

## Gas and Water Metering with the PIC16F91X Family

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### INTRODUCTION

Electronic utility meters are an important step towards automating the utility metering process. Automated utility meters allow many new features that help reduce the cost of utilities to customers and reduce the cost of delivering utilities to the utility provider.

### TYPES OF UTILITY METERS

The primary utilities metered are electricity, water and gas. Water and Gas are measured with very similar systems while electric meters are very unique.

#### Electric Meters

Electric meters measure the power consumed at a customers site. This type of meter is very easy to convert into an electronic version using an MCP3905 single-phase power metering IC.

#### Gas and Water Meters

Gas and water meters are based upon a mechanical flow meter. There are many types of flow meters, but the most common type for gas is a positive displacement flow meter. In this type of meter, a known volume of gas is accumulated and then released to the customer. Each time the volume of gas is released, a shaft rotates. The rotating shaft is attached to a meter movement to indicate the number of rotations or the total volume sold to the customer. Water flow meters are typically flow rate systems. The water flow impinges upon an impeller, causing rotation. The rotating impeller is attached to a magnet. A second magnet inside the meter movement couples to the first magnet by virtue of the magnetic fields. As the fluid motion causes the first magnet to turn, the second magnet also turns and the rotations are counted by the meter mechanism (see Figure 1).

By using a magnetically coupled system, the wetted portion of the meter can be kept clean, while the meter portion of the system can be converted to any type of sensor or display without affecting the measured fluid.

### READING FLUID FLOW

Because the water flow meter uses a spinning magnet to indicate flow rate, we must use a magnetic sensor or a spinning magnet to couple the flow meter. For this application, we decided to eliminate all moving parts in the display by using Hall effect switches to detect when the spinning magnet makes one revolution. By using two Hall effect switches, it is possible to determine which direction the water is flowing and to take an appropriate action. When using two switches, the digital outputs will sequence through the following four states as the magnets rotate (see Table 1).

**TABLE 1:**

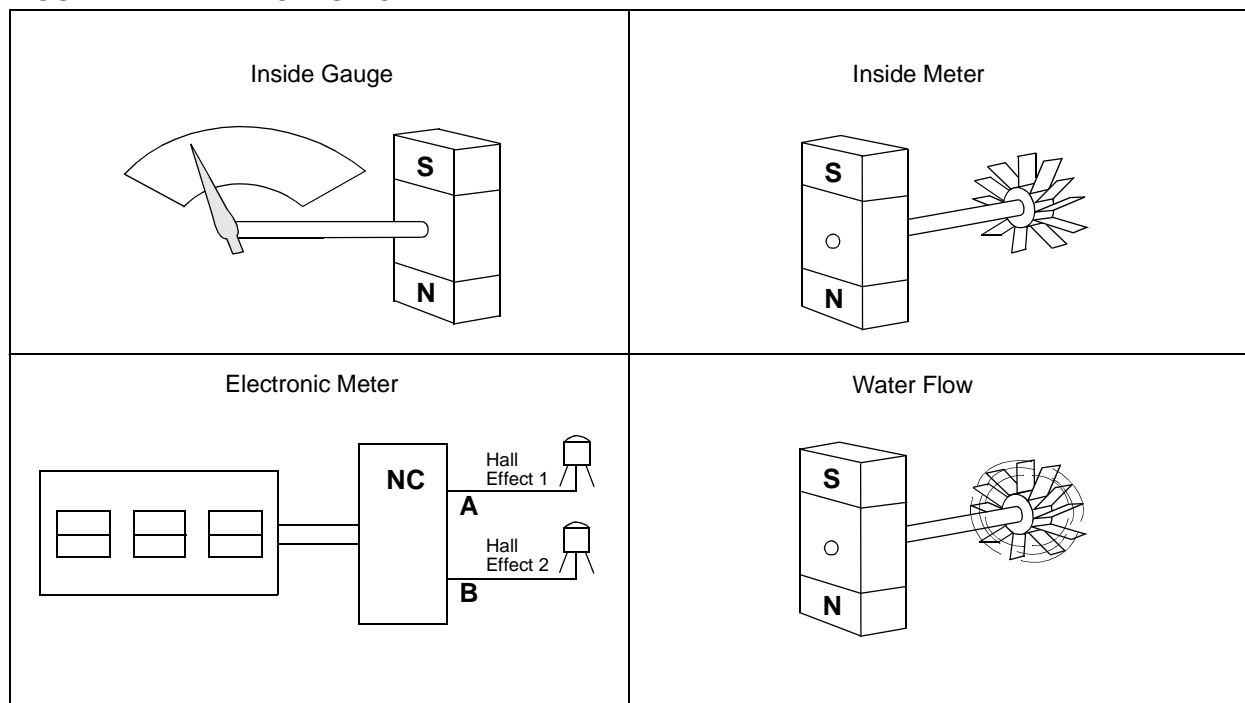
Switch States	Meaning
00	The magnet is not near the switches.
01	The magnet has reached the first switch.
11	The magnet is between the two switches.
10	The magnet has reached the second switch.
00	The magnet has moved past the switches.

If the state goes in the other direction, it means that the water has begun to backup. This indicates one of three things:

1. The system is installed incorrectly
2. The anti-siphon system has broken
3. The meter has been tampered with

It is also possible that some bouncing between adjacent states will occur. This is normal when the water has been turned off and the flow goes to zero.

**FIGURE 1: ELECTRONIC METER**



## DATA DISPLAY

Electronic displays come in a large variety of types but the most appropriate type for a low-power meter application is a LCD segment type display. Typically, these displays are custom built for the application they will be used in. For a demonstration unit, the cost of custom LCD glass was not appropriate, so an 8-digit, 7-segment display was found in the form of a Varitronix VIM-838 display. This display is available with pins to connect to the PCB which makes prototype units easier to construct. Driving this display requires a LCD controller device. Fortunately, Microchip Technology offers a wide variety of LCD controller equipped PICmicro<sup>®</sup> microcontrollers.

## ADVANCED FEATURES

Thinking of the future, this application was equipped with a radio transmitter to allow the meter data to be sent wirelessly to a nearby data collection device. Generally, the data collection devices are in a passing vehicle, so a wireless method to start the transmission is required. A radio receiver was added to accomplish the wake-up function. There are many simple RF solutions on the market. When building any RF transmission system, care must be taken to ensure that emitted power and frequency are within the regulated limits for the region the transmitter will be operating.

## MICROCONTROLLER CHOICE

For this application, the PIC16F917 was chosen from Microchip's new low-cost LCD family of devices (see Table 2):

- It can drive the number of segments in the chosen LCD glass
- It is low cost
- There are enough I/O pins left for the application and communications
- There is sufficient program space to handle the entire application

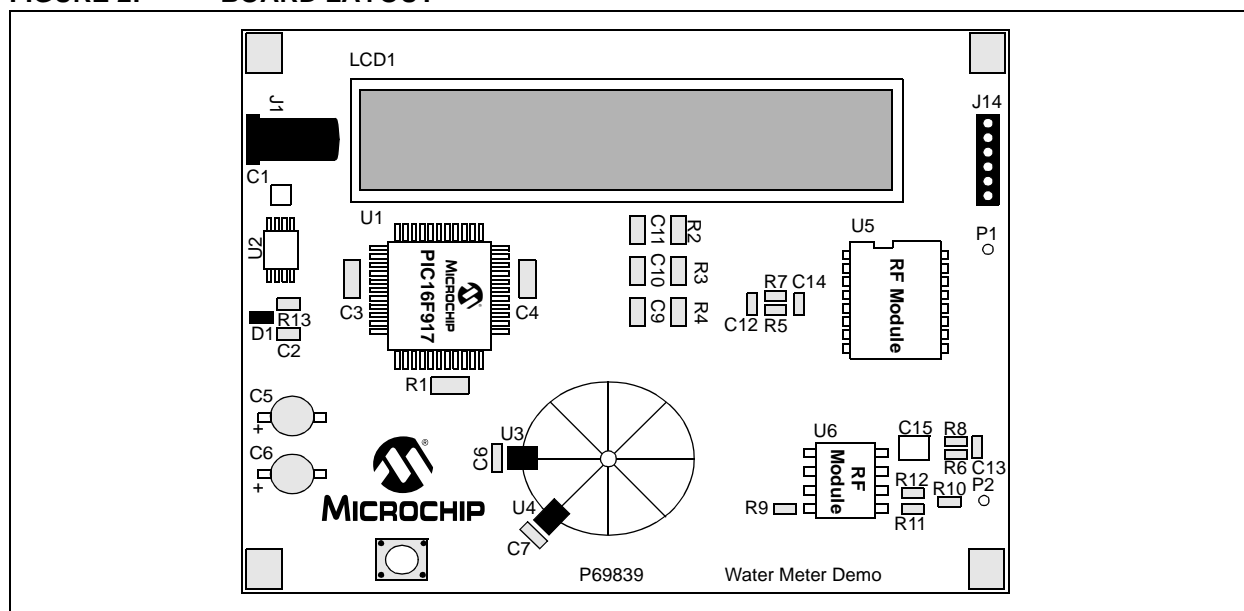
Other advantages of using the PIC16F917 is the possibility to add additional advanced features in the application, such as:

- Automatic contrast control with the internal comparators
- Low-voltage operation to allow a simple battery backup for off-line operation
- Internal nonvolatile memory (EEPROM) to back-up meter readings during power failures
- Variable clock speed to reduce power consumption between meter calculations
- In-circuit debugging allows debugging the code in the final circuit with the final device
- In-circuit programming simplifies programming of surface mount devices

TABLE 2:

Device	Program Memory	Data Memory		I/O	10-bit A/D (ch)	LCD (segment drivers)	CCP	Timer 8/16-bit
	Flash (words/bytes)	SRAM (bytes)	EEPROM (bytes)					
PIC16F913	4K/7K	256	256	24	5	16	1	2/1
PIC16F914	4K/7K	256	256	35	8	24	2	2/1
PIC16F916	8K/14K	352	256	24	5	16	1	2/1
PIC16F917	8K/14K	352	256	35	8	24	2	2/1

FIGURE 2: BOARD LAYOUT



## PUTTING THE HARDWARE TOGETHER

With the basic design decisions made, the next step is to assemble the building blocks into a working system.

## WIRING THE GLASS

In this system, the LCD display will require thirty of the I/O pins of the microcontroller. Six of these pins have fixed functions, so the first step is to connect the commons (COM<0-2>) and the LCD voltages (VLCD<0-3>). The glass chosen has only three commons. Looking up three common glass connections in the data sheet provides the first section of the schematic. Another look at the devices reveals that there are only 23 available segment pins and 23 segment pins are required. Attach all the segments from the glass to the PIC® microcontroller.

## ADDING THE HALL EFFECT SWITCHES

The Hall effect switches simply need two available input pins and two pull-up resistors, this is because they are open-drain output. Looking at the pins on the left of the PICmicro device shows that the choices are:

1. RA6 and RA7 (OSC1 and OSC2)
2. RD0
3. RD1
4. RD2

The remaining tasks for the application are communications and detecting when the power fails. Simply because it keeps the Hall effect switches together, RA6 and RA7 will be chosen for the Hall effect inputs.

## RF COMMUNICATIONS

The RF communications is being handled by a pair of RF modules. The transmitter accepts an input from a digital output and produces RF energy. The receiver receives the RF energy and produces a digital signal. There are three choices left for pins. For this application, attaching the transmitter to RD0 will save a few instructions in the serial transmit software. This is because we can load the carry flag with the next bit and rotate the bit into RD0 with one instruction. If we attach the receiver to RD2, it will allow the software to use the CCP module to capture the data pulses, making the software a little easier.

## POWER FAIL DETECTION

The power fail detection is a simple input from the voltage regulator. A diode/capacitor combination (D1, C5/C6) will keep the voltage available to the application for a few milliseconds to provide a graceful power-down. The most important task during the power-down is to save the current water usage to the EEPROM. The voltage on RD1 comes before D1 allowing the voltage, at RD1, to drop faster than VDD. If RD1 ever goes low, the firmware will know that the power has been removed and it must save its data.

## WHAT IS LEFT?

The last major step is providing a connection for programming and debugging. A 6-pin connector will allow an MPLAB® ICD 2 or other programmer to be attached during development. Because the ICD requires the use of RB6 and RB7, there will be an affect on the LCD. Fortunately, this affect is temporary and will not damage the glass. Before the LCD code is finished, it will be tested without the ICD attached to verify that the software is correctly using the RB6 and RB7 segments.

## SCHEMATIC

The complete schematic for this application is located in **Appendix A: Schematic**.

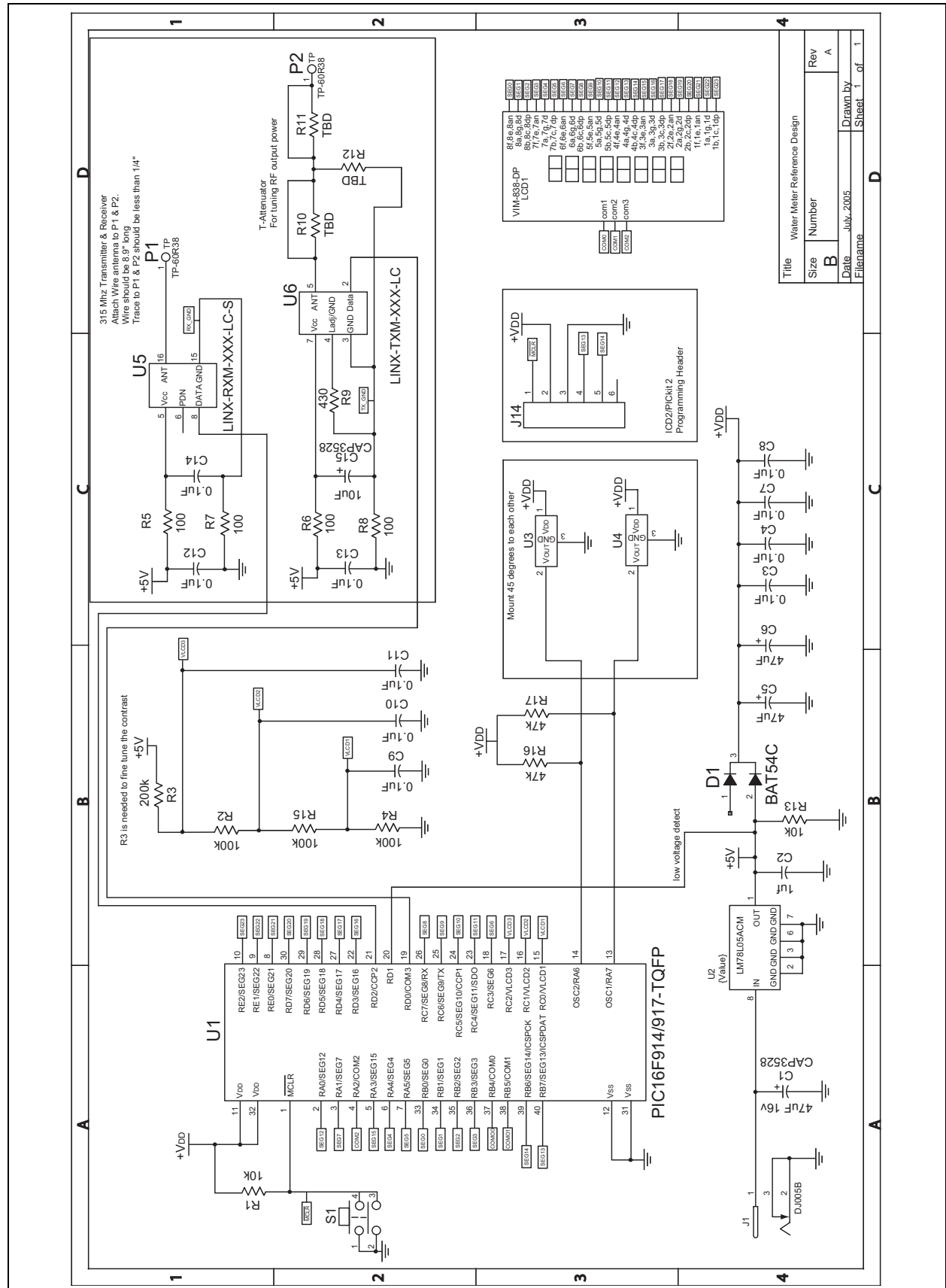
## SOFTWARE DEVELOPMENT

The software for this application was developed in Assembly Language using the freely downloaded MPLAB development tools. Debugging the software was done simply by using the included simulator, and, after the board was completed, the in-circuit debugging features. Programming and the in-circuit debug were accomplished with the MPLAB ICD 2 device from Microchip Technology. The software is included, in a zip file, with this application note.

## CONCLUSION

Implementing a basic electronic water meter is very easy with the PIC16F917. It is also a very cost-effective solution towards advanced metering features.

## APPENDIX A: SCHEMATIC



# AN1013

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NOTES:

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