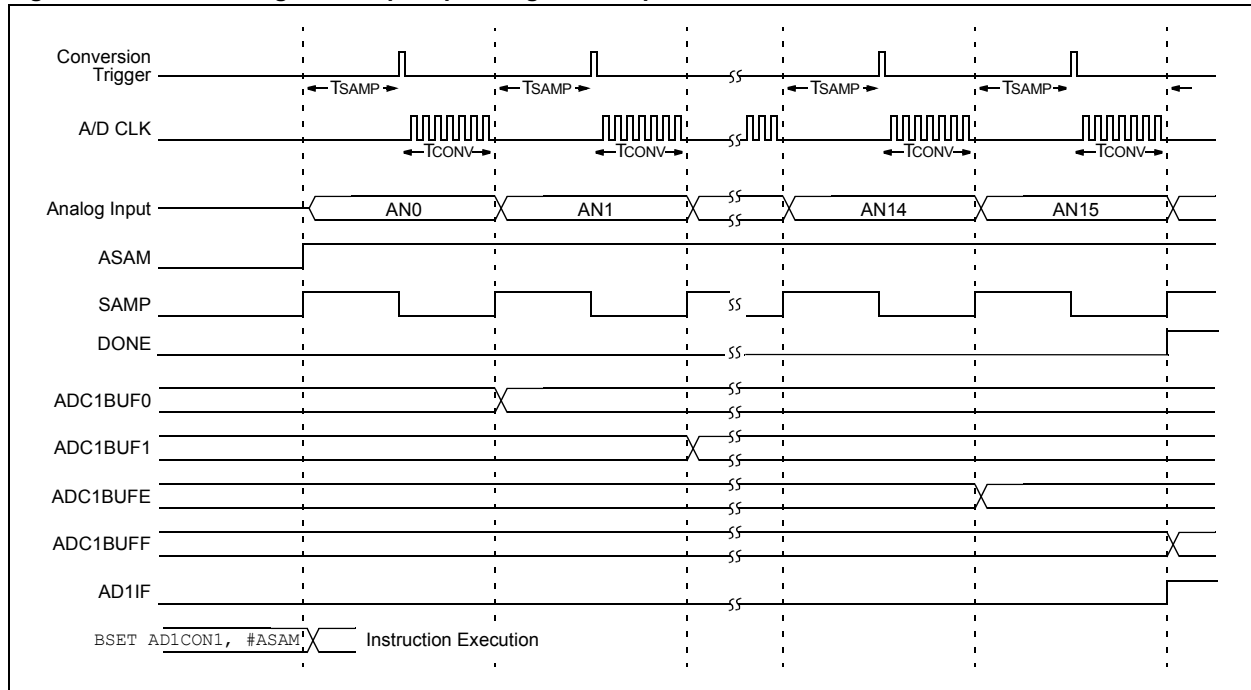
Buffer Address	Buffer Contents at 1st AD1IF Event	Buffer Contents at 2nd AD1IF Event
ADC1BUF0	AN0, Sample 1	AN0, Sample 17
ADC1BUF1	AN0, Sample 2	AN0, Sample 18
ADC1BUF2	AN0, Sample 3	AN0, Sample 19
ADC1BUF3	AN0, Sample 4	AN0, Sample 20
ADC1BUF4	AN0, Sample 5	AN0, Sample 21
ADC1BUF5	AN0, Sample 6	AN0, Sample 22
ADC1BUF6	AN0, Sample 7	AN0, Sample 23
ADC1BUF7	AN0, Sample 8	AN0, Sample 24
ADC1BUF8	AN0, Sample 9	AN0, Sample 25
ADC1BUF9	AN0, Sample 10	AN0, Sample 26
ADC1BUFA	AN0, Sample 11	AN0, Sample 27
ADC1BUFB	AN0, Sample 12	AN0, Sample 28
ADC1BUFC	AN0, Sample 13	AN0, Sample 29
ADC1BUFD	AN0, Sample 14	AN0, Sample 30
ADC1BUFE	AN0, Sample 15	AN0, Sample 31
ADC1BUFF	AN0, Sample 16	AN0, Sample 32

17.9.2 A/D Conversions While Scanning Through All Analog Inputs

Figure 17-12 and Example 17-9 illustrate a typical setup, where all available analog input channels are sampled and converted. The set CSCNA bit specifies scanning of the A/D inputs to the S/H positive input. Other conditions are similar to **Section 17.9.1 “Sampling and Converting a Single Channel Multiple Times”**.

Initially, the AN0 input is sampled and converted. The result is stored in the ADC1BUF0 buffer. Then, the AN1 input is sampled and converted. This process of scanning the inputs repeats 16 times until the buffer is full and then the module generates an interrupt. The entire process will then repeat.

Figure 17-12: Scanning All 16 Inputs per Single Interrupt



Example 17-8: Sampling and Converting All Channels

```
int ADCValue, count;
int *ADC16Ptr;

AD1PCFG = 0x0000;           // Configure all pins as analog inputs
AD1CSSL = 0xFFFF;          // Include all channels in scan
AD1CON1 = 0x00E0;           // Internal counter triggers conversion
AD1CON3 = 0x0F00;           // Sample time = 15Tad, Tad = Tcy
AD1CON2 = 0x043C;           // Set AD1IF after every 16 samples, enable scanning
AD1CON1bits.ADON = 1;       // turn ADC ON
while (1)                   // repeat continuously
{
    ADCValue = 0;            // clear value
    ADC16Ptr = &ADC1BUF0;   // initialize ADC1BUF pointer
    IFS0bits.AD1IF = 0;      // clear ADC interrupt flag
    AD1CON1bits.ASAM = 1;     // auto start sampling for 31Tad
                                // then go to conversion
    while (!IFS0bits.AD1IF){}; // conversion done?
    AD1CON1bits.ASAM = 0;     // yes then stop sample/convert
    for (count = 0; count < 16; count++) // average the 16 ADC value
    {
        ADCValue = ADCValue + *ADC16Ptr++;
    }
    ADCValue = ADCValue >> 4;
}                             // repeat
```

Example 17-9: Scanning and Converting All 16 Channels per Single Interrupt

A/D Configuration:

- Select Any Channel for S/H+ Input (CH0SA<3:0> = xxxx)
- Select VR- for S/H- Input (CH0NA = 0)
- Use Only MUX A for Sampling (ALTS = 0)
- Configure MUX A for Input Scan (CSCNA = 1)
- Include All Analog Channels in Scanning (AD1CSSL = 1111 1111 1111 1111)
- Set AD1IF on Every 16th Sample (SMPI<3:0> = 1111)
- Configure Buffers for Single, 16-Word Results (BUFM = 0)

Operational Sequence:

1. Sample MUX A Input AN0; Convert and Write to Buffer 0h
2. Sample MUX A Input AN1; Convert and Write to Buffer 1h
3. Sample MUX A Input AN2; Convert and Write to Buffer 2h
4. Sample MUX A Input AN3; Convert and Write to Buffer 3h
5. Sample MUX A Input AN4; Convert and Write to Buffer 4h
6. Sample MUX A Input AN5; Convert and Write to Buffer 5h
7. Sample MUX A Input AN6; Convert and Write to Buffer 6h
8. Sample MUX A Input AN7; Convert and Write to Buffer 7h
9. Sample MUX A Input AN8; Convert and Write to Buffer 8h
10. Sample MUX A Input AN9; Convert and Write to Buffer 9h
11. Sample MUX A Input AN10; Convert and Write to Buffer Ah
12. Sample MUX A Input AN11; Convert and Write to Buffer Bh
13. Sample MUX A Input AN12; Convert and Write to Buffer Ch
14. Sample MUX A Input AN13; Convert and Write to Buffer Dh
15. Sample MUX A Input AN14; Convert and Write to Buffer Eh
16. Sample MUX A Input AN15; Convert and Write to Buffer Fh
17. Set AD1IF Flag (and generate interrupt, if enabled)
18. Repeat (1-16) after Return from Interrupt

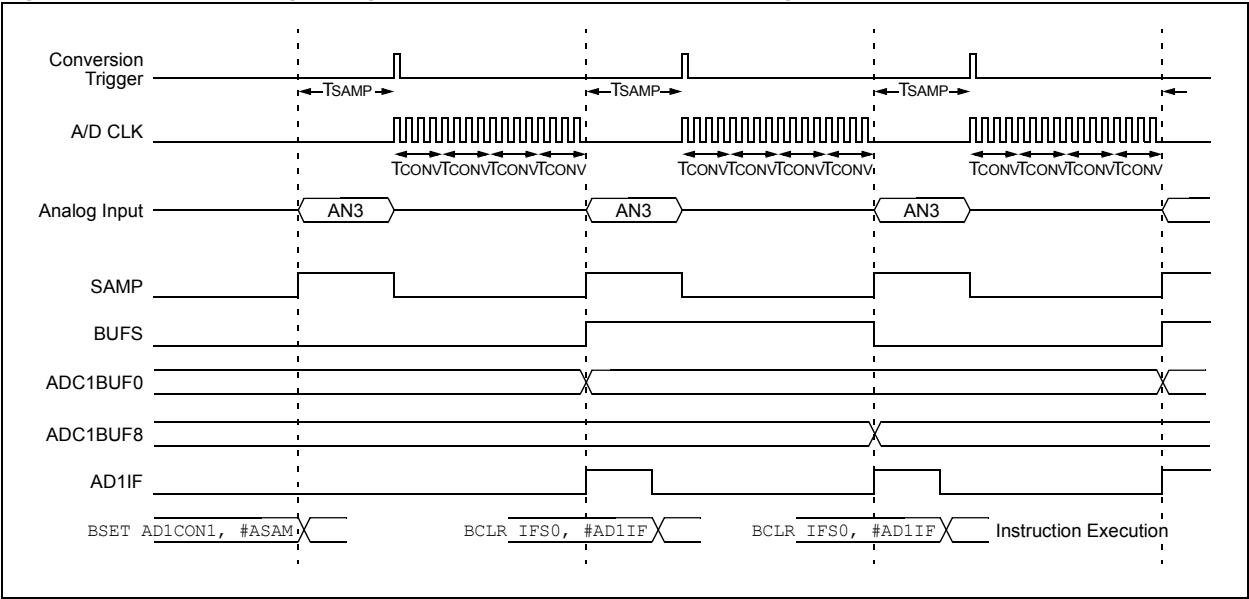
Results Stored in Buffer (after 2 cycles):

Buffer Address	Buffer Contents at 1st AD1IF Event	Buffer Contents at 2nd AD1IF Event
ADC1BUF0	Sample 1 (AN0, Sample 1)	Sample 17 (AN0, Sample 2)
ADC1BUF1	Sample 2 (AN1, Sample 1)	Sample 18 (AN1, Sample 2)
ADC1BUF2	Sample 3 (AN2, Sample 1)	Sample 19 (AN2, Sample 2)
ADC1BUF3	Sample 4 (AN3, Sample 1)	Sample 20 (AN3, Sample 2)
ADC1BUF4	Sample 5 (AN4, Sample 1)	Sample 21 (AN4, Sample 2)
ADC1BUF5	Sample 6 (AN5, Sample 1)	Sample 22 (AN5, Sample 2)
ADC1BUF6	Sample 7 (AN6, Sample 1)	Sample 23 (AN6, Sample 2)
ADC1BUF7	Sample 8 (AN7, Sample 1)	Sample 24 (AN7, Sample 2)
ADC1BUF8	Sample 9 (AN8, Sample 1)	Sample 25 (AN8, Sample 2)
ADC1BUF9	Sample 10 (AN9, Sample 1)	Sample 26 (AN9, Sample 2)
ADC1BUFA	Sample 11 (AN10, Sample 1)	Sample 27 (AN10, Sample 2)
ADC1BUFB	Sample 12 (AN11, Sample 1)	Sample 28 (AN11, Sample 2)
ADC1BUFC	Sample 13 (AN12, Sample 1)	Sample 29 (AN12, Sample 2)
ADC1BUFD	Sample 14 (AN13, Sample 1)	Sample 30 (AN13, Sample 2)
ADC1BUFE	Sample 15 (AN14, Sample 1)	Sample 31 (AN14, Sample 2)
ADC1BUFF	Sample 16 (AN15, Sample 1)	Sample 32 (AN15, Sample 2)

17.9.3 Using Dual, 8-Word Buffers

Figure 17-13 and Example 17-10 demonstrate using dual, 8-word buffers and alternating the buffer fill. Setting the BUFM bit enables dual, 8-word buffers. In this example, an interrupt is generated after each sample. The BUFM setting does not affect other operational parameters. First, the conversion sequence starts filling the buffer at ADC1BUF0. After the first interrupt occurs, the buffer begins to fill at ADC1BUF8. The BUFS status bit is toggled after each interrupt.

Figure 17-13: Converting a Single Channel, Once per Interrupt Using Dual, 8-Word Buffers



Example 17-10: Converting a Single Channel Once per Interrupt, Dual Buffer Mode

A/D Configuration:

- Select AN3 for S/H+ Input (CH0SA<3:0> = 0011)
- Select VR- for S/H- Input (CH0NA = 0)
- Configure for No Input Scan (CSCNA = 0)
- Use Only MUX A for Sampling (ALTS = 0)
- Set AD1IF on Every Sample (SMPI<3:0> = 0000)
- Configure Buffer as Dual, 8-Word Segments (BUFM = 1)

Operational Sequence:

1. Sample MUX A Input AN3; Convert and Write to Buffer 0h
2. Set AD1IF Flag (and generate interrupt, if enabled); Write Access Automatically Switches to Alternate Buffer
3. Sample MUX A Input AN3; Convert and Write to Buffer 8h
4. Set AD1IF Flag (and generate interrupt, if enabled); Write Access Automatically Switches to Alternate Buffer
5. Repeat (1-4)

Results Stored in Buffer (after 2 cycles):

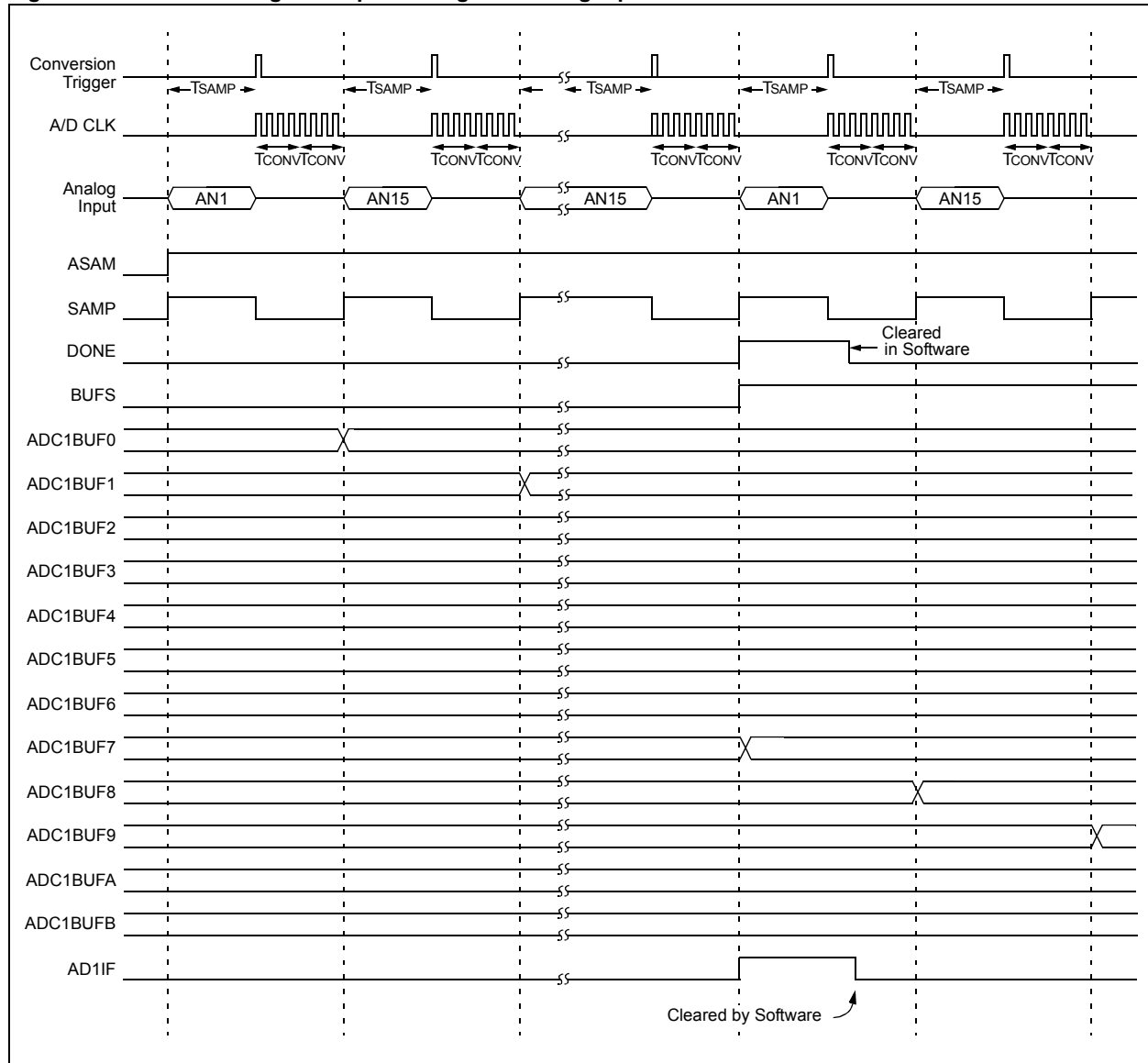
Buffer Address	Buffer Contents at 1st AD1IF Event	Buffer Contents at 2nd AD1IF Event
ADC1BUF0	Sample 1 (AN3, Sample 1)	(undefined)
ADC1BUF1	(undefined)	(undefined)
ADC1BUF2	(undefined)	(undefined)
ADC1BUF3	(undefined)	(undefined)
ADC1BUF4	(undefined)	(undefined)
ADC1BUF5	(undefined)	(undefined)
ADC1BUF6	(undefined)	(undefined)
ADC1BUF7	(undefined)	(undefined)
ADC1BUF8	(undefined)	Sample 2 (AN3, Sample 2)
ADC1BUF9	(undefined)	(undefined)
ADC1BUFA	(undefined)	(undefined)
ADC1BUFB	(undefined)	(undefined)
ADC1BUFC	(undefined)	(undefined)
ADC1BUFD	(undefined)	(undefined)
ADC1BUFE	(undefined)	(undefined)
ADC1BUFF	(undefined)	(undefined)

17.9.4 Using Alternating MUX A and MUX B Input Selections

Figure 17-14 and Example 17-11 demonstrate alternate sampling of the inputs assigned to MUX A and MUX B. Setting the ALTS bit enables alternating input selections. The first sample uses the MUX A inputs specified by the CH0SA and CH0NA bits. The next sample uses the MUX B inputs specified by the CH0SB and CH0NB bits.

This example also demonstrates use of the dual, 8-word buffers. An interrupt occurs after every 8th sample, resulting in filling 8 words into the buffer on each interrupt.

Figure 17-14: Converting Two Inputs Using Alternating Input Selections



Example 17-11: Converting Two Inputs by Alternating MUX A and MUX B

A/D Configuration:

- Select AN1 for MUX A S/H+ Input (CH0SA<3:0> = 0001)
- Select VR- for MUX A S/H- Input (CH0NA = 0)
- Configure for No Input Scan (CSCNA = 0)
- Select AN15 for MUX B S/H+ Input (CH0SB<3:0> = 1111)
- Select VR- for MUX B S/H- Input (CH0NB = 0)
- Alternate MUX A and MUX B for Sampling (ALTS = 1)
- Set AD1IF on Every 8th Sample (SMPI<3:0> = 0111)
- Configure Buffer as Two, 8-Word Segments (BUFM = 1)

Operational Sequence:

1. Sample MUX A Input AN1; Convert and Write to Buffer 0h
2. Sample MUX B Input AN15; Convert and Write to Buffer 1h
3. Sample MUX A Input AN1; Convert and Write to Buffer 2h
4. Sample MUX B Input AN15; Convert and Write to Buffer 3h
5. Sample MUX A Input AN1; Convert and Write to Buffer 4h
6. Sample MUX B Input AN15; Convert and Write to Buffer 5h
7. Sample MUX A Input AN1; Convert and Write to Buffer 6h
8. Sample MUX B Input AN15; Convert and Write to Buffer 7h
9. Set AD1IF Flag (and generate interrupt, if enabled); Write Access Automatically Switches to Alternate Buffer
10. Repeat (1-9); Resume Writing to Buffer with Buffer 8h (first address of alternate buffer)

Results Stored in Buffer (after 2 cycles):

Buffer Address	Buffer Contents at 1st AD1IF Event	Buffer Contents at 2nd AD1IF Event
ADC1BUF0	Sample 1 (AN1, Sample 1)	(undefined)
ADC1BUF1	Sample 2 (AN15, Sample 1)	(undefined)
ADC1BUF2	Sample 3 (AN1, Sample 2)	(undefined)
ADC1BUF3	Sample 4 (AN15, Sample 2)	(undefined)
ADC1BUF4	Sample 5 (AN1, Sample 3)	(undefined)
ADC1BUF5	Sample 6 (AN15, Sample 3)	(undefined)
ADC1BUF6	Sample 7 (AN1, Sample 4)	(undefined)
ADC1BUF7	Sample 8 (AN15, Sample 4)	(undefined)
ADC1BUF8	(undefined)	Sample 9 (AN1, Sample 5)
ADC1BUF9	(undefined)	Sample 10 (AN15, Sample 5)
ADC1BUFA	(undefined)	Sample 11 (AN1, Sample 6)
ADC1BUFB	(undefined)	Sample 12 (AN15, Sample 6)
ADC1BUFC	(undefined)	Sample 13 (AN1, Sample 7)
ADC1BUFD	(undefined)	Sample 14 (AN15, Sample 7)
ADC1BUFE	(undefined)	Sample 15 (AN1, Sample 8)
ADC1BUFF	(undefined)	Sample 16 (AN15, Sample 8)

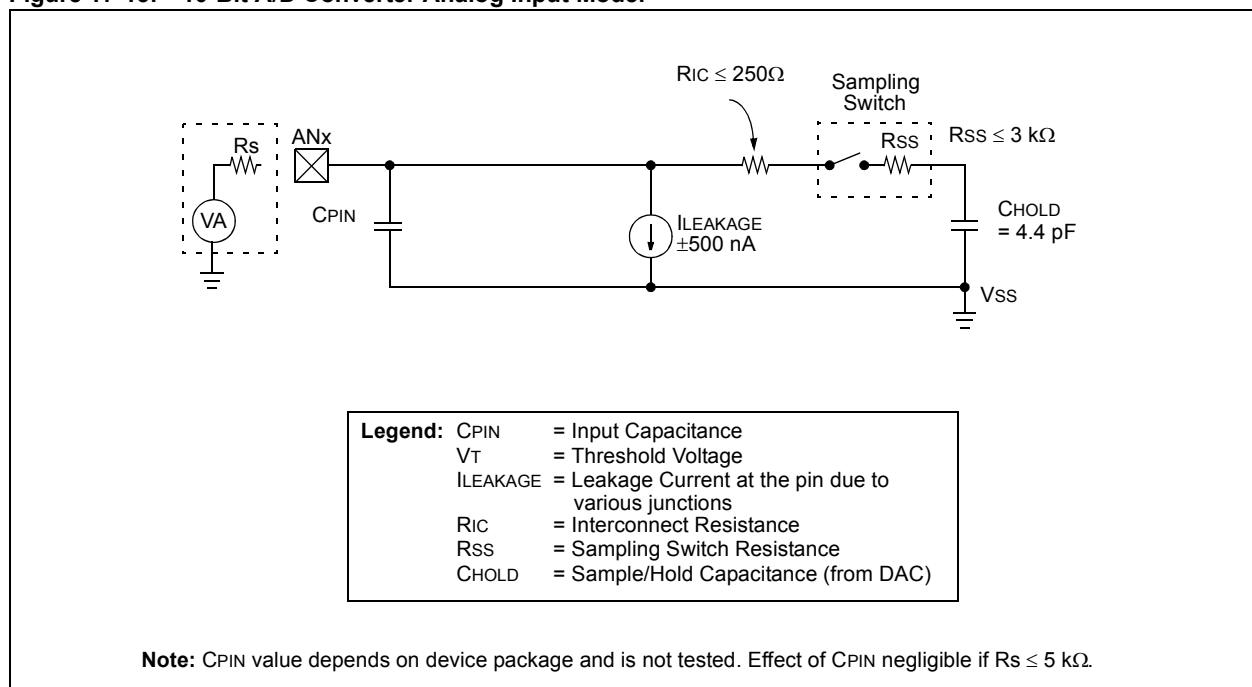
17.10 A/D SAMPLING REQUIREMENTS

The analog input model of the 10-bit A/D Converter is shown in Figure 18-11. The total sampling time for the A/D is a function of the holding capacitor charge time.

For the A/D Converter to meet its specified accuracy, the charge holding capacitor (CHOLD) must be allowed to fully charge to the voltage level on the analog input pin. The source impedance (Rs), the interconnect impedance (Ric) and the internal sampling switch (Rss) impedance combine to directly affect the time required to charge CHOLD. The combined impedance of the analog sources must, therefore, be small enough to fully charge the holding capacitor within the chosen sample time. To minimize the effects of pin leakage currents on the accuracy of the A/D Converter, the maximum recommended source impedance, Rs, is 2.5 kΩ. After the analog input channel is selected (changed), this sampling function must be completed prior to starting the conversion. The internal holding capacitor will be in a discharged state prior to each sample operation.

At least 1 TAD time period should be allowed between conversions for the sample time. For more details, see **Section 17.16 “Electrical Specifications”**.

Figure 17-15: 10-Bit A/D Converter Analog Input Model

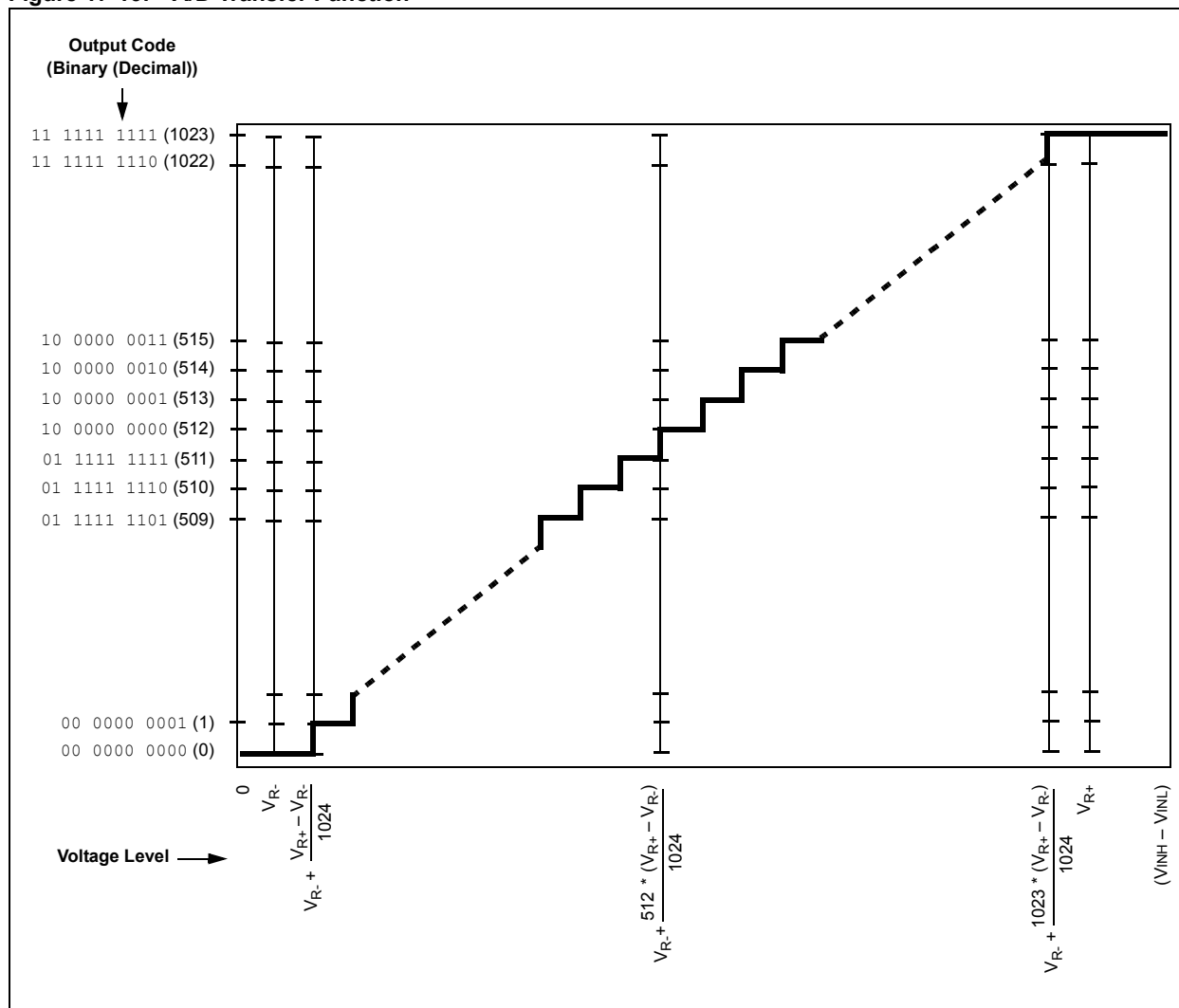


17.11 TRANSFER FUNCTION

The transfer function of the A/D Converter is shown in Figure 17-16. The difference of the input voltages, $(V_{INH} - V_{INL})$, is compared to the reference, $((V_{R+}) - (V_{R-}))$.

- The first code transition occurs when the input voltage is $((V_{R+}) - (V_{R-}))/1024$ or 1.0 LSB.
- The 00 0000 0001 code is centered at $V_{R-} + (1.5 * ((V_{R+}) - (V_{R-}))/1024)$.
- The 10 0000 0000 code is centered at $V_{REFL} + (512.5 * ((V_{R+}) - (V_{R-}))/1024)$.
- An input voltage less than $V_{R-} + (((V_{R-}) - (V_{R-}))/1024)$ converts as 00 0000 0000.
- An input voltage greater than $(V_{R-}) + (1023 * ((V_{R+}) - (V_{R-}))/1024)$ converts as 11 1111 1111.

Figure 17-16: A/D Transfer Function



17.12 A/D ACCURACY/ERROR

Refer to **Section 17.18 “Related Application Notes”** for a list of documents that discuss A/D accuracy.

17.13 OPERATION DURING SLEEP AND IDLE MODES

Sleep and Idle modes are useful for minimizing conversion noise because the digital activity of the CPU, buses and other peripherals is minimized.

17.13.1 CPU Sleep Mode Without RC A/D Clock

When the device enters Sleep mode, all clock sources to the module are shut down and stay at logic ‘0’.

If Sleep occurs in the middle of a conversion, the conversion is aborted unless the A/D is clocked from its internal RC clock generator. The converter will not resume a partially completed conversion on exiting from Sleep mode.

Register contents are not affected by the device entering or leaving Sleep mode.

17.13.2 CPU Sleep Mode With RC A/D Clock

The A/D module can operate during Sleep mode if the A/D clock source is set to the internal A/D RC oscillator ($ADRC = 1$). This eliminates digital switching noise from the conversion. When the conversion is completed, the DONE bit will be set and the result loaded into the A/D Result Buffer, ADC1BUF.

If the A/D interrupt is enabled ($AD1IE = 1$), the device will wake-up from Sleep when the A/D interrupt occurs. Program execution will resume at the A/D Interrupt Service Routine if the A/D interrupt is greater than the current CPU priority. Otherwise, execution will continue from the instruction after the `PWRSV` instruction that placed the device in Sleep mode.

If the A/D interrupt is not enabled, the A/D module will then be turned off, although the ADON bit will remain set.

To minimize the effects of digital noise on the A/D module operation, the user should select a conversion trigger source that ensures the A/D conversion will take place in Sleep mode. The automatic conversion trigger option can be used for sampling and conversion in Sleep ($SSRC<2:0> = 111$). To use the automatic conversion option, the ADON bit should be set in the instruction prior to the `PWRSV` instruction.

Note: For the A/D module to operate in Sleep, the A/D clock source must be set to RC ($ADRC = 1$).

17.13.3 A/D Operation During CPU Idle Mode

The ADSIDL bit ($AD1CON1<13>$) determines whether the module stops or continues operation on Idle. If $ADSIDL = 0$, the module will continue normal operation when the device enters Idle mode. If the A/D interrupt is enabled ($AD1IE = 1$), the device will wake-up from Idle mode when the A/D interrupt occurs. Program execution will resume at the A/D Interrupt Service Routine if the A/D interrupt is greater than the current CPU priority. Otherwise, execution will continue from the instruction after the `PWRSV` instruction that placed the device in Idle mode.

If $ADSIDL = 1$, the module will stop in Idle. If the device enters Idle mode in the middle of a conversion, the conversion is aborted. The converter will not resume a partially completed conversion on exiting from Idle mode.

17.13.4 Peripheral Module Disable (PMD) Register

The Peripheral Module Disable (PMD) registers provide a method to disable the A/D module by stopping all clock sources supplied to that module. When a peripheral is disabled via the appropriate PMD control bit, the peripheral is in a minimum power consumption state. The control and status registers associated with the peripheral will also be disabled, so writes to those registers will have no effect and read values will be invalid. The ADC module is enabled only when the ADC1MD bit in the the PMDx register is cleared.

<p>Note: Disabling the A/D module through the PMD register also disables the AD1PCFG registers, which in turn, affects the state of any port pins with analog inputs. Users should consider the effect on I/O ports and other digital peripherals on those ports when ADC1MD is used for power conservation.</p>

17.14 EFFECTS OF A RESET

A device Reset forces all registers to their Reset state. This forces the A/D module to be turned off and any conversion in progress to be aborted. All pins that are multiplexed with analog inputs will be configured as analog inputs. The corresponding TRIS bits will be set.

The values in the ADC1BUF registers are not initialized during a Power-on Reset; they will contain unknown data.

17.15 REGISTER MAPS

A summary of the registers associated with the PIC24F 10-Bit A/D Converter is provided in Table 17-4.

Table 17-4: ADC Register Map

File Name	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ADC1BUF0	ADC Data Buffer 0																xxxx
ADC1BUF1	ADC Data Buffer 1																xxxx
ADC1BUF2	ADC Data Buffer 2																xxxx
ADC1BUF3	ADC Data Buffer 3																xxxx
ADC1BUF4	ADC Data Buffer 4																xxxx
ADC1BUF5	ADC Data Buffer 5																xxxx
ADC1BUF6	ADC Data Buffer 6																xxxx
ADC1BUF7	ADC Data Buffer 7																xxxx
ADC1BUF8	ADC Data Buffer 8																xxxx
ADC1BUF9	ADC Data Buffer 9																xxxx
ADC1BUFA	ADC Data Buffer 10																xxxx
ADC1BUFB	ADC Data Buffer 11																xxxx
ADC1BUFC	ADC Data Buffer 12																xxxx
ADC1BUFD	ADC Data Buffer 13																xxxx
ADC1BUFE	ADC Data Buffer 14																xxxx
ADC1BUFF	ADC Data Buffer 15																xxxx
AD1CON1	ADON	—	ADSIDL	—	—	—	FORM1	FORM0	SSRC2	SSRC1	SSRC0	—	—	ASAM	SAMP	DONE	0000
AD1CON2	VCFG2	VCFG1	VCFG0	r	—	CSCNA	—	—	BUFS	—	SMP13	SMP12	SMP11	SMP10	BUFM	ALTS	0000
AD1CON3	ADRC	—	—	SAMC4	SAMC3	SAMC2	SAMC1	SAMC0	ADCS7	ADCS6	ADCS5	ADCS4	ADCS3	ADCS2	ADCS1	ADCS0	0000
AD1CHS	CH0NB	—	—	CH0SB4 ⁽²⁾	CH0SB3	CH0SB2	CH0SB1	CH0SB0	CH0NA	—	—	CH0SA4 ⁽²⁾	CH0SA3	CH0SA2	CH0SA1	CH0SA0	0000
AD1PCFGL ⁽¹⁾	PCFG15	PCFG14	PCFG13	PCFG12	PCFG11	PCFG10	PCFG9	PCFG8	PCFG7	PCFG6	PCFG5	PCFG4	PCFG3	PCFG2	PCFG1	PCFG0	0000
AD1PCFGH ⁽²⁾	—	—	—	—	—	—	—	—	—	—	—	—	—	—	PCFG17	PCFG16	0000
AD1CSSL	CSSL15	CSSL14	CSSL13	CSSL12	CSSL11	CSSL10	CSSL9	CSSL8	CSSL7	CSSL6	CSSL5	CSSL4	CSSL3	CSSL2	CSSL1	CSSL0	0000
AD1CSSH ⁽²⁾	—	—	—	—	—	—	—	—	—	—	—	—	—	—	CSSL17	CSSL16	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: This register is named AD1PCFG in devices without the AD1PCFGH register.

Note 2: These registers and/or bits are implemented in select devices only.

17.16 ELECTRICAL SPECIFICATIONS

Figure 17-17: A/D Conversion Timing

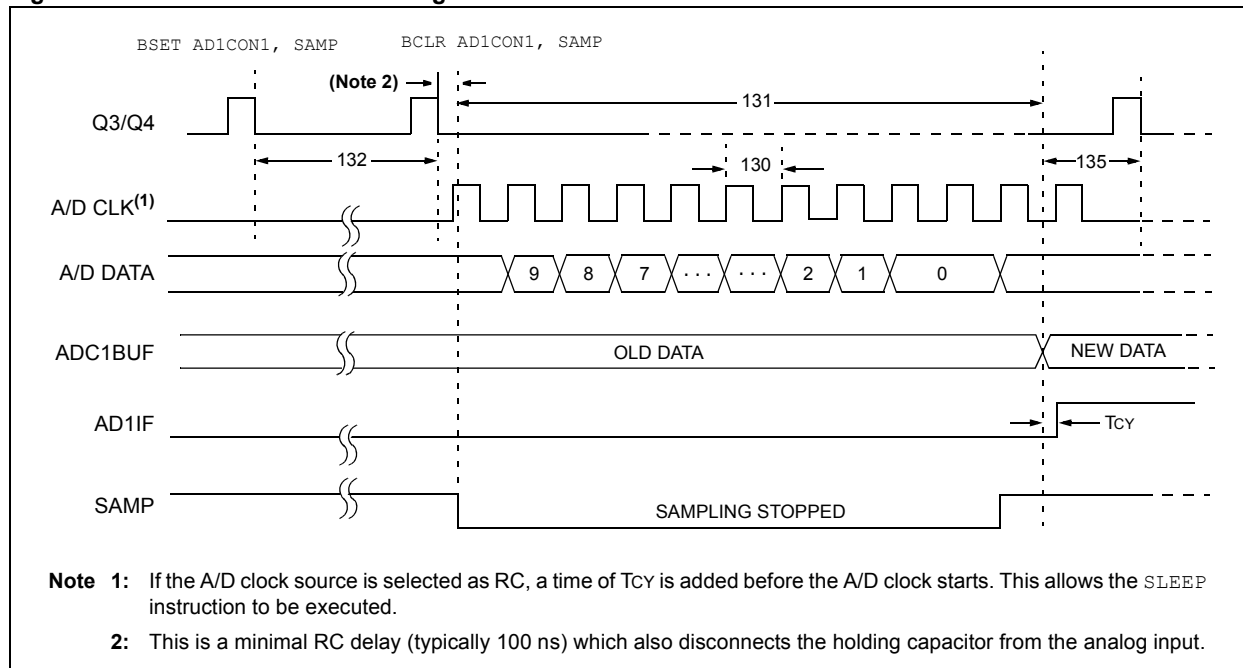


Table 17-5: A/D Conversion Requirements

Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
AD61	t_{PSS}	Sample Start Delay from Setting SAMP	2	—	3	T_{AD}	
AD130	T_{AD}	A/D Clock Period	75	—	—	ns	TOSC-based
			—	250	—	ns	A/D RC mode
AD131	T_{CNV}	Conversion Time (not including acquisition time)	11	—	12	T_{AD}	(Note 1)
AD132	T_{ACQ}	Acquisition Time	—	—	750	ns	(Note 2)
AD135	T_{SWC}	Switching Time from Convert to Sample	—	—	(Note 3)		
AD137	T_{DIS}	Discharge Time	0.5	—	—	T_{AD}	
		A/D Stabilization Time (from setting ADON to setting SAMP)	—	300	—	ns	

Note 1: The ADC1BUF register may be read on the following T_{cy} cycle.

Note 2: The time for the holding capacitor to acquire the "New" input voltage when the voltage changes full scale after the conversion (AV_{DD} to AV_{SS} or AV_{SS} to AV_{DD}).

Note 3: On the following cycle of the device clock.

17.17 DESIGN TIPS

Question 1: *How can I optimize the system performance of the A/D Converter?*

Answer: There are three main things to consider in optimizing A/D performance:

1. Make sure you are meeting all of the timing specifications. If you are turning the module off and on, there is a minimum delay you must wait before taking a sample. If you are changing input channels, there is a minimum delay you must wait for this as well, and finally, there is TAD, which is the time selected for each bit conversion. This is selected in AD1CON3 and should be within a certain range, as specified in **Section 17.16 “Electrical Specifications”**. If TAD is too short, the result may not be fully converted before the conversion is terminated, and if TAD is made too long, the voltage on the sampling capacitor can decay before the conversion is complete. These timing specifications are provided in the **“Electrical Characteristics”** section of the device data sheets.
2. Often, the source impedance of the analog signal is high (greater than 2.5 k Ω), so the current drawn from the source by leakage, and to charge the sample capacitor, can affect accuracy. If the input signal does not change too quickly, try putting a 0.1 μ F capacitor on the analog input. This capacitor will charge to the analog voltage being sampled and supply the instantaneous current needed to charge the 4.4 pF internal holding capacitor.
3. Put the device into Sleep mode before the start of the A/D conversion. The RC clock source selection is required for conversions in Sleep mode. This technique increases accuracy, because digital noise from the CPU and other peripherals is minimized.

Question 2: *Do you know of a good reference on A/D Converters?*

Answer: A good reference for understanding A/D conversions is the *“Analog-Digital Conversion Handbook”* third edition, published by Prentice Hall (ISBN 0-13-03-2848-0).

Question 3: *My combination of channels/samples and samples/interrupt is greater than the size of the buffer. What will happen to the buffer?*

Answer: This configuration is not recommended. The buffer will contain unknown results.

17.18 RELATED APPLICATION NOTES

This section lists application notes that are related to this section of the manual. These application notes may not be written specifically for the PIC24F device family, but the concepts are pertinent and could be used with modification and possible limitations. The current application notes related to the 10-Bit A/D Converter module are:

Title	Application Note #
Using the Analog-to-Digital (A/D) Converter	AN546
Four-Channel Digital Voltmeter with Display and Keyboard	AN557
Understanding A/D Converter Performance Specifications	AN693

Note: Please visit the Microchip web site (www.microchip.com) for additional application notes and code examples for the PIC24F family of devices.

17.19 REVISION HISTORY

Revision A (April 2006)

This is the initial released revision of this document.

Revision B (September 2009)

Updated to include PIC24F devices with internal input channels (band gap, voltage reference and external modules). Updated Figure 17-1 to include new internal channels. Added the AD1CSSH, AD1PCFGH and AD1PCFGL registers; updated bit descriptions in the ADICON1, AD1CON3 and AD1CHS registers; revised the text in **Section 17.3 “Registers”** and **Section 17.4 “A/D Module Configuration”** to describe the new registers and bit selection options; and updated Table 17-4 to show the location of the new registers in the memory map.

Revised **Section 17.2 “A/D Terminology and Conversion Sequence”** to provide a clearer explanation of module operation, primarily by adding **Section 17.2.1 “Operation as a State Machine”**.

Added text and an additional table (Table 17-1) to **Section 17.4 “A/D Module Configuration”** to better identify the control functions of the registers.

Updated text throughout the chapter to remove the deprecated terms “Channel 0” and “CH0”. In most places, the preferred term, “S/H amplifier” or “S/H”, is substituted where appropriate.

Other minor typographic changes and corrections throughout the text.

NOTES: