MIC24051

12V, 6A High-Efficiency Buck Regulator with Hyper Speed Control®

Features

- Hyper Speed Control® Architecture Enables:
  - High Delta V Operation (V_IN = 19V and V_OUT = 0.8V)
  - Small Output Capacitance
- 4.5V to 19V Voltage Input
- 6A Output Current Capability, up to 95% Efficiency
- Adjustable Output from 0.8V to 5.5V
- ±1% Feedback Accuracy
- Any Capacitor Stable - Zero-to-High ESR
- 600 kHz Switching Frequency
- No External Compensation
- Power Good (PG) Output
- Foldback Current-Limit and “Hiccup Mode” Short-Circuit Protection
- Supports Safe Start-Up into a Pre-Biased Load
- −40°C to +125°C Junction Temperature Range
- Available in a 28-pin 5 mm x 6 mm QFN Package

Applications

- Servers and Workstations
- Routers, Switches, and Telecom Equipment
- Base Stations

General Description

The MIC24051 is a constant-frequency, synchronous buck regulator featuring a unique adaptive on-time control architecture. The MIC24051 operates over an input supply range of 4.5V to 19V and provides a regulated output of up to 6A of output current. The output voltage is adjustable down to 0.8V with a guaranteed accuracy of ±1%, and the device operates at a switching frequency of 600 kHz.

Microchip’s Hyper Speed Control® architecture allows for ultra-fast transient response while reducing the output capacitance and also makes (High V_IN)/(Low V_OUT) operation possible. This adaptive t_ON ripple control architecture combines the advantages of fixed-frequency operation and fast transient response in a single device.

The MIC24051 offers a full suite of protection features to ensure protection of the IC during fault conditions. These include undervoltage lockout to ensure proper operation under power-sag conditions, internal soft-start to reduce inrush current, foldback current limit, “hiccup mode” short-circuit protection and thermal shutdown. An open-drain Power Good (PG) pin is provided.

The 6A HyperLight Load® part, MIC24052, is also available on Microchip’s web site.

Typical Application Schematic
MIC24051

Package Type

MIC24051
28-Pin QFN (JL)
(Top View)

Block Diagram
1.0  ELECTRICAL CHARACTERISTICS

Absolute Maximum Ratings †

- PVIN to PGND ............................................................................................................................................ –0.3V to +29V
- VIN to PGND ............................................................................................................................................... –0.3V to PVIN
- PVDD, VDD to PGND .................................................................................................................................... –0.3V to +6V
- VSW, VCS to PGND ....................................................................................................................... –0.3V to (PVIN + 0.3V)
- VBST to VSW ................................................................................................................................................. –0.3V to +6V
- VBST to PGND ............................................................................................................................................ –0.3V to +35V
- VBST to VPG .............................................................................................................................................. –0.3V to (VDD + 0.3V)
- VEN to PGND ...................................................................................................................................–0.3V to (VIN + 0.3V)
- PGND to SGND ........................................................................................................................................ –0.3V to +0.3V
- ESD Rating (Note 1) ................................................................................................................................. ESD Sensitive

Operating Ratings ‡

- Supply Voltage (PVIN, VIN) ......................................................................................................................... +4.5V to +19V
- PVDD, VDD Supply Voltage (PVDD, VDD) ................................................................................................... +4.5V to +5.5V
- Enable Input (VEN) ..............................................................................................................................................0V to VIN

† Notice: Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational sections of this specification is not intended. Exposure to maximum rating conditions for extended periods may affect device reliability.

‡ Notice: The device is not guaranteed to function outside its operating ratings.

Note 1: Devices are ESD sensitive. Handling precautions recommended. Human body model, 1.5 kΩ in series with 100 pF.
**TABLE 1-1: ELECTRICAL CHARACTERISTICS**

Electrical Characteristics: $PV_{IN} = V_{IN} = V_{EN} = 12V$, $V_{BST} - V_{SW} = 5V$; $T_A = 25°C$, unless noted. **Bold** values indicate $-40°C \leq T_J \leq +125°C$. (Note 1).

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Sym.</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Units</th>
<th>Conditions</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Power Supply Input</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input Voltage Range ($V_{IN}, PV_{IN}$)</td>
<td></td>
<td>4.5</td>
<td></td>
<td>19</td>
<td>V</td>
<td>$V_{IN} = 7V$ to $19V$, $I_{DD} = 40 mA$</td>
</tr>
<tr>
<td>Quiescent Supply Current</td>
<td></td>
<td></td>
<td></td>
<td>730</td>
<td>1500</td>
<td>$\mu A$</td>
</tr>
<tr>
<td>Shutdown Supply Current</td>
<td></td>
<td></td>
<td></td>
<td>5</td>
<td>10</td>
<td>$\mu A$</td>
</tr>
<tr>
<td><strong>$V_{DD}$ Supply Voltage</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$V_{DD}$ Output Voltage</td>
<td></td>
<td>4.8</td>
<td>5</td>
<td>5.4</td>
<td>V</td>
<td>$V_{IN} = 7V$ to $19V$, $I_{DD} = 40 mA$</td>
</tr>
<tr>
<td>$V_{DD}$ UVLO Threshold</td>
<td></td>
<td>3.7</td>
<td>4.2</td>
<td>4.5</td>
<td>V</td>
<td>$V_{DD}$ Rising</td>
</tr>
<tr>
<td>$V_{DD}$ UVLO Hysteresis</td>
<td></td>
<td></td>
<td>400</td>
<td></td>
<td>mV</td>
<td></td>
</tr>
<tr>
<td>Dropout Voltage ($V_{IN} - V_{DD}$)</td>
<td></td>
<td></td>
<td></td>
<td>380</td>
<td>600</td>
<td>mV</td>
</tr>
<tr>
<td><strong>DC/DC Controller</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output-Voltage Adjust Range ($V_{OUT}$)</td>
<td></td>
<td>0.8</td>
<td></td>
<td>5.5</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td><strong>Reference</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Feedback Reference Voltage</td>
<td></td>
<td>0.792</td>
<td>0.8</td>
<td>0.808</td>
<td>V</td>
<td>0°C $\leq T_J \leq +85°C$ (±1.0%)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0.788</td>
<td>0.8</td>
<td>0.812</td>
<td>V</td>
<td>$-40°C \leq T_J \leq +125°C$ (±1.5%)</td>
</tr>
<tr>
<td>Load Regulation</td>
<td></td>
<td></td>
<td></td>
<td>0.25</td>
<td></td>
<td>%</td>
</tr>
<tr>
<td>Line Regulation</td>
<td></td>
<td></td>
<td></td>
<td>0.25</td>
<td></td>
<td>%</td>
</tr>
<tr>
<td>FB Bias Current</td>
<td></td>
<td></td>
<td></td>
<td>50</td>
<td>500</td>
<td>nA</td>
</tr>
<tr>
<td><strong>Enable Control</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>EN Logic Level High</td>
<td></td>
<td>1.8</td>
<td></td>
<td></td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>EN Logic Level Low</td>
<td></td>
<td></td>
<td></td>
<td>0.6</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>EN Bias Current</td>
<td></td>
<td></td>
<td></td>
<td>6</td>
<td>30</td>
<td>$\mu A$</td>
</tr>
<tr>
<td><strong>Oscillator</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Switching Frequency (Note 2)</td>
<td></td>
<td>450</td>
<td>600</td>
<td>750</td>
<td>kHz</td>
<td>$V_{OUT} = 2.5V$</td>
</tr>
<tr>
<td>Maximum Duty Cycle (Note 3)</td>
<td></td>
<td></td>
<td></td>
<td>82</td>
<td></td>
<td>%</td>
</tr>
<tr>
<td>Minimum Duty Cycle</td>
<td></td>
<td></td>
<td></td>
<td>0</td>
<td></td>
<td>%</td>
</tr>
<tr>
<td>Minimum Off-Time</td>
<td></td>
<td></td>
<td></td>
<td>300</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td><strong>Soft-Start</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Soft-Start Time</td>
<td></td>
<td></td>
<td></td>
<td>3</td>
<td></td>
<td>ms</td>
</tr>
<tr>
<td><strong>Short-Circuit Protection</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Peak Inductor Current-Limit Threshold</td>
<td></td>
<td>7.5</td>
<td>11</td>
<td>17</td>
<td>A</td>
<td>$V_{FB} = 0.8V$, $T_J = 25°C$</td>
</tr>
<tr>
<td></td>
<td></td>
<td>6.6</td>
<td>11</td>
<td>17</td>
<td>A</td>
<td>$V_{FB} = 0.8V$, $T_J = 125°C$</td>
</tr>
<tr>
<td>Short-Circuit Current</td>
<td></td>
<td></td>
<td></td>
<td>8</td>
<td></td>
<td>A</td>
</tr>
<tr>
<td><strong>Internal FETs</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Note 1:** Specification for packaged product only.

**2:** Measured in test mode.

**3:** The maximum duty-cycle is limited by the fixed mandatory off-time ($t_{OFF}$) of typically 300 ns.
TABLE 1-1: ELECTRICAL CHARACTERISTICS (CONTINUED)

Electrical Characteristics: PVIN = VIN = VEN = 12V, VBST – VSW = 5V; TA = 25°C, unless noted. **Bold** values indicate –40°C ≤ TJ ≤ +125°C. *(Note 1).*

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Sym.</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Units</th>
<th>Conditions</th>
</tr>
</thead>
<tbody>
<tr>
<td>Top MOSFET RDS(ON)</td>
<td>—</td>
<td>—</td>
<td>42</td>
<td>—</td>
<td>mΩ</td>
<td>ISW = 1A</td>
</tr>
<tr>
<td>Bottom MOSFET RDS(ON)</td>
<td>—</td>
<td>—</td>
<td>12.5</td>
<td>—</td>
<td>mΩ</td>
<td>ISW = 1A</td>
</tr>
<tr>
<td>SW Leakage Current</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>60</td>
<td>µA</td>
<td>VEN = 0V</td>
</tr>
<tr>
<td>VIN Leakage Current</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>25</td>
<td>µA</td>
<td>VEN = 0V</td>
</tr>
</tbody>
</table>

**Power Good (PG)**

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Sym.</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Units</th>
<th>Conditions</th>
</tr>
</thead>
<tbody>
<tr>
<td>PG Threshold Voltage</td>
<td>—</td>
<td>85</td>
<td>92</td>
<td>95</td>
<td>%VOUT</td>
<td>Sweep VFB from Low to High</td>
</tr>
<tr>
<td>PG Hysteresis</td>
<td>—</td>
<td>5.5</td>
<td>—</td>
<td>—</td>
<td>%VOUT</td>
<td>Sweep VFB from High to Low</td>
</tr>
<tr>
<td>PG Delay Time</td>
<td>—</td>
<td>100</td>
<td>—</td>
<td>—</td>
<td>µs</td>
<td>Sweep VFB from Low to High</td>
</tr>
<tr>
<td>PG Low Voltage</td>
<td>—</td>
<td>70</td>
<td>200</td>
<td>—</td>
<td>mV</td>
<td>Sweep VFB &lt; 0.9 x VNOM, IPG = 1 mA</td>
</tr>
</tbody>
</table>

**Thermal Protection**

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Sym.</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Units</th>
<th>Conditions</th>
</tr>
</thead>
<tbody>
<tr>
<td>Overtemperature Shutdown</td>
<td>—</td>
<td>—</td>
<td>160</td>
<td>—</td>
<td>°C</td>
<td>TJ Rising</td>
</tr>
<tr>
<td>Overtemperature Shutdown Hysteresis</td>
<td>—</td>
<td>—</td>
<td>15</td>
<td>—</td>
<td>°C</td>
<td></td>
</tr>
</tbody>
</table>

**Note 1:** Specification for packaged product only.

**Note 2:** Measured in test mode.

**Note 3:** The maximum duty-cycle is limited by the fixed mandatory off-time (tOFF) of typically 300 ns.
## TEMPERATURE SPECIFICATIONS

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Sym.</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Units</th>
<th>Conditions</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Temperature Ranges</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Junction Operating Temperature Range</td>
<td>$T_J$</td>
<td>$-40$</td>
<td></td>
<td>$+125$</td>
<td>°C</td>
<td>Note 1</td>
</tr>
<tr>
<td>Maximum Junction Temperature</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Storage Temperature</td>
<td>$T_S$</td>
<td>$-65$</td>
<td></td>
<td>$+150$</td>
<td>°C</td>
<td></td>
</tr>
<tr>
<td>Lead Temperature</td>
<td></td>
<td></td>
<td></td>
<td>$+260$</td>
<td>°C</td>
<td>Soldering, 10s</td>
</tr>
</tbody>
</table>

| Package Thermal Resistances | | | | | | |
| Thermal Resistance, 5x6 QFN-28 | $\theta_{JA}$ | | $28$ | | °C/W | Note 2 |
| Thermal Resistance, 5x6 QFN-28 | $\theta_{JC}$ | | $2.5$ | | °C/W | |

**Note 1:** The maximum allowable power dissipation is a function of ambient temperature, the maximum allowable junction temperature and the thermal resistance from junction to air (i.e., $T_A$, $T_J$, $\theta_{JA}$). Exceeding the maximum allowable power dissipation will cause the device operating junction temperature to exceed the maximum +125°C rating. Sustained junction temperatures above +125°C can impact the device reliability.

**2:** $P_{D(MAX)} = (T_{J(MAX)} - T_A)/\theta_{JA}$, where $\theta_{JA}$ depends upon the printed circuit layout. A 5 square inch 4 layer, 0.62", FR-4 PCB with 2 oz. finish copper weight per layer is used for the $\theta_{JA}$.
2.0 TYPICAL PERFORMANCE CURVES

**Note:** The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

**FIGURE 2-1:** $V_{\text{IN}}$ Operating Supply Current vs. Input Voltage.

**FIGURE 2-2:** $V_{\text{IN}}$ Shutdown Current vs. Input Voltage.

**FIGURE 2-3:** $V_{\text{DD}}$ Output Voltage vs. Input Voltage.

**FIGURE 2-4:** Feedback Voltage vs. Input Voltage.

**FIGURE 2-5:** Total Regulation vs. Input Voltage.

**FIGURE 2-6:** Output Current Limit vs. Input Voltage.
**FIGURE 2-7:** Switching Frequency vs. Input Voltage.

**FIGURE 2-8:** Enable Input Current vs. Input Voltage.

**FIGURE 2-9:** PG Threshold/$V_{REF}$ Ratio vs. Input Voltage.

**FIGURE 2-10:** $V_{IN}$ Operating Supply Current vs. Temperature.

**FIGURE 2-11:** $V_{IN}$ Shutdown Current vs. Temperature.

**FIGURE 2-12:** $V_{DD}$ UVLO Threshold vs. Temperature.
FIGURE 2-13: Feedback Voltage vs. Temperature.

FIGURE 2-14: Load Regulation vs. Temperature.

FIGURE 2-15: Line Regulation vs. Temperature.

FIGURE 2-16: Switching Frequency vs. Temperature.

FIGURE 2-17: $V_{DD}$ vs. Temperature.

FIGURE 2-18: Output Current Limit vs. Temperature.
FIGURE 2-19: Switching Frequency vs. Output Voltage.

FIGURE 2-20: Feedback Voltage vs. Output Current.

FIGURE 2-21: Output Voltage vs. Output Current.


FIGURE 2-23: Switching Frequency vs. Output Current.

FIGURE 2-24: Output Voltage ($V_{IN} = 5V$) vs. Output Current.
FIGURE 2-25: Efficiency ($V_{IN} = 5V$) vs. Output Current.

FIGURE 2-26: IC Power Dissipation ($V_{IN} = 5V$) vs. Output Current.

FIGURE 2-27: Die Temperature ($V_{IN} = 5V$) vs. Output Current (Note 1).

FIGURE 2-28: Efficiency ($V_{IN} = 12V$) vs. Output Current.

FIGURE 2-29: IC Power Dissipation ($V_{IN} = 12V$) vs. Output Current.

FIGURE 2-30: Die Temperature ($V_{IN} = 12V$) vs. Output Current (Note 1).
FIGURE 2-31: Thermal Derating vs. Ambient Temperature (Note 1).

FIGURE 2-32: Thermal Derating vs. Ambient Temperature (Note 1).

FIGURE 2-33: Thermal Derating vs. Ambient Temperature (Note 1).

FIGURE 2-34: Thermal Derating vs. Ambient Temperature (Note 1).

FIGURE 2-35: $V_{IN}$ Soft Turn-On.

FIGURE 2-36: $V_{IN}$ Soft Turn-Off.

Note 1: The temperature measurement was taken at the hottest point on the MIC24051 case mounted on a 5 square inch 4 layer, 0.62”, FR-4 PCB with 2oz finish copper weight per layer, see Thermal Measurement section. Actual results will depend upon the size of the PCB, ambient temperature and proximity to other heat emitting components.
FIGURE 2-37: Enable Turn-On Delay and Rise Time.

FIGURE 2-38: Enable Turn-Off Delay and Fall Time.

FIGURE 2-39: \(V_{IN}\) Start-Up with Pre-Biased Output.

FIGURE 2-40: Enable Turn-On/Turn-Off.

FIGURE 2-41: Enable Thresholds.

FIGURE 2-42: \(V_{DD}\) UVLO Thresholds.
FIGURE 2-43: Power-Up Into Short Circuit.

FIGURE 2-44: Enable Into Short Circuit.

FIGURE 2-45: Short Circuit.

FIGURE 2-46: Output Recovery from Short Circuit.

FIGURE 2-47: Output Current-Limit Threshold.

FIGURE 2-48: Output Recovery from Thermal Shutdown.
**FIGURE 2-49:** Switching Waveforms ($I_{OUT} = 6A$).

**FIGURE 2-50:** Switching Waveforms ($I_{OUT} = 0A$).

**FIGURE 2-51:** Transient Response.
3.0 PIN DESCRIPTIONS

The descriptions of the pins are listed in Table 3-1.

<table>
<thead>
<tr>
<th>Pin Number</th>
<th>Pin Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>PVDD</td>
<td>5V Internal Linear Regulator output. PVDD supply is the power MOSFET gate drive supply voltage and created by internal LDO from VIN. When VIN &lt; +5.5V, PVDD should be tied to PVIN pins. A 2.2 μF ceramic capacitor from the PVDD pin to PGND (Pin 2) must be placed next to the IC.</td>
</tr>
<tr>
<td>2, 5, 6, 7, 8, 21</td>
<td>PGND</td>
<td>Power Ground. PGND is the ground path for the MIC24051 buck converter power stage. The PGND pins connect to the low-side N-Channel internal MOSFET gate drive supply ground, the sources of the MOSFETs, the negative terminals of input capacitors, and the negative terminals of output capacitors. The loop for the power ground should be as small as possible and separate from the signal ground (SGND) loop.</td>
</tr>
<tr>
<td>3</td>
<td>NC</td>
<td>No connect.</td>
</tr>
<tr>
<td>4, 9, 10, 11, 12</td>
<td>SW</td>
<td>Switch Node output. Internal connection for the high-side MOSFET source and low-side MOSFET drain. Due to the high-speed switching on this pin, the SW pin should be routed away from sensitive nodes.</td>
</tr>
<tr>
<td>13,14,15, 16,17,18,19</td>
<td>PVIN</td>
<td>High-Side N-Internal MOSFET Drain Connection input. The PVIN operating voltage range is from 4.5V to 19V. Input capacitors between the PVIN pins and the Power Ground (PGND) are required and keep the connection short.</td>
</tr>
<tr>
<td>20</td>
<td>BST</td>
<td>Boost output. Bootstrapped voltage to the high-side N-channel MOSFET driver. A Schottky diode is connected between the PVDD pin and the BST pin. A boost capacitor of 0.1 μF is connected between the BST pin and the SW pin. Adding a small resistor at the BST pin can slow down the turn-on time of high-side N-Channel MOSFETs.</td>
</tr>
<tr>
<td>22</td>
<td>CS</td>
<td>Current Sense input. The CS pin senses current by monitoring the voltage across the low-side MOSFET during the OFF-time. The current sensing is necessary for short circuit protection. In order to sense the current accurately, connect the low-side MOSFET drain to SW using a Kelvin connection. The CS pin is also the high-side MOSFET's output driver return.</td>
</tr>
<tr>
<td>23</td>
<td>SGND</td>
<td>Signal Ground. SGND must be connected directly to the ground planes. Do not route the SGND pin to the PGND Pad on the top layer (see PCB Layout Recommendations for details).</td>
</tr>
<tr>
<td>24</td>
<td>FB</td>
<td>Feedback input. Input to the transconductance amplifier of the control loop. The FB pin is regulated to 0.8V. A resistor divider connecting the feedback to the output is used to adjust the desired output voltage.</td>
</tr>
<tr>
<td>25</td>
<td>PG</td>
<td>Power Good output. Open drain output. The PG pin is externally tied with a resistor to VDD. A high output is asserted when VOUT &gt; 92% of nominal.</td>
</tr>
<tr>
<td>26</td>
<td>EN</td>
<td>Enable input. A logic level control of the output. The EN pin is CMOS-compatible. Logic high = enable, logic low = shutdown. In the off state, supply current of the device is greatly reduced (typically 5 μA). The EN pin should not be left floating.</td>
</tr>
<tr>
<td>27</td>
<td>VIN</td>
<td>Power Supply Voltage input. Requires bypass capacitor to SGND.</td>
</tr>
<tr>
<td>28</td>
<td>VDD</td>
<td>5V Internal Linear Regulator output. VDD supply is the supply bus for the IC control circuit. VDD is created by internal LDO from VIN. When VIN &lt; +5.5V, VDD should be tied to PVIN pins. A 1 μF ceramic capacitor from the VDD pin to SGND pins must be placed next to the IC.</td>
</tr>
</tbody>
</table>
4.0 FUNCTIONAL DESCRIPTION

The MIC24051 is an adaptive ON-time synchronous step-down DC/DC regulator with an internal 5V linear regulator and a Power Good (PG) output. It is designed to operate over a wide input voltage range from 4.5V to 19V and provides a regulated output voltage at up to 6A of output current. An adaptive ON-time control scheme is employed in order to obtain a constant switching frequency and to simplify the control compensation. Overcurrent protection is implemented without the use of an external sense resistor. The device includes an internal soft-start function which reduces the power supply input surge current at start-up by controlling the output voltage rise time.

4.1 Theory of Operation

The MIC24051 operates in a continuous mode as shown in the Block Diagram.

4.2 Continuous Mode

In continuous mode, the output voltage is sensed by the MIC24051 feedback pin FB via the voltage divider R1 and R2, and compared to a 0.8V reference voltage VREF at the error comparator through a low gain transconductance (g_m) amplifier. If the feedback voltage decreases and the output of the g_m amplifier is below 0.8V, then the error comparator will trigger the control logic and generate an ON-time period. The ON-time period length is predetermined by the "FIXED tON ESTIMATION" circuitry:

EQUATION 4-1:

\[ t_{\text{ON(EFFECTED) }} = \frac{V_{\text{OUT}}}{V_{\text{IN}} \times 600 \text{kHz}} \]

Where:
- \( V_{\text{OUT}} \) Output voltage
- \( V_{\text{IN}} \) Power stage input voltage

At the end of the ON-time period, the internal high-side driver turns off the high-side MOSFET and the low-side driver turns on the low-side MOSFET. The OFF-time period length depends upon the feedback voltage in most cases. When the feedback voltage decreases and the output of the g_m amplifier is below 0.8V, the ON-time period is triggered and the OFF-time period ends. If the OFF-time period determined by the feedback voltage is less than the minimum OFF-time \( t_{\text{OFF(min)}} \), which is about 300 ns, the MIC24051 control logic will apply the \( t_{\text{OFF(min)}} \) instead. \( t_{\text{OFF(min)}} \) is required to maintain enough energy in the boost capacitor (\( C_{\text{BST}} \)) to drive the high-side MOSFET.

The maximum duty cycle is obtained from the 300 ns \( t_{\text{OFF(min)}} \):

EQUATION 4-2:

\[ D_{\text{MAX}} = \frac{t_{\text{S}} - t_{\text{OFF(min)}}}{t_{\text{S}}} = 1 - \frac{300 \text{ns}}{t_{\text{S}}} \]

Where:
- \( t_{\text{S}} \) 1/600 kHz = 1.66 µs

It is not recommended to use MIC24051 with a OFF-time close to \( t_{\text{OFF(min)}} \) during steady-state operation. Also, as \( V_{\text{OUT}} \) increases, the internal ripple injection will increase and reduce the line regulation performance. Therefore, the maximum output voltage of the MIC24051 should be limited to 5.5V and the maximum external ripple injection should be limited to 200 mV. Please refer to Setting Output Voltage in the Application Information section for more details.

The actual ON-time and resulting switching frequency will vary with the part-to-part variation in the rise and fall times of the internal MOSFETs, the output load current, and variations in the \( V_{\text{DD}} \) voltage. Also, the minimum \( t_{\text{ON}} \) results in a lower switching frequency in high \( V_{\text{IN}} \) to \( V_{\text{OUT}} \) applications, such as 18V to 1.0V. The minimum \( t_{\text{ON}} \) measured on the MIC24051 evaluation board is about 100 ns. During load transients, the switching frequency is changed due to the varying OFF-time.

To illustrate the control loop operation, we will analyze both the steady-state and load transient scenarios. Figure 4-1 shows the MIC24051 control loop timing during steady-state operation. During steady-state, the gm amplifier senses the feedback voltage ripple, which is proportional to the output voltage ripple and the inductor current ripple, to trigger the ON-time period. The ON-time is predetermined by the \( t_{\text{ON}} \) estimator. The termination of the OFF-time is controlled by the feedback voltage. At the valley of the feedback voltage ripple, which occurs when \( V_{\text{FB}} \) falls below \( V_{\text{REF}} \), the OFF period ends and the next ON-time period is triggered through the control logic circuitry.
Figure 4-1 shows the operation of the MIC24051 during a load transient. The output voltage drops due to the sudden load increase, which causes the VFB to be less than VREF. This will cause the error comparator to trigger an ON-time period. At the end of the ON-time period, a minimum OFF-time \( t_{OFF(min)} \) is generated to charge \( C_{BST} \) because the feedback voltage is still below \( V_{REF} \). Then, the next ON-time period is triggered due to the low feedback voltage. Therefore, the switching frequency changes during the load transient, but returns to the nominal fixed frequency once the output has stabilized at the new load current level. With the varying duty cycle and switching frequency, the output recovery time is fast and the output voltage deviation is small in MIC24051 converter.

Unlike true current-mode control, the MIC24051 uses the output voltage ripple to trigger an ON-time period. The output voltage ripple is proportional to the inductor current ripple if the ESR of the output capacitor is large enough. The MIC24051 control loop has the advantage of eliminating the need for slope compensation.

In order to meet the stability requirements, the MIC24051 feedback voltage ripple should be in phase with the inductor current ripple and large enough to be sensed by the gm amplifier and the error comparator. The recommended feedback voltage ripple is 20 mV~100 mV. If a low-ESR output capacitor is selected, then the feedback voltage ripple may be too small to be sensed by the gm amplifier and the error comparator. Also, the output voltage ripple and the feedback voltage ripple are not necessarily in phase with the inductor current ripple if the ESR of the output capacitor is very low. In these cases, ripple injection is required to ensure proper operation. Please refer to Ripple Injection in the Application Information section for more details about the ripple injection technique.

### 4.3 \( V_{DD} \) Regulator

The MIC24051 provides a 5V regulated output for input voltage \( V_{IN} \) ranging from 5.5V to 19V. When \( V_{IN} < 5.5V \), \( V_{DD} \) should be tied to \( PVIN \) pins to bypass the internal linear regulator.

### 4.4 Soft-Start

Soft-start reduces the power supply input surge current at startup by controlling the output voltage rise time. The input surge appears while the output capacitor is charged up. A slower output rise time will draw a lower input surge current.

The MIC24051 implements an internal digital soft-start by making the 0.8V reference voltage \( V_{REF} \) ramp from 0 to 100% in about 3 ms with 9.7 mV steps. Therefore, the output voltage is controlled to increase slowly by a stair-case \( V_{FB} \) ramp. Once the soft-start cycle ends, the related circuitry is disabled to reduce current consumption. \( V_{DD} \) must be powered up at the same time or after \( V_{IN} \) to make the soft-start function correctly.

### 4.5 Current Limit

The MIC24051 uses the \( R_{DS(ON)} \) of the internal low-side power MOSFET to sense over-current conditions. This method will avoid adding cost, board space and power losses taken by a discrete current sense resistor. The low-side MOSFET is used because it displays much lower parasitic oscillations during switching than the high-side MOSFET.

In each switching cycle of the MIC24051 converter, the inductor current is sensed by monitoring the low-side MOSFET in the OFF period. If the peak inductor current is greater than 11A, then the MIC24051 turns off the high-side MOSFET and a soft-start sequence is triggered. This mode of operation is called “hiccup mode” and its purpose is to protect the downstream load in case of a hard short. The load current-limit threshold has a fold-back characteristic related to the feedback voltage as shown in Figure 4-3.
4.6 Power Good (PG)

The Power Good (PG) pin is an open drain output which indicates logic high when the output is nominally 92% of its steady state voltage. A pull-up resistor of more than 10 kΩ should be connected from PG to VDD.

4.7 MOSFET Gate Drive

The Block Diagram shows a bootstrap circuit, consisting of D1 (a Schottky diode is recommended) and C_{BST}. This circuit supplies energy to the high-side drive circuit. Capacitor C_{BST} is charged, while the low-side MOSFET is on, and the voltage on the SW pin is approximately 0V. When the high-side MOSFET driver is turned on, energy from C_{BST} is used to turn the MOSFET on. As the high-side MOSFET turns on, the voltage on the SW pin increases to approximately V_{IN}. Diode D1 is reverse biased and C_{BST} floats high while continuing to keep the high-side MOSFET on. The bias current of the high-side driver is less than 10 mA, so a 0.1 μF to 1 μF is sufficient to hold the gate voltage with minimal droop for the power stroke (high-side switching) cycle, i.e. \( \Delta BST = 10 \text{ mA} \times 1.67 \mu s/0.1 \mu F = 167 \text{ mV} \). When the low-side MOSFET is turned back on, C_{BST} is recharged through D1. A small resistor R_G, which is in series with C_{BST}, can be used to slow down the turn-on time of the high-side N-channel MOSFET.

The drive voltage is derived from the V_{DD} supply voltage. The nominal low-side gate drive voltage is V_{DD} and the nominal high-side gate drive voltage is approximately V_{DD} - V_{DIODE}, where V_{DIODE} is the voltage drop across D1. An approximate 30 ns delay between the high-side and low-side driver transitions is used to prevent current from simultaneously flowing unimpeded through both MOSFETs.
5.0 APPLICATION INFORMATION

5.1 Inductor Selection

Values for inductance, peak, and RMS currents are required to select the output inductor. The input and output voltages and the inductance value determine the peak-to-peak inductor ripple current. Generally, higher inductance values are used with higher input voltages. Larger peak-to-peak ripple currents will increase the power dissipation in the inductor and MOSFETs. Larger output ripple currents will also require more output capacitance to smooth out the larger ripple current. Smaller peak-to-peak ripple currents require a larger inductance value and therefore a larger and more expensive inductor. A good compromise between size, loss and cost is to set the inductor ripple current to be equal to 20% of the maximum output current. The inductance value is calculated in Equation 5-1.

**EQUATION 5-1:**

\[
L = \frac{V_{OUT} \times (V_{IN(MAX)} - V_{OUT})}{V_{IN(MAX)} \times f_{SW} \times 20\% \times I_{OUT(MAX)}}
\]

Where:
- \(f_{SW}\) Switching frequency, 600 kHz
- 20% Ratio of AC ripple current to DC output current
- \(V_{IN(MAX)}\) Maximum power stage input voltage

The peak-to-peak inductor current ripple is:

**EQUATION 5-2:**

\[
\Delta I_{L(PP)} = \frac{V_{OUT} \times (V_{IN(MAX)} - V_{OUT})}{V_{IN(MAX)} \times f_{SW} \times L}
\]

The peak inductor current is equal to the average output current plus one half of the peak-to-peak inductor current ripple.

**EQUATION 5-3:**

\[
I_{L(PK)} = I_{OUT(MAX)} + 0.5 \times \Delta I_{L(PP)}
\]

The RMS inductor current is used to calculate the \(I^2R\) losses in the inductor.

**EQUATION 5-4:**

\[
I_{L(RMS)} = \sqrt{\frac{I_{OUT(MAX)}^2 \times \Delta I_{L(PP)}^2}{12}}
\]

Maximizing efficiency requires the proper selection of core material and minimizing the winding resistance. The high-frequency operation of the MIC24051 requires the use of ferrite materials for all but the most cost sensitive applications. Lower cost iron powder cores may be used but the increase in core loss will reduce the efficiency of the power supply. This is especially noticeable at low output power. The winding resistance decreases efficiency at the higher output current levels. The winding resistance must be minimized although this usually comes at the expense of a larger inductor. The power dissipated in the inductor is equal to the sum of the core and copper losses. At higher output loads, the core losses are usually insignificant and can be ignored. At lower output currents, the core losses can be a significant contributor. Core loss information is usually available from the magnetics vendor. Copper loss in the inductor is calculated by Equation 5-5:

**EQUATION 5-5:**

\[
P_{INDUCTOR(CU)} = I_{L(RMS)}^2 \times R_{WINDING}
\]

The resistance of the copper wire, \(R_{WINDING}\), increases with the temperature. The value of the winding resistance used should be at the operating temperature.

**EQUATION 5-6:**

\[
R_{WINDING(HT)} = R_{WINDING(20C)} \times (1 + 0.0042 \times (T_H - T_{20C}))
\]

Where:
- \(T_H\) Temperature of wire under full load
- \(T_{20C}\) Ambient temperature
- \(R_{WINDING(20C)}\) Room temperature winding resistance (usually specified by the manufacturer)
5.2 Output Capacitor Selection

The type of the output capacitor is usually determined by its equivalent series resistance (ESR). Voltage and RMS current capability are two other important factors for selecting the output capacitor. Recommended capacitor types are ceramic, low-ESR aluminum electrolytic, OS-CON and POSCAP. The output capacitor’s ESR is usually the main cause of the output ripple. The output capacitor ESR also affects the control loop from a stability point of view.

The maximum value of ESR is calculated:

\[ ESR_{COUT} \leq \frac{\Delta V_{OUT(PP)}}{\Delta I_{L(PP)}} \]

Where:
- \( \Delta V_{OUT(PP)} \) Peak-to-peak output voltage ripple
- \( \Delta I_{L(PP)} \) Peak-to-peak inductor current ripple

The total output ripple is a combination of the ESR and output capacitance. The total ripple is calculated in Equation 5-8:

\[ \Delta V_{OUT(PP)} = \sqrt{\left( \frac{\Delta I_{L(PP)}}{C_{OUT} \times f_{SW} \times 8/3} \right)^2 + \left( \Delta I_{L(PP)} \times ESR_{COUT} \right)^2} \]

Where:
- \( C_{OUT} \) Output capacitance value
- \( f_{SW} \) Switching frequency

As described in the Theory of Operation section, the MIC24051 requires at least 20 mV peak-to-peak ripple at the FB pin to make the \( g_m \) amplifier and the error comparator behave properly. Also, the output voltage ripple should be in phase with the inductor current. Therefore, the output voltage ripple caused by the output capacitors value should be much smaller than the ripple caused by the output capacitor ESR. If low-ESR capacitors, such as ceramic capacitors, are selected as the output capacitors, a ripple injection method should be applied to provide the enough feedback voltage ripple. Please refer to the Ripple Injection section for more details.

The voltage rating of the capacitor should be twice the output voltage for a tantalum and 20% greater for aluminum electrolytic or OS-CON. The output capacitor RMS current is calculated in Equation 5-9:

\[ I_{COUT(RMS)} = \frac{\Delta I_{L(PP)}}{\sqrt{12}} \]

The power dissipated in the output capacitor is:

\[ P_{DISS(COUT)} = I_{COUT(RMS)} \times ESR_{COUT} \]

5.3 Input Capacitor Selection

The input capacitor for the power stage input \( V_{IN} \) should be selected for ripple current rating and voltage rating. Tantalum input capacitors may fail when subjected to high inrush currents, caused by turning the input supply on. A tantalum input capacitor’s voltage rating should be at least two times the maximum input voltage to maximize reliability. Aluminum electrolytic, OS-CON, and multilayer polymer film capacitors can handle the higher inrush currents without voltage de-rating. The input voltage ripple will primarily depend on the input capacitor’s ESR. The peak input current is equal to the peak inductor current, so:

\[ \Delta V_{IN} = I_{L(PP)} \times ESR_{CIN} \]

The input capacitor must be rated for the input current ripple. The RMS value of input capacitor current is determined at the maximum output current. Assuming the peak-to-peak inductor current ripple is low:

\[ I_{CIN(RMS)} = I_{OUT(MAX)} \times \sqrt{D \times (1 - D)} \]
5.4 Ripple Injection

The \( V_{FB} \) ripple required for proper operation of the MIC24051 \( g_m \) amplifier and error comparator is 20 mV to 100 mV. However, the output voltage ripple is generally designed as 1% to 2% of the output voltage. For a low output voltage, such as a 1V, the output voltage ripple is only 10 mV to 20 mV, and the feedback voltage ripple is less than 20 mV. If the feedback voltage ripple is so small that the \( g_m \) amplifier and error comparator can’t sense it, then the MIC24051 will lose control and the output voltage is not regulated. In order to have some amount of \( V_{FB} \) ripple, a ripple injection method is applied for low output voltage ripple applications.

The applications are divided into three situations according to the amount of the feedback voltage ripple:

1. **Enough ripple at the feedback voltage due to the large ESR of the output capacitors.**
   
   As shown in Figure 5-1, the converter is stable without any ripple injection. The feedback voltage ripple is:

   \[
   \Delta V_{FB(PP)} = \frac{R_2}{R_1 + R_2} \times ESR_{COUT} \times \Delta I_{L(PP)}
   \]

   Where:
   
   \( \Delta I_{L(PP)} \) Peak-to-peak value of the inductor current ripple

2. **Inadequate ripple at the feedback voltage due to the small ESR of the output capacitors.**

   The output voltage ripple is fed into the FB pin through a feed-forward capacitor \( C_{ff} \) in this situation, as shown in Figure 5-2. The typical \( C_{ff} \) value is between 1 nF and 100 nF. With the feed-forward capacitor, the feedback voltage ripple is very close to the output voltage ripple:

   \[
   \Delta V_{FB(PP)} \approx ESR \times \Delta I_{L(PP)}
   \]

3. **Virtually no ripple at the FB pin voltage due to the very low ESR of the output capacitors.**

   In this situation, the output voltage ripple is less than 20 mV. Therefore, additional ripple is injected into the FB pin from the switching node SW via a resistor \( R_{INJ} \) and a capacitor \( C_{INJ} \), as shown in Figure 5-3. The injected ripple is:

   \[
   \Delta V_{FB(PP)} = V_{IN} \times K_D \times D \times (1 - D) \times \frac{1}{f_{SW} \times \tau}
   \]

   Where:
   
   - \( V_{IN} \) Power stage input voltage
   - \( D \) Duty cycle
   - \( f_{SW} \) Switching frequency
   - \( \tau \) \((R_1/R_2/R_{INJ}) \times C_{ff}\)
MIC24051

5.5 Setting Output Voltage

The MIC24051 requires two resistors to set the output voltage as shown in Figure 5-4.

The output voltage is determined by Equation 5-21:

\[
V_{OUT} = V_{FB} \times \left(1 + \frac{R1}{R2}\right)
\]

\(V_{FB}\) equals 0.8V. A typical value of \(R1\) can be between 3 kΩ and 10 kΩ. If \(R1\) is too large, it may allow noise to be introduced into the voltage feedback loop. If \(R1\) is too small, it will decrease the efficiency of the power supply, especially at light loads. Once \(R1\) is selected, \(R2\) can be calculated using:

\[
R2 = \frac{V_{FB} \times R1}{V_{OUT} - V_{FB}}
\]

FIGURE 5-4: Voltage Divider Configuration.

In addition to the external ripple injection added at the FB pin, internal ripple injection is added at the inverting input of the comparator inside the MIC24051, as shown in Figure 5-5. The inverting input voltage \(V_{INJ}\) is clamped to 1.2V. As \(V_{OUT}\) is increased, the swing of \(V_{INJ}\) will be clamped. The clamped \(V_{INJ}\) reduces the line regulation because it is reflected as a DC error on the FB terminal. Therefore, the maximum output voltage of the MIC24051 should be limited to 5.5V to avoid this problem.

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EQUATION 5-17:

\[
K_{DIV} = \frac{R1//R2}{R_{INJ} + R1//R2}
\]

In Equation 5-16 and Equation 5-17, it is assumed that the time constant associated with \(C_{ff}\) must be much greater than the switching period:

EQUATION 5-18:

\[
\frac{1}{f_{SW} \times \tau} = \frac{T}{\tau} \ll 1
\]

If the voltage divider resistors \(R1\) and \(R2\) are in the kΩ range, a \(C_{ff}\) of 1 nF to 100 nF can easily satisfy the large time constant requirements. Also, a 100 nF injection capacitor \(C_{INJ}\) is used in order to be considered as short for a wide range of the frequencies.

The process of sizing the ripple injection resistor and capacitors is:

1. Select \(C_{ff}\) to feed all output ripples into the feedback pin and make sure the large time constant assumption is satisfied. Typical choice of \(C_{ff}\) is 1 nF to 100 nF if \(R1\) and \(R2\) are in kΩ range.

2. Select \(R_{INJ}\) according to the expected feedback voltage ripple using Equation 5-19:

EQUATION 5-19:

\[
K_{DIV} = \frac{\Delta V_{FB(PP)}}{V_{IN}} \times \frac{f_{SW} \times \tau}{D \times (1 - D)}
\]

Then the value of \(R_{INJ}\) is obtained as:

EQUATION 5-20:

\[
R_{INJ} = (R1//R2) \times \left(\frac{1}{K_{DIV}} - 1\right)
\]

3. Select \(C_{INJ}\) as 100 nF, which could be considered as short for a wide range of the frequencies.
5.6 Thermal Measurements

Measuring the IC’s case temperature is recommended to ensure it is within its operating limits. Although this might seem like a very elementary task, it is easy to get erroneous results. The most common mistake is to use the standard thermal couple that comes with a thermal meter. This thermal couple wire gauge is large, typically 22 gauge, and behaves like a heatsink, resulting in a lower case measurement.

Two methods of temperature measurement are using a smaller thermal couple wire or an infrared thermometer. If a thermal couple wire is used, it must be constructed of 36 gauge wire or higher then (smaller wire size) to minimize the wire heat-sinking effect. In addition, the thermal couple tip must be covered in either thermal grease or thermal glue to make sure that the thermal couple junction is making good contact with the case of the IC. Omega brand thermal couple (5SC-TT-K-36-36) is adequate for most applications.

Wherever possible, an infrared thermometer is recommended. The measurement spot size of most infrared thermometers is too large for an accurate reading on a small form factor ICs. However, an IR thermometer from Optris has a 1 mm spot size, which makes it a good choice for measuring the hottest point on the case. An optional stand makes it easy to hold the beam on the IC for long periods of time.
6.0 PCB LAYOUT RECOMMENDATIONS

To minimize EMI and output noise, follow these layout recommendations.

PCB layout is critical to achieve reliable, stable and efficient performance. A ground plane is required to control EMI and minimize the inductance in power, signal and return paths.

The following guidelines should be followed to insure proper operation of the MIC24051 regulator.

6.1 IC

• A 2.2 µF ceramic capacitor, which is connected to the PVDD pin, must be located right at the IC. The PVDD pin is very noise sensitive and placement of the capacitor is very critical. Use wide traces to connect to the PVDD and PGND pins.
• A 1 µF ceramic capacitor must be placed right between VDD and the signal ground SGND. The SGND must be connected directly to the ground planes. Do not route the SGND pin to the PGND Pad on the top layer.
• Place the IC close to the point-of-load (POL).
• Use fat traces to route the input and output power lines.
• Signal and power grounds should be kept separate and connected at only one location.

6.2 Input Capacitor

• Place the input capacitors on the same side of the board and as close to the IC as possible.
• Keep both the PVIN pin and PGND connections short.
• Place several vias to the ground plane close to the input capacitor ground terminal.
• Use either X7R or X5R dielectric input capacitors. Do not use Y5V or Z5U type capacitors.
• Do not replace the ceramic input capacitor with any other type of capacitor. Any type of capacitor can be placed in parallel with the input capacitor.
• If a Tantalum input capacitor is placed in parallel with the input capacitor, it must be recommended for switching regulator applications and the operating voltage must be derated by 50%.
• In “Hot-Plug” applications, a Tantalum or Electrolytic bypass capacitor must be used to limit the over-voltage spike seen on the input supply with power is suddenly applied.

6.3 Inductor

• Keep the inductor connection to the switch node (SW) short.
• Do not route any digital lines underneath or close to the inductor.
• Keep the switch node (SW) away from the feedback (FB) pin.
• The CS pin should be connected directly to the SW pin to accurately sense the voltage across the low-side MOSFET.
• To minimize noise, place a ground plane underneath the inductor.
• The inductor can be placed on the opposite side of the PCB with respect to the IC. It does not matter whether the IC or inductor is on the top or bottom as long as there is enough air flow to keep the power components within their temperature limits. The input and output capacitors must be placed on the same side of the board as the IC.

6.4 Output Capacitor

• Use a wide trace to connect the output capacitor ground terminal to the input capacitor ground terminal.
• Phase margin will change as the output capacitor value and ESR changes. Contact the factory if the output capacitor is different from what is shown in the user guide.
• The feedback trace should be separate from the power trace and connected as close as possible to the output capacitor. Sensing a long high-current load trace can degrade the DC load regulation.

6.5 Optional RC Snubber

• Place the RC snubber on either side of the board and as close to the SW pin as possible.
7.0 PACKAGING INFORMATION

7.1 Package Marking Information

Legend:

- XX...X Product code or customer-specific information
- Y Year code (last digit of calendar year)
- YY Year code (last 2 digits of calendar year)
- WW Week code (week of January 1 is week ‘01’)
- NNN Alphanumeric traceability code
- 3e Pb-free JEDEC® designator for Matte Tin (Sn)
- This package is Pb-free. The Pb-free JEDEC designator (3e) can be found on the outer packaging for this package.
- ●, ▲, ▼ Pin one index is identified by a dot, delta up, or delta down (triangle mark).

Note: In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information. Package may or may not include the corporate logo.

Underbar (_) and/or Overbar (') symbol may not be to scale.
28-Pin 5 mm x 6 mm QFN Package Outline and Recommended Land Pattern

**TITLE**

28 LEAD QFN 5x6mm PACKAGE OUTLINE (Co-Package) & RECOMMENDED LAND PATTERN

**DRAWING #** QFN56-28LD-PL-1

**UNIT** MM

---

**NOTE:**
1. MAX PACKAGE VARIANCE IS ±0.05 MM
2. MAX ALLOWABLE BURR IS 0.05 MM IN ALL DIRECTIONS
3. PIN K, 13 ON TOP WILL BE UNDER MOLD
4. RED CIRCLES IN LAND PATTERN REPRESENT THERMAL VIA & SHOULD BE CONNECTED TO GND FOR MAXIMUM PERFORMANCE.
5. GREEN RECTANGLES SHADED AREA REPRESENT SOLDER STENCIL OPENING IN EXPOSED PAI AREA.
6. BLUE CIRCLES & PURPLE CIRCLES PADS REPRESENT DIFFERENTIALS. DO NOT CONNECT TO GND.
7. RECOMMENDED SOLDER STENCIL OPENING AND VIA SIZES:

<table>
<thead>
<tr>
<th>Via size/Pad</th>
<th>Solder stencil opening/Pitch</th>
<th>Comments</th>
</tr>
</thead>
<tbody>
<tr>
<td>Red circle, black pad</td>
<td>0.166x0.318mm/0.8mm</td>
<td>1.5х1.8mm/1.75mm</td>
</tr>
<tr>
<td>Blue circle, black pad</td>
<td>0.166x0.318mm/0.8mm</td>
<td>0.81х1.61mm/1.12mm</td>
</tr>
<tr>
<td>Magenta circle, black pad</td>
<td>0.166x0.318mm/0.8mm</td>
<td>0.81х1.61mm/1.12mm</td>
</tr>
</tbody>
</table>

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**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at [http://www.microchip.com/packaging](http://www.microchip.com/packaging).
APPENDIX A: REVISION HISTORY

Revision A (November 2016)

- Converted Micrel document MIC24051 to Microchip data sheet DS20005658A.
- Minor text changes throughout.
- Vertical axis description updated in Figure 2-9.
- Labeling of Figure 2-42 corrected $V_{IN}$ to $V_{DD}$.
- Corrected a naming error in Equation 5-6.
- Corrected a formatting error in Equation 5-17.
## PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, contact your local Microchip representative or sales office.

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<td>Temperature</td>
<td>Package</td>
<td>Media Type</td>
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- **Device:** MIC24051: 12V, 6A High-Efficiency Buck Regulator with Hyper Speed Control
- **Temperature:** Y = −40°C to +125°C (Industrial)
- **Package:** JL = 28-Lead 5 mm x 6 mm QFN
- **Media Type:** TR = 1,000/Reel

### Examples:

a) MIC24051YJL-TR: 12V, 6A High-Efficiency Buck Regulator with Hyper Speed Control, −40°C to +125°C Temperature Range, 28-Lead QFN, 1,000/Reel

### Note 1:
Tape and Reel identifier only appears in the catalog part number description. This identifier is used for ordering purposes and is not printed on the device package. Check with your Microchip Sales Office for package availability with the Tape and Reel option.
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